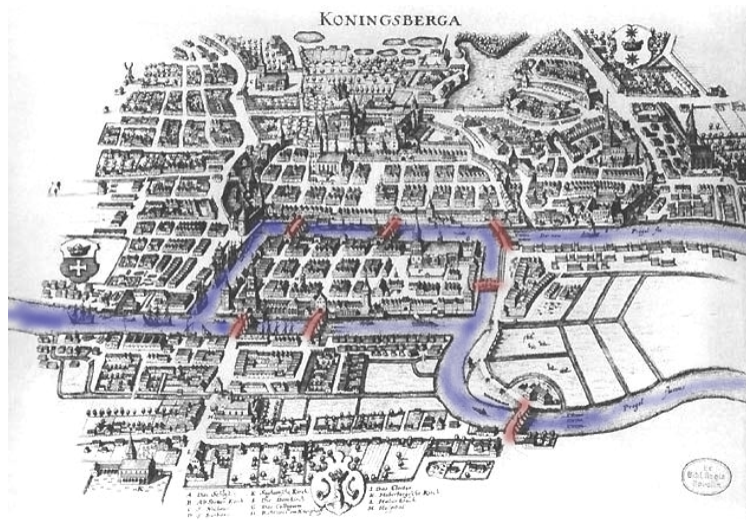


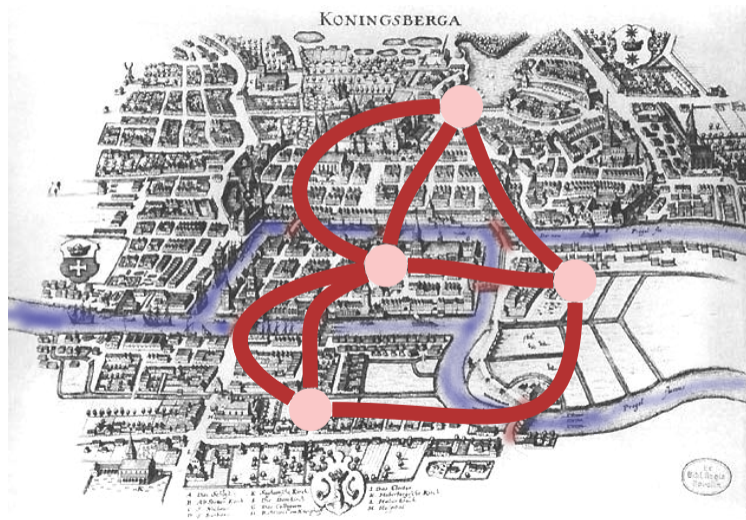
12. Graphs

Notation, Representation, Graph Traversal (DFS, BFS), Topological Sorting
[Ottman/Widmayer, Kap. 9.1 - 9.4, Cormen et al, Kap. 22]

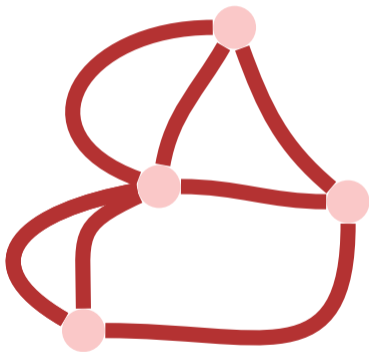
Königsberg 1736



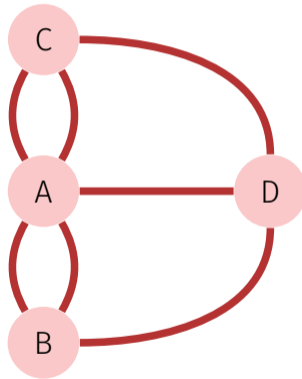
Königsberg 1736



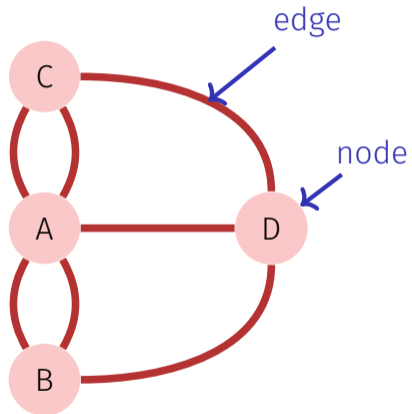
Königsberg 1736



[Multi]Graph

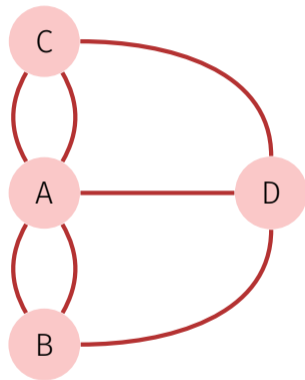


[Multi]Graph



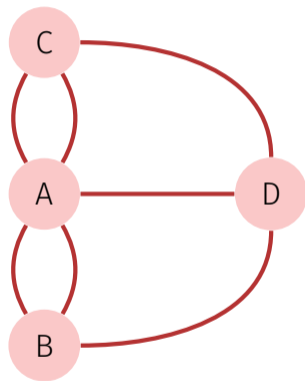
Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?



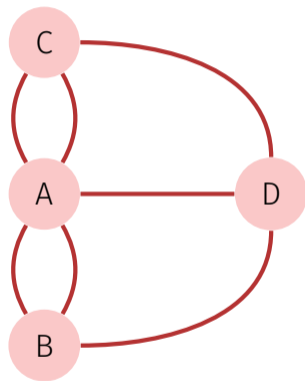
Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?
- Euler (1736): no.



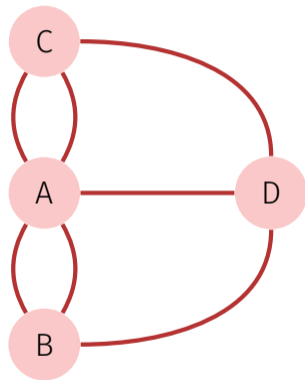
Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?
- Euler (1736): no.
- Such a *cycle* is called *Eulerian path*.

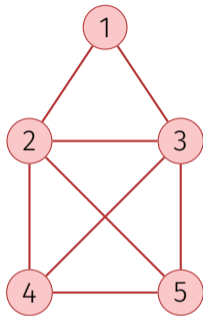


Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?
- Euler (1736): no.
- Such a *cycle* is called *Eulerian path*.
- Eulerian path \Leftrightarrow each node provides an even number of edges (each node is of an *even degree*).
' \Rightarrow ' is straightforward, " \Leftarrow " is a bit more difficult but still elementary.



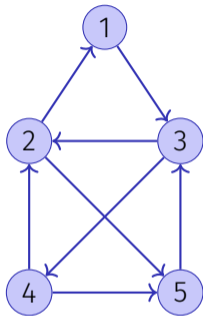
Notation



undirected

$$V = \{1, 2, 3, 4, 5\}$$

$$E = \{\{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \\ \{2, 5\}, \{3, 4\}, \{3, 5\}, \{4, 5\}\}$$



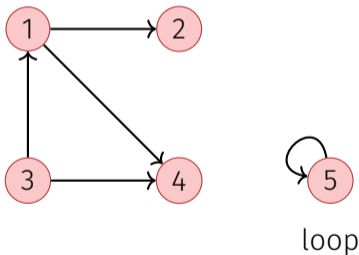
directed

$$V = \{1, 2, 3, 4, 5\}$$

$$E = \{(1, 2), (1, 3), (2, 1), (2, 3), (2, 5), (3, 2), \\ (3, 4), (3, 5), (4, 2), (4, 5), (5, 3)\}$$

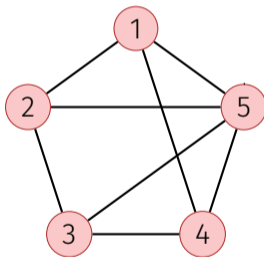
Notation

A **directed graph** consists of a set $V = \{v_1, \dots, v_n\}$ of nodes (*Vertices*) and a set $E \subseteq V \times V$ of Edges. The same edges may not be contained more than once.



Notation

An **undirected graph** consists of a set $V = \{v_1, \dots, v_n\}$ of nodes and a set $E \subseteq \{\{u, v\} | u, v \in V\}$ of edges. Edges may not be contained more than once.¹⁵

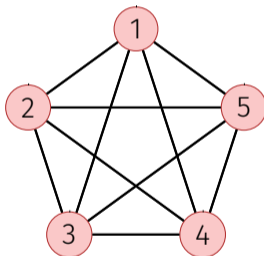


undirected graph

¹⁵As opposed to the introductory example – it is then called multi-graph.

Notation

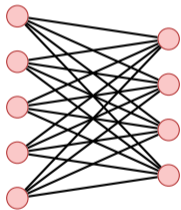
An undirected graph $G = (V, E)$ without loops where E comprises all edges between pairwise different nodes is called **complete**.



a complete undirected graph

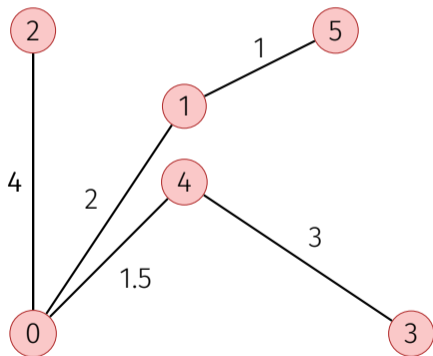
Notation

A graph where V can be partitioned into disjoint sets U and W such that each $e \in E$ provides a node in U and a node in W is called **bipartite**.



Notation

A **weighted graph** $G = (V, E, c)$ is a graph $G = (V, E)$ with an **edge weight function** $c : E \rightarrow \mathbb{R}$. $c(e)$ is called **weight** of the edge e .



Notation

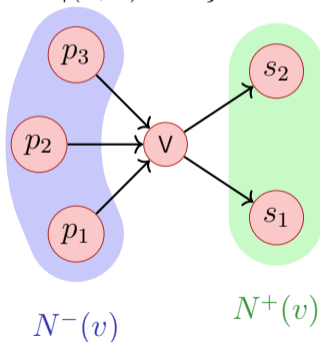
For directed graphs $G = (V, E)$

- $w \in V$ is called adjacent to $v \in V$, if $(v, w) \in E$

Notation

For directed graphs $G = (V, E)$

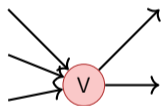
- $w \in V$ is called adjacent to $v \in V$, if $(v, w) \in E$
- **Predecessors** of $v \in V$: $N^-(v) := \{u \in V \mid (u, v) \in E\}$.
Successors: $N^+(v) := \{u \in V \mid (v, u) \in E\}$



Notation

For directed graphs $G = (V, E)$

- **In-Degree:** $\deg^-(v) = |N^-(v)|$,
Out-Degree: $\deg^+(v) = |N^+(v)|$



$$\deg^-(v) = 3, \deg^+(v) = 2$$



$$\deg^-(w) = 1, \deg^+(w) = 1$$

Notation

For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$

Notation

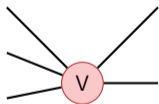
For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$
- **Neighbourhood** of $v \in V$: $N(v) = \{w \in V \mid \{v, w\} \in E\}$

Notation

For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$
- **Neighbourhood** of $v \in V$: $N(v) = \{w \in V \mid \{v, w\} \in E\}$
- **Degree** of v : $\deg(v) = |N(v)|$ with a special case for the loops: increase the degree by 2.



$$\deg(v) = 5$$



$$\deg(w) = 2$$

Relationship between node degrees and number of edges

For each graph $G = (V, E)$ it holds

1. $\sum_{v \in V} \deg^-(v) = \sum_{v \in V} \deg^+(v) = |E|$, for G directed
2. $\sum_{v \in V} \deg(v) = 2|E|$, for G undirected.

Paths

- **Path:** a sequence of nodes $\langle v_1, \dots, v_{k+1} \rangle$ such that for each $i \in \{1 \dots k\}$ there is an edge from v_i to v_{i+1} .

Paths

- **Path:** a sequence of nodes $\langle v_1, \dots, v_{k+1} \rangle$ such that for each $i \in \{1 \dots k\}$ there is an edge from v_i to v_{i+1} .
- **Length** of a path: number of contained edges k .

Paths

- **Path:** a sequence of nodes $\langle v_1, \dots, v_{k+1} \rangle$ such that for each $i \in \{1 \dots k\}$ there is an edge from v_i to v_{i+1} .
- **Length** of a path: number of contained edges k .
- **Weight** of a path (in weighted graphs): $\sum_{i=1}^k c((v_i, v_{i+1}))$ (bzw. $\sum_{i=1}^k c(\{v_i, v_{i+1}\})$)

Paths

- **Path:** a sequence of nodes $\langle v_1, \dots, v_{k+1} \rangle$ such that for each $i \in \{1 \dots k\}$ there is an edge from v_i to v_{i+1} .
- **Length** of a path: number of contained edges k .
- **Weight** of a path (in weighted graphs): $\sum_{i=1}^k c((v_i, v_{i+1}))$ (bzw. $\sum_{i=1}^k c(\{v_i, v_{i+1}\})$)
- **Simple path:** path without repeating vertices

Connectedness

- An undirected graph is called **connected**, if for each pair $v, w \in V$ there is a connecting path.
- A directed graph is called **strongly connected**, if for each pair $v, w \in V$ there is a connecting path.
- A directed graph is called **weakly connected**, if the corresponding undirected graph is connected.

Simple Observations

- generally: $0 \leq |E| \in \mathcal{O}(|V|^2)$
- connected graph: $|E| \in \Omega(|V|)$
- complete graph: $|E| = \frac{|V| \cdot (|V| - 1)}{2}$ (undirected)
- Maximally $|E| = |V|^2$ (directed), $|E| = \frac{|V| \cdot (|V| + 1)}{2}$ (undirected)

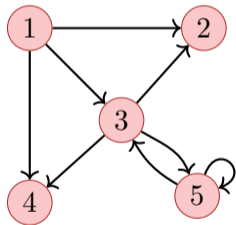
Cycles

- **Cycle:** path $\langle v_1, \dots, v_{k+1} \rangle$ with $v_1 = v_{k+1}$
- **Simple cycle:** Cycle with pairwise different v_1, \dots, v_k , that does not use an edge more than once.
- **Acyclic:** graph without any cycles.

Conclusion: undirected graphs cannot contain cycles with length 2 (loops have length 1)

Representation using a Matrix

Graph $G = (V, E)$ with nodes $v_1 \dots, v_n$ stored as **adjacency matrix**
 $A_G = (a_{ij})_{1 \leq i, j \leq n}$ with entries from $\{0, 1\}$. $a_{ij} = 1$ if and only if edge from v_i to v_j .

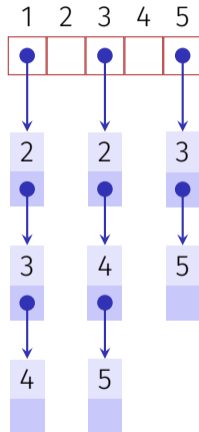
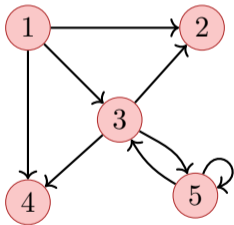


$$\begin{pmatrix} 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}$$

Memory consumption $\Theta(|V|^2)$. A_G is symmetric, if G undirected.

Representation with a List

Many graphs $G = (V, E)$ with nodes v_1, \dots, v_n provide much less than n^2 edges. Representation with **adjacency list**: Array $A[1], \dots, A[n]$, A_i comprises a linked list of nodes in $N^+(v_i)$.



Memory Consumption $\Theta(|V| + |E|)$.

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$		
find $v \in V$ without neighbour/successor		
$(u, v) \in E$?		
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	
find $v \in V$ without neighbour/successor		
$(u, v) \in E$?		
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor		
$(u, v) \in E$?		
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	
$(u, v) \in E$?		
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?		
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?	$\Theta(1)$	
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?	$\Theta(1)$	$\Theta(\deg^+ v)$
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?	$\Theta(1)$	$\Theta(\deg^+ v)$
Insert edge	$\Theta(1)$	
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?	$\Theta(1)$	$\Theta(\deg^+ v)$
Insert edge	$\Theta(1)$	$\Theta(1)$
Delete edge		

Runtimes of simple Operations

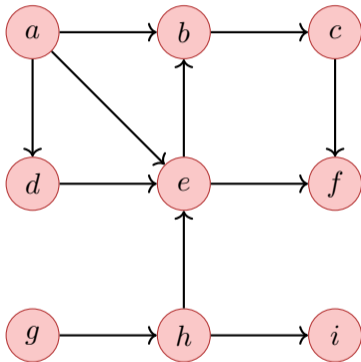
Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?	$\Theta(1)$	$\Theta(\deg^+ v)$
Insert edge	$\Theta(1)$	$\Theta(1)$
Delete edge	$\Theta(1)$	

Runtimes of simple Operations

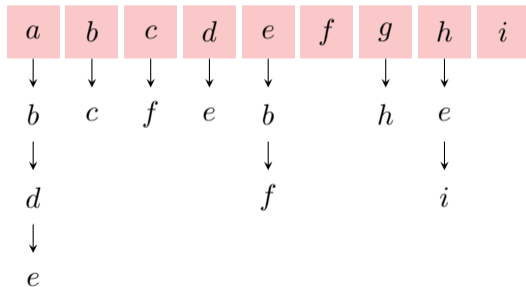
Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	$\Theta(n)$
$(u, v) \in E$?	$\Theta(1)$	$\Theta(\deg^+ v)$
Insert edge	$\Theta(1)$	$\Theta(1)$
Delete edge	$\Theta(1)$	$\Theta(\deg^+ v)$

Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

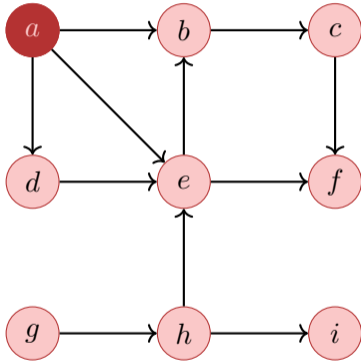


Adjazenzliste

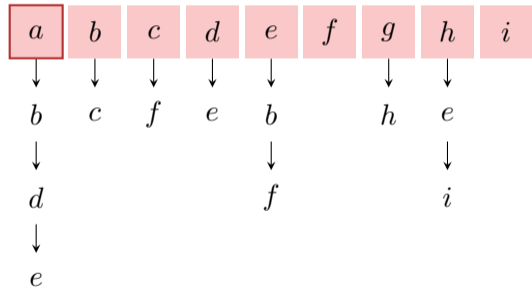


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

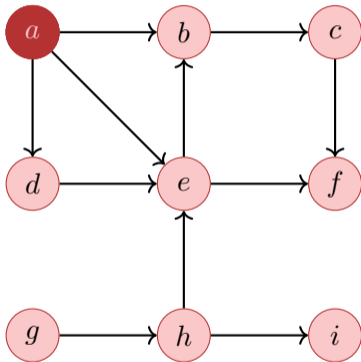


Adjazenzliste

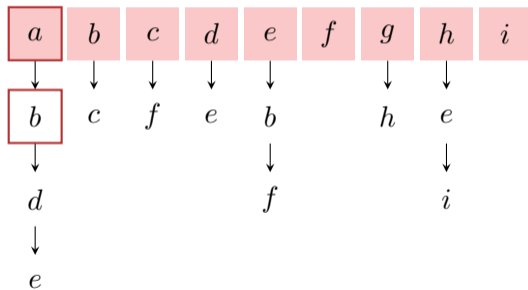


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

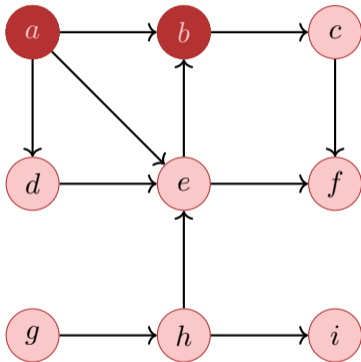


Adjazenzliste

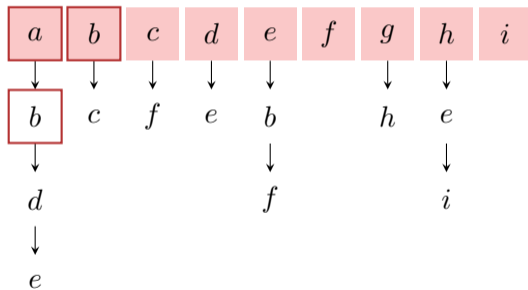


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

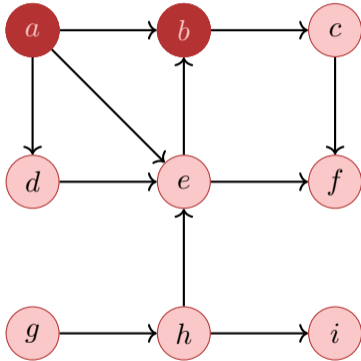


Adjazenzliste

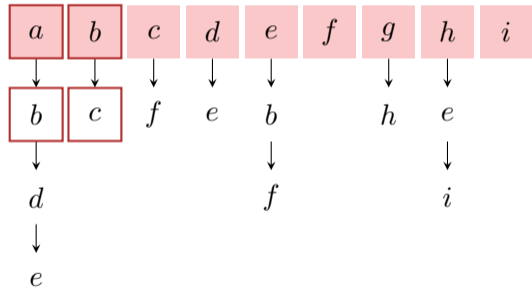


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

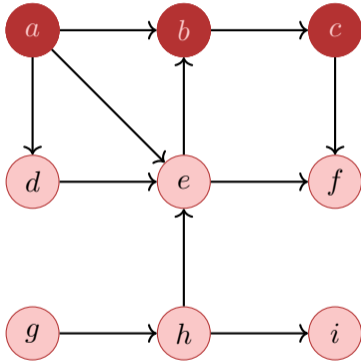


Adjazenzliste

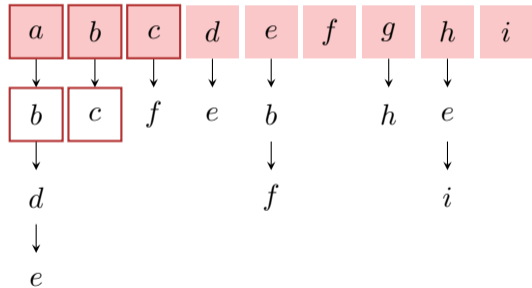


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

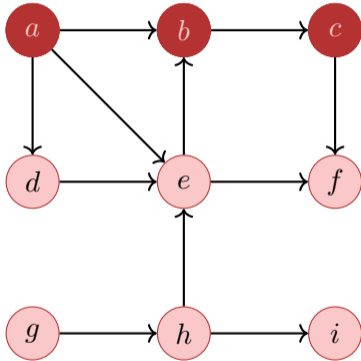


Adjazenzliste

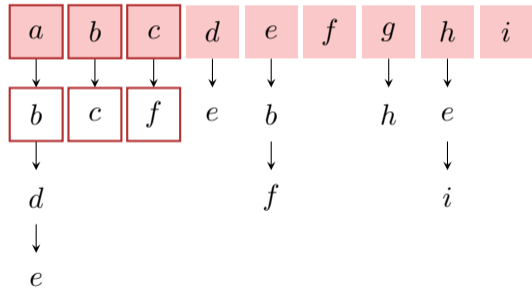


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

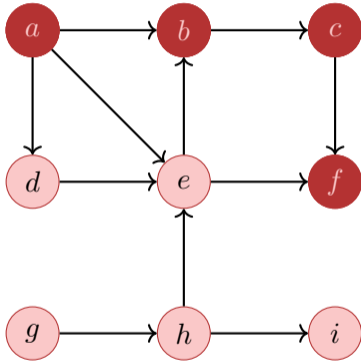


Adjazenzliste

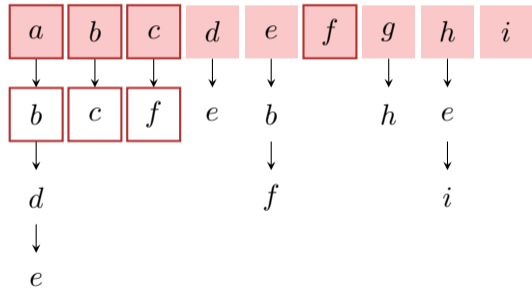


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

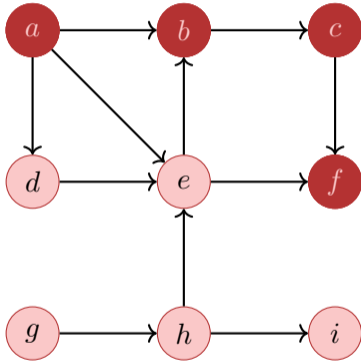


Adjazenzliste

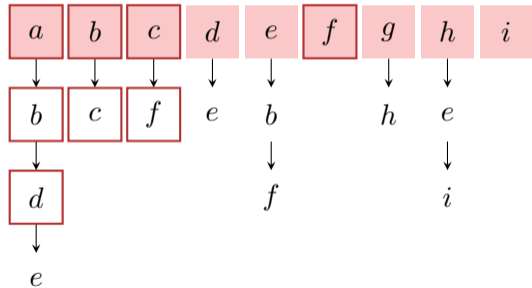


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

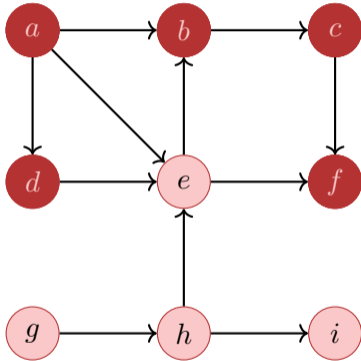


Adjazenzliste

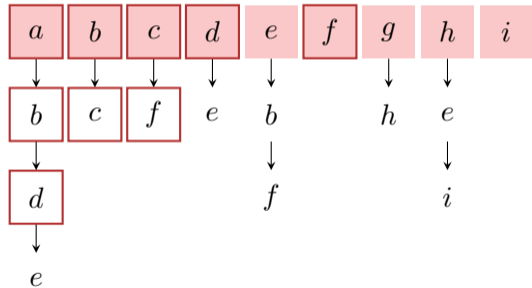


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

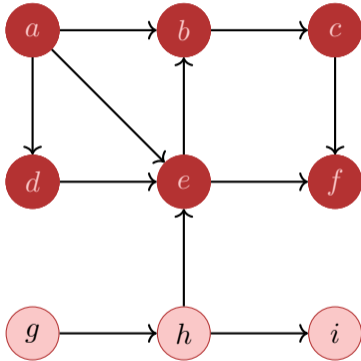


Adjazenzliste

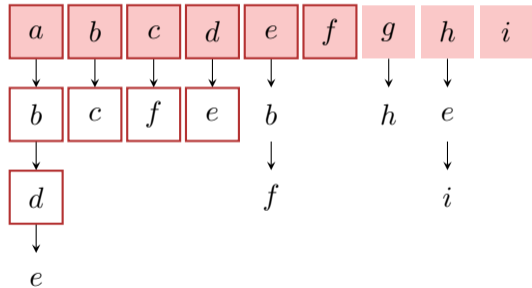


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

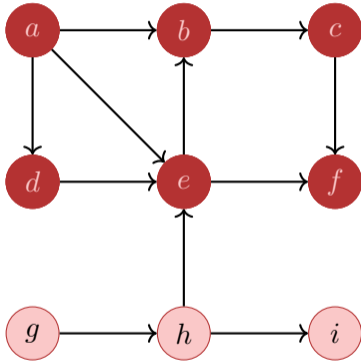


Adjazenzliste

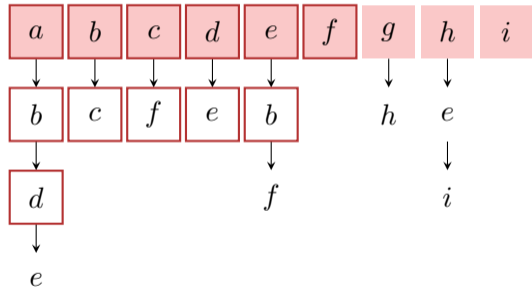


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

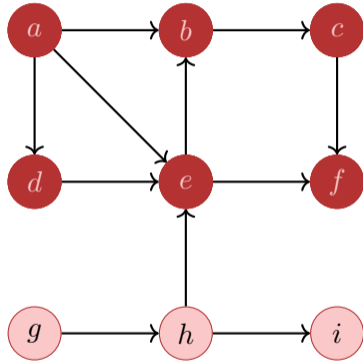


Adjazenzliste

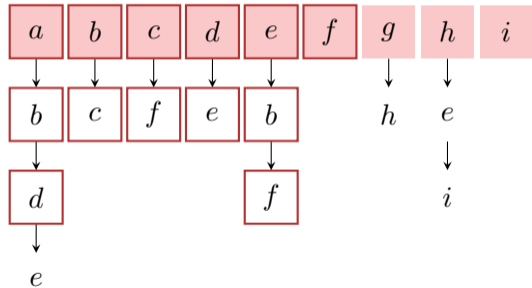


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

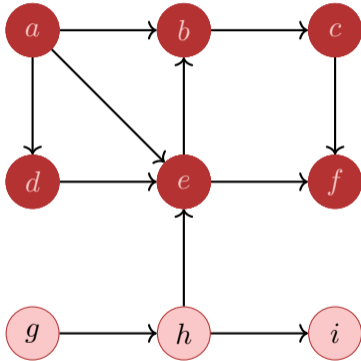


Adjazenzliste

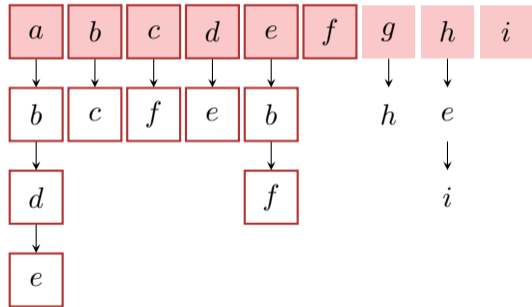


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

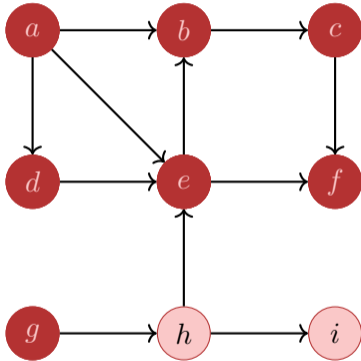


Adjazenzliste

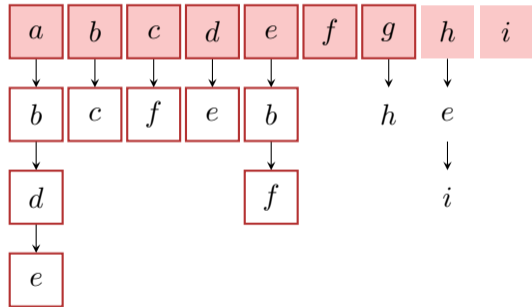


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

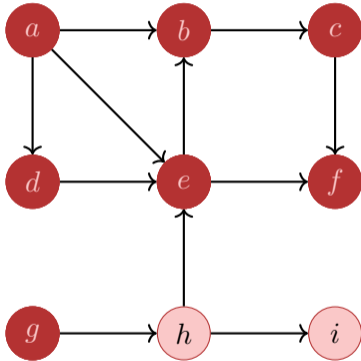


Adjazenzliste

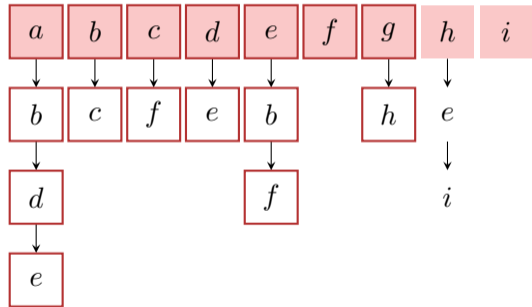


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

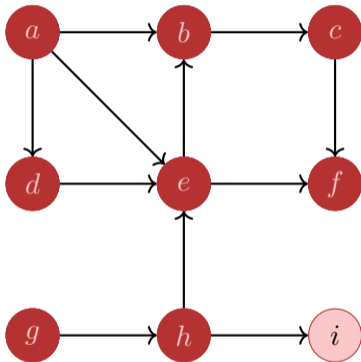


Adjazenzliste

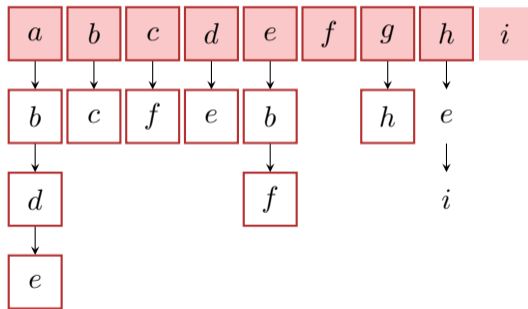


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

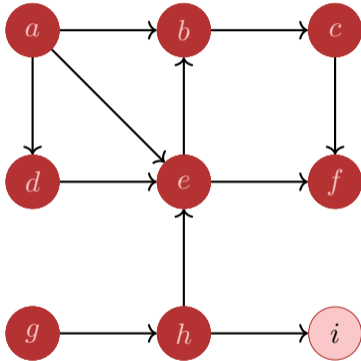


Adjazenzliste

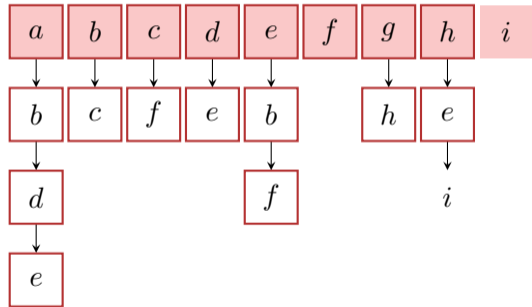


Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

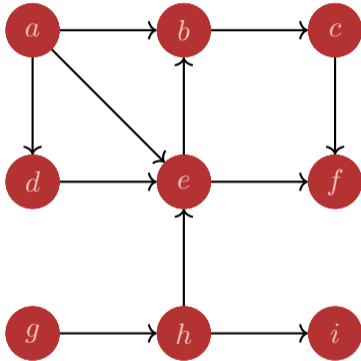


Adjazenzliste



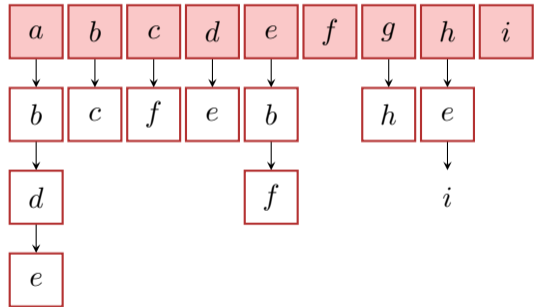
Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.



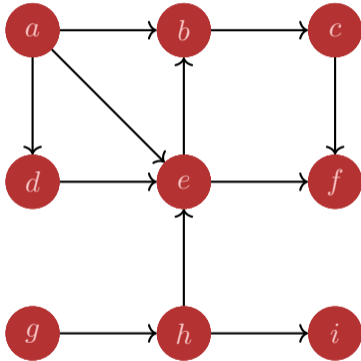
Order $a, b, c, f, d, e, g, h, i$

Adjazenzliste



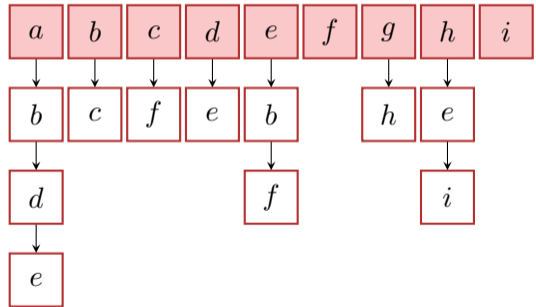
Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.



Order $a, b, c, f, d, e, g, h, i$

Adjazenzliste



Conceptual coloring of nodes

- **white:** node has not been discovered yet.
- **grey:** node has been discovered and is marked for traversal / being processed.
- **black:** node was discovered and entirely processed.

Algorithm Depth First visit DFS-Visit(G, v)

Input: graph $G = (V, E)$, Knoten v .

$v.color \leftarrow \text{grey}$

foreach $w \in N^+(v)$ **do**

if $w.color = \text{white}$ **then**
 └ DFS-Visit(G, w)

$v.color \leftarrow \text{black}$

Depth First Search starting from node v . Running time (without recursion):
 $\Theta(\text{deg}^+ v)$

Algorithm Depth First visit DFS-Visit(G)

Input: graph $G = (V, E)$

foreach $v \in V$ **do**

└ $v.color \leftarrow \text{white}$

foreach $v \in V$ **do**

└ **if** $v.color = \text{white}$ **then**

└ └ DFS-Visit(G, v)

Depth First Search for all nodes of a graph. Running time:

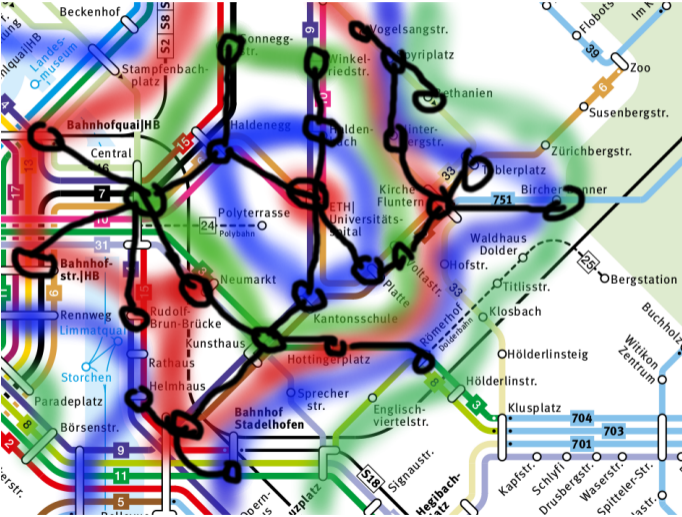
$$\Theta(|V| + \sum_{v \in V} (\deg^+(v) + 1)) = \Theta(|V| + |E|).$$

Interpretation of the Colors

When traversing the graph, a tree (or Forest) is built. When nodes are discovered there are three cases

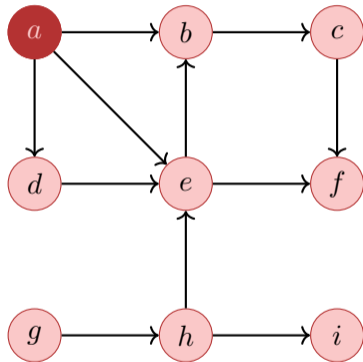
- White node: new tree edge
- Grey node: Zyklus (“back-edge”)
- Black node: forward- / cross edge

Breadth First Search

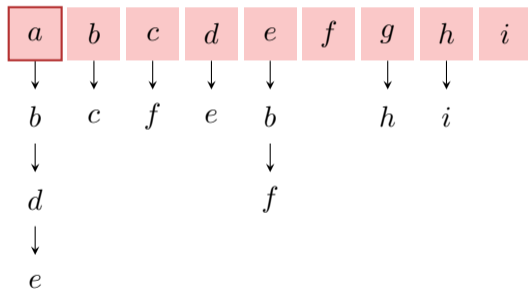


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

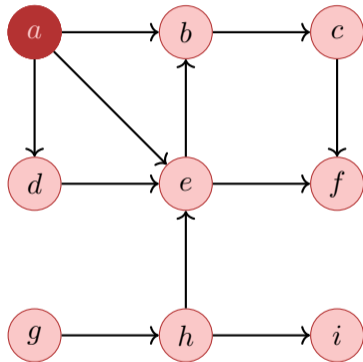


Adjazenzliste

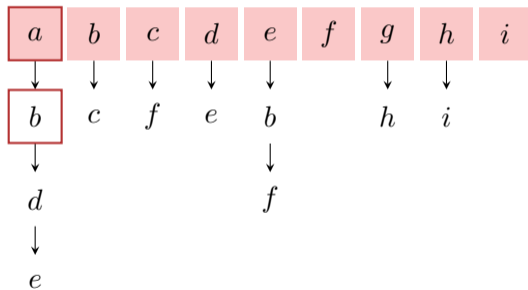


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

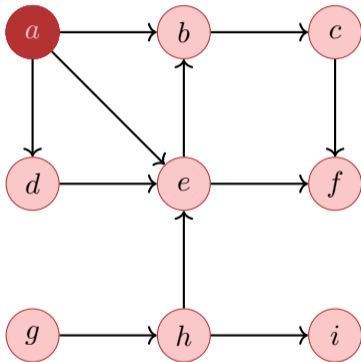


Adjazenzliste

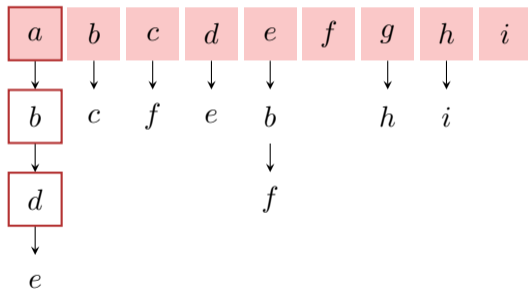


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

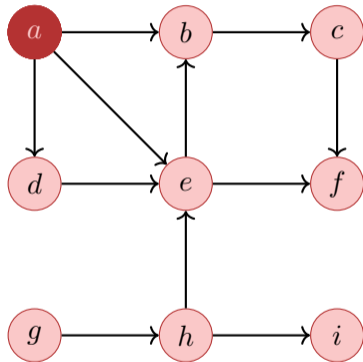


Adjazenzliste

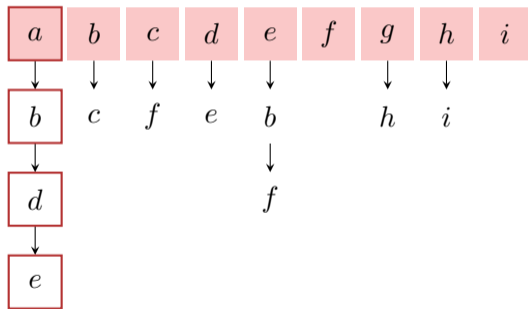


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

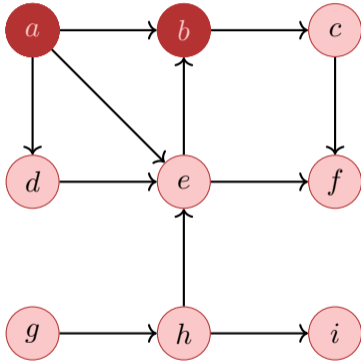


Adjazenzliste

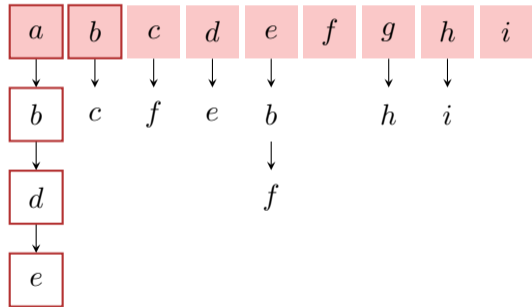


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

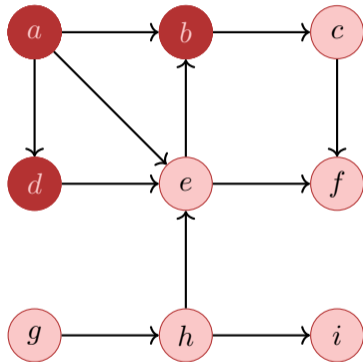


Adjazenzliste

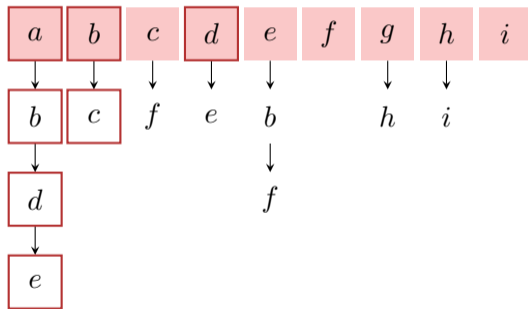


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

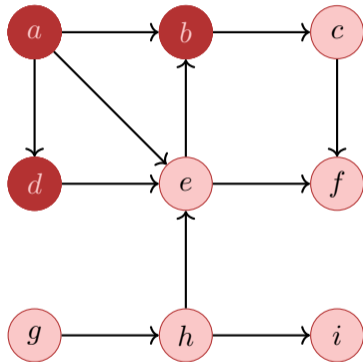


Adjazenzliste

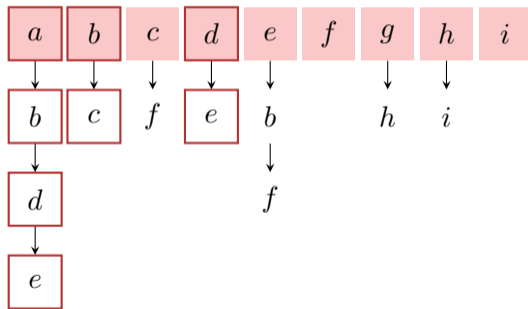


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

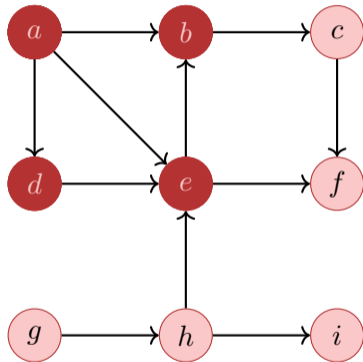


Adjazenzliste

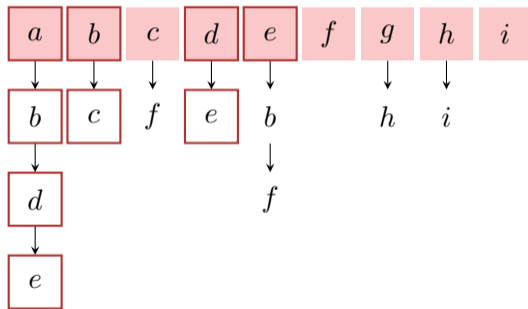


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

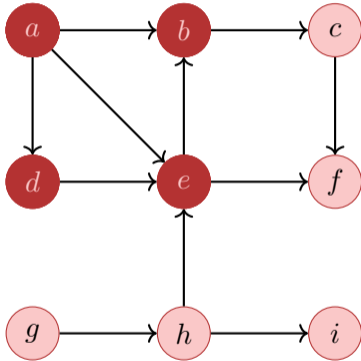


Adjazenzliste

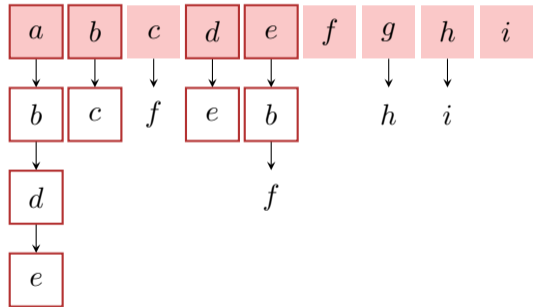


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

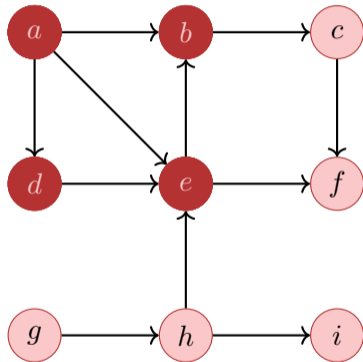


Adjazenzliste

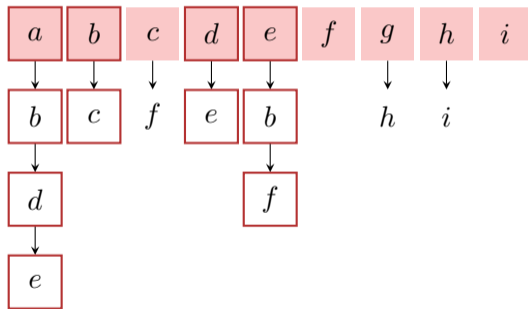


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

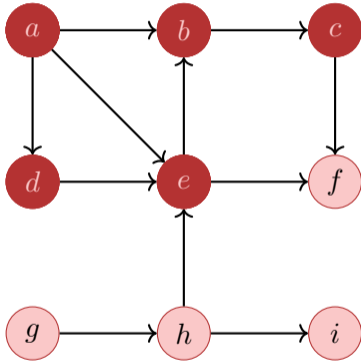


Adjazenzliste

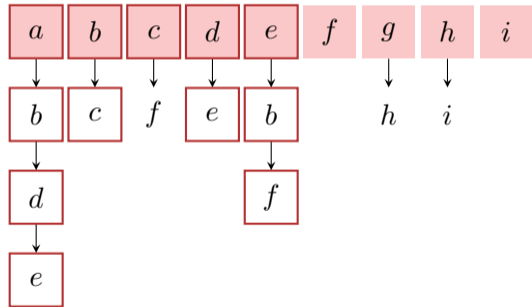


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

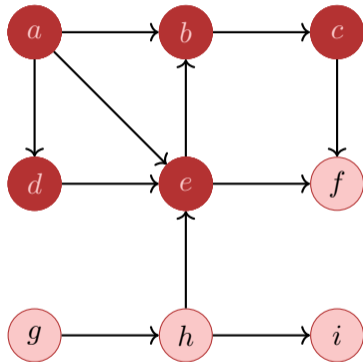


Adjazenzliste

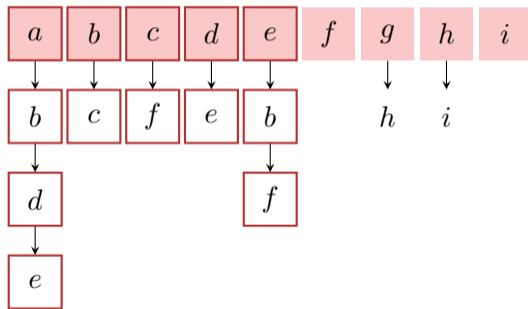


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

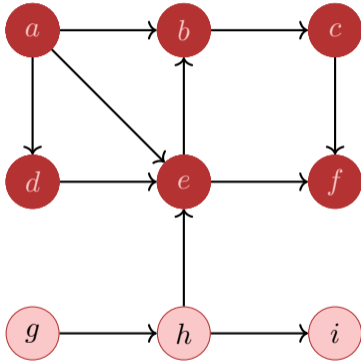


Adjazenzliste

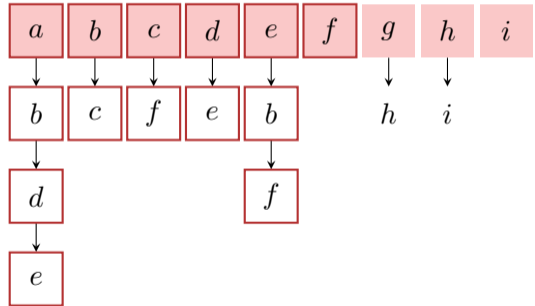


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

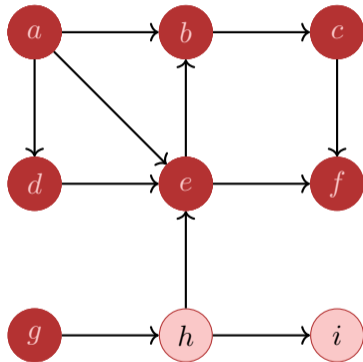


Adjazenzliste

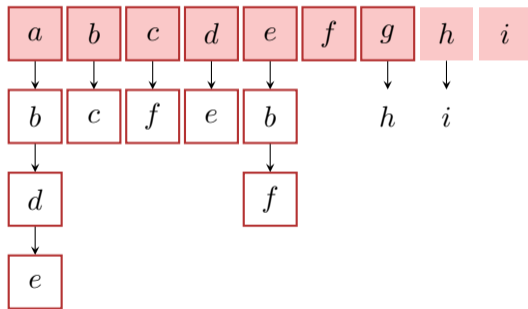


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

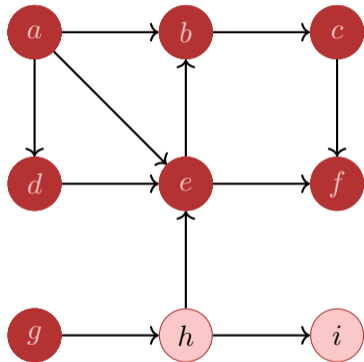


Adjazenzliste

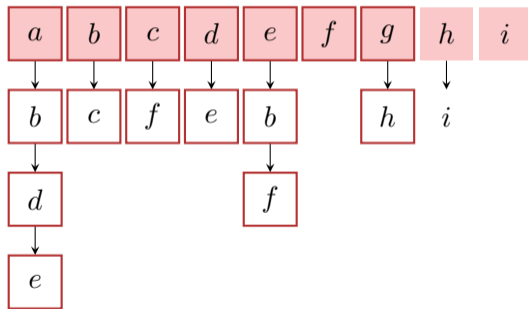


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

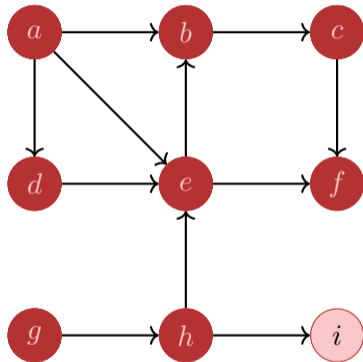


Adjazenzliste

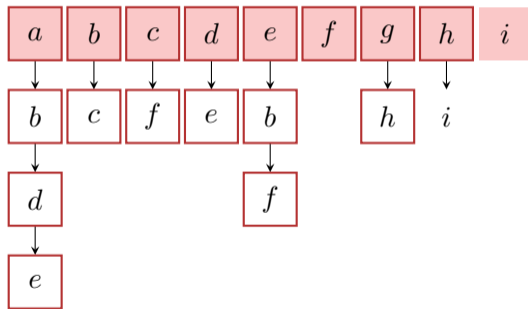


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

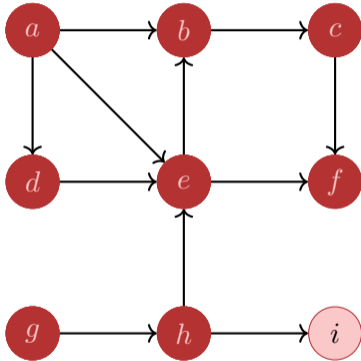


Adjazenzliste

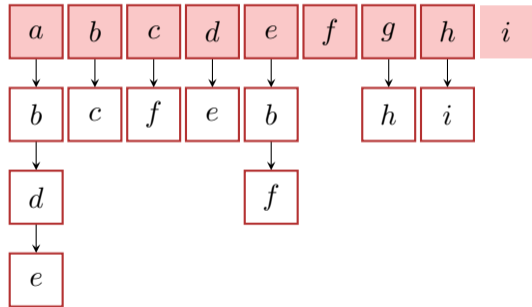


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

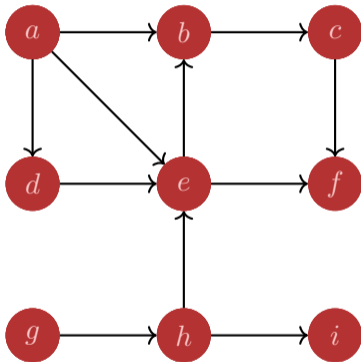


Adjazenzliste



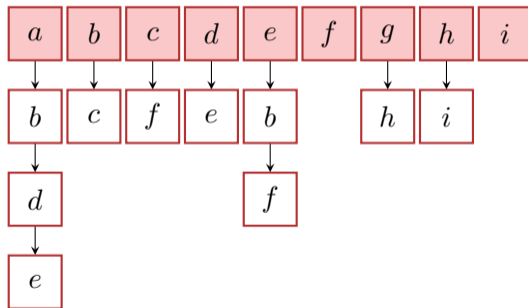
Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.



Order $a, b, d, e, c, f, g, h, i$

Adjazenzliste



(Iterative) BFS-Visit(G, v)

Input: graph $G = (V, E)$

Queue $Q \leftarrow \emptyset$

$v.color \leftarrow \text{grey}$

enqueue(Q, v)

while $Q \neq \emptyset$ **do**

$w \leftarrow \text{dequeue}(Q)$

foreach $c \in N^+(w)$ **do**

if $c.color = \text{white}$ **then**

$c.color \leftarrow \text{grey}$

 enqueue(Q, c)

$w.color \leftarrow \text{black}$

Algorithm requires extra space of $\mathcal{O}(|V|)$.

Main program BFS-Visit(G)

Input: graph $G = (V, E)$

foreach $v \in V$ **do**

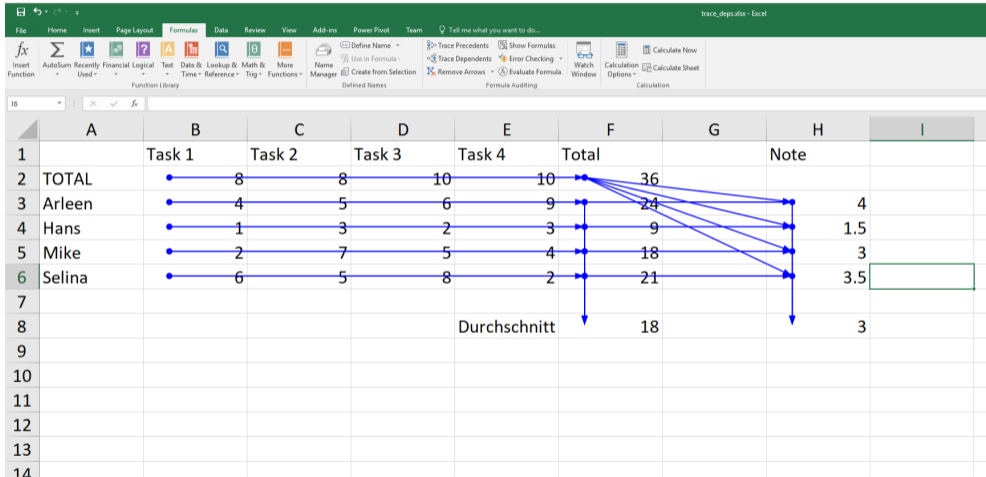
└ $v.color \leftarrow \text{white}$

foreach $v \in V$ **do**

└ **if** $v.color = \text{white}$ **then**
└└ BFS-Visit(G, v)

Breadth First Search for all nodes of a graph. Running time: $\Theta(|V| + |E|)$.

Topological Sorting



Evaluation Order?

Topological Sorting

Topological Sorting of an acyclic directed graph $G = (V, E)$:

Bijjective mapping

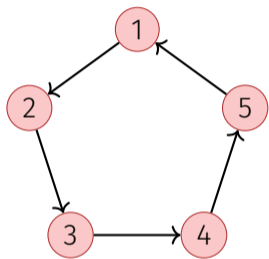
$$\text{ord} : V \rightarrow \{1, \dots, |V|\}$$

such that

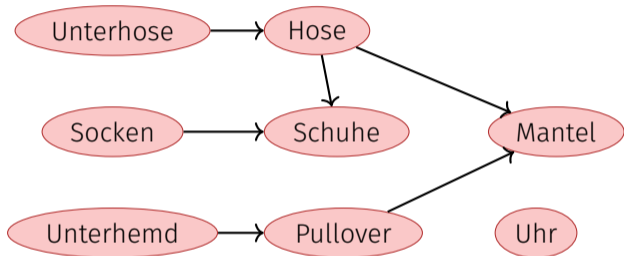
$$\text{ord}(v) < \text{ord}(w) \forall (v, w) \in E.$$

Identify i with Element $v_i := \text{ord}^{-1}(i)$. Topological sorting $\hat{=} \langle v_1, \dots, v_{|V|} \rangle$.

(Counter-)Examples



Cyclic graph: cannot be sorted topologically.



A possible topological sorting of the graph:
Unterhemd,Pullover,Unterhose,Uhr,Hose,Mantel,Socken,S

Observation

Theorem 7

A directed graph $G = (V, E)$ permits a topological sorting if and only if it is acyclic.

Observation

Theorem 7

A directed graph $G = (V, E)$ permits a topological sorting if and only if it is acyclic.

Proof “ \Rightarrow ”: If G contains a cycle it cannot permit a topological sorting, because in a cycle $\langle v_{i_1}, \dots, v_{i_m} \rangle$ it would hold that $v_{i_1} < \dots < v_{i_m} < v_{i_1}$.

Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, $\text{setord}(v_1) = 1$.

Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, $\text{setord}(v_1) = 1$.
- Hypothesis: Graph with n nodes can be sorted topologically

Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, $\text{setord}(v_1) = 1$.
- Hypothesis: Graph with n nodes can be sorted topologically
- Step ($n \rightarrow n + 1$):

Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, $\text{setord}(v_1) = 1$.
- Hypothesis: Graph with n nodes can be sorted topologically
- Step ($n \rightarrow n + 1$):
 1. G contains a node v_q with in-degree $\text{deg}^-(v_q) = 0$. Otherwise iteratively follow edges backwards – after at most $n + 1$ iterations a node would be revisited. Contradiction to the cycle-freeness.

Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, $\text{setord}(v_1) = 1$.
- Hypothesis: Graph with n nodes can be sorted topologically
- Step ($n \rightarrow n + 1$):
 1. G contains a node v_q with in-degree $\text{deg}^-(v_q) = 0$. Otherwise iteratively follow edges backwards – after at most $n + 1$ iterations a node would be revisited. Contradiction to the cycle-freeness.
 2. Graph without node v_q and without its edges can be topologically sorted by the hypothesis. Now use this sorting and set $\text{ord}(v_i) \leftarrow \text{ord}(v_i) + 1$ for all $i \neq q$ and set $\text{ord}(v_q) \leftarrow 1$.

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.
3. Set $\text{ord}(v_q) \leftarrow d$.

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.
3. Set $\text{ord}(v_q) \leftarrow d$.
4. Remove v_q and his edges from G .

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.
3. Set $\text{ord}(v_q) \leftarrow d$.
4. Remove v_q and his edges from G .
5. If $V \neq \emptyset$, then $d \leftarrow d + 1$, go to step 1.

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.
3. Set $\text{ord}(v_q) \leftarrow d$.
4. Remove v_q and his edges from G .
5. If $V \neq \emptyset$, then $d \leftarrow d + 1$, go to step 1.

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.
3. Set $\text{ord}(v_q) \leftarrow d$.
4. Remove v_q and his edges from G .
5. If $V \neq \emptyset$, then $d \leftarrow d + 1$, go to step 1.

Worst case runtime: $\Theta(|V|^2)$.

Improvement

Idea?

Improvement

Idea?

Compute the in-degree of all nodes in advance and traverse the nodes with in-degree 0 while correcting the in-degrees of following nodes.

Algorithm Topological-Sort(G)

Input: graph $G = (V, E)$.

Output: Topological sorting ord

Stack $S \leftarrow \emptyset$

foreach $v \in V$ **do** $A[v] \leftarrow 0$

foreach $(v, w) \in E$ **do** $A[w] \leftarrow A[w] + 1$ // Compute in-degrees

foreach $v \in V$ with $A[v] = 0$ **do** $\text{push}(S, v)$ // Memorize nodes with in-degree 0

$i \leftarrow 1$

while $S \neq \emptyset$ **do**

$v \leftarrow \text{pop}(S)$; $\text{ord}[v] \leftarrow i$; $i \leftarrow i + 1$ // Choose node with in-degree 0

foreach $(v, w) \in E$ **do** // Decrease in-degree of successors

$A[w] \leftarrow A[w] - 1$

if $A[w] = 0$ **then** $\text{push}(S, w)$

if $i = |V| + 1$ **then return** ord **else return** "Cycle Detected"

Algorithm Correctness

Theorem 8

Let $G = (V, E)$ be a directed acyclic graph. Algorithm `TopologicalSort(G)` computes a topological sorting `ord` for G with runtime $\Theta(|V| + |E|)$.

Algorithm Correctness

Theorem 8

Let $G = (V, E)$ be a directed acyclic graph. Algorithm `TopologicalSort(G)` computes a topological sorting `ord` for G with runtime $\Theta(|V| + |E|)$.

Proof: follows from previous theorem:

1. Decreasing the in-degree corresponds with node removal.
2. In the algorithm it holds for each node v with $A[v] = 0$ that either the node has in-degree 0 or that previously all predecessors have been assigned a value $\text{ord}[u] \leftarrow i$ and thus $\text{ord}[v] > \text{ord}[u]$ for all predecessors u of v . Nodes are put to the stack only once.
3. Runtime: inspection of the algorithm (with some arguments like with graph traversal)

Algorithm Correctness

Theorem 9

Let $G = (V, E)$ be a directed graph containing a cycle. Algorithm `TopologicalSort` terminates within $\Theta(|V| + |E|)$ steps and detects a cycle.

Algorithm Correctness

Theorem 9

Let $G = (V, E)$ be a directed graph containing a cycle. Algorithm `TopologicalSort` terminates within $\Theta(|V| + |E|)$ steps and detects a cycle.

Proof: let $\langle v_{i_1}, \dots, v_{i_k} \rangle$ be a cycle in G . In each step of the algorithm remains $A[v_{i_j}] \geq 1$ for all $j = 1, \dots, k$. Thus k nodes are never pushed on the stack and therefore at the end it holds that $i \leq V + 1 - k$.

The runtime of the second part of the algorithm can become shorter. But the computation of the in-degree costs already $\Theta(|V| + |E|)$.