

## 8. Binary Search Trees

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[Ottman/Widmayer, Kap. 5.1, Cormen et al, Kap. 12.1 - 12.3]

# Trees

Trees are

- Generalized lists: nodes can have more than one successor
- Special graphs: graphs consist of nodes and edges. A tree is a fully connected, directed, acyclic graph.

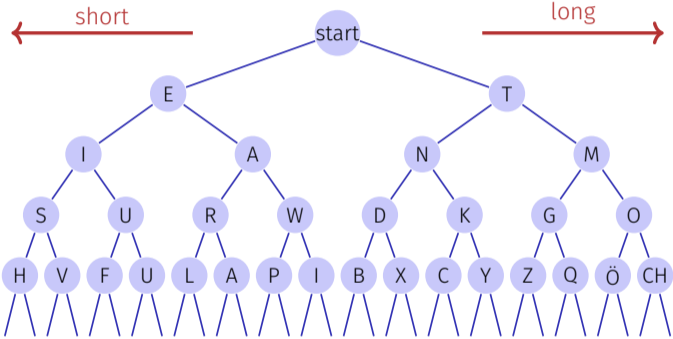
# Trees

## Use

- Decision trees: hierarchic representation of decision rules
- syntax trees: parsing and traversing of expressions, e.g. in a compiler
- Code trees: representation of a code, e.g. morse alphabet, huffman code
- Search trees: allow efficient searching for an element by value

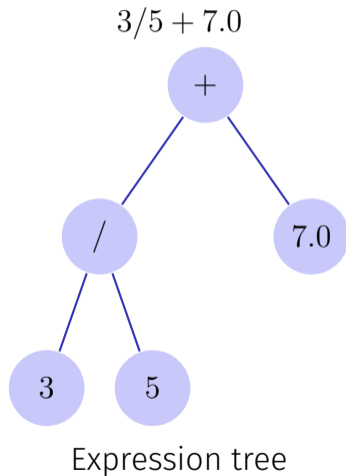


# Examples

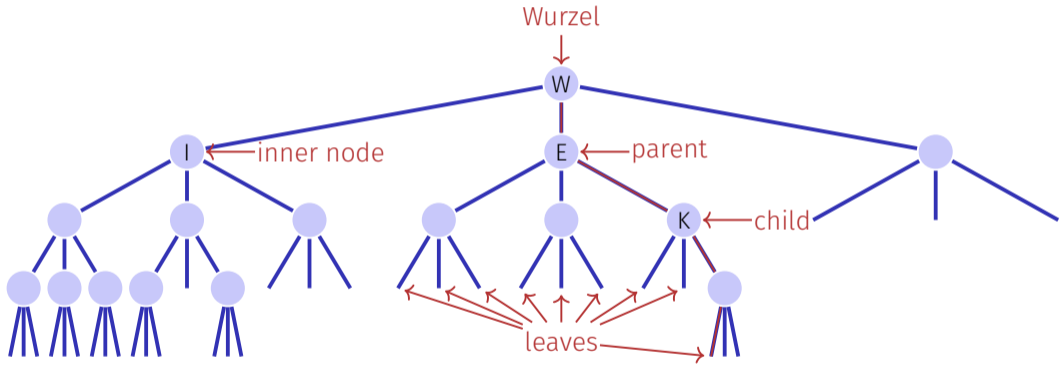


Morsealphabet

# Examples



# Nomenclature



- Order of the tree: maximum number of child nodes, here: 3
- Height of the tree: maximum path length root – leaf (here: 4)

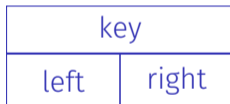
# Binary Trees

A binary tree is

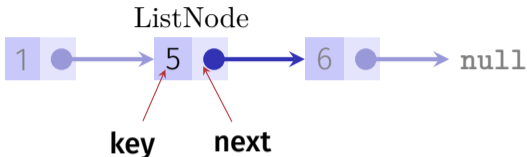
- either a leaf, i.e. an empty tree,
- or an inner leaf with two trees  $T_l$  (left subtree) and  $T_r$  (right subtree) as left and right successor.

In each inner node  $v$  we store

- a key  $v.\mathbf{key}$  and
  - two nodes  $v.\mathbf{left}$  and  $v.\mathbf{right}$  to the roots of the left and right subtree.
- a leaf is represented by the **null**-pointer



# Linked List Node in Python



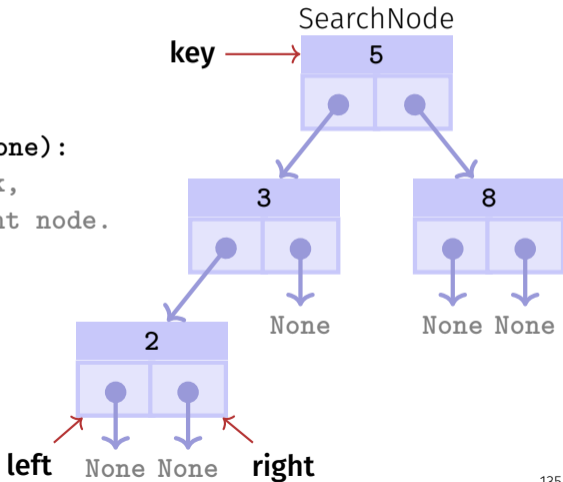
```
class ListNode:
    # entries key, next implicit via constructor

    def __init__(self, key , next = None):
        """Constructor that takes a key and, optionally, next."""
        self.key = key
        self.next = next
}
```



# Now: tree nodes in Python

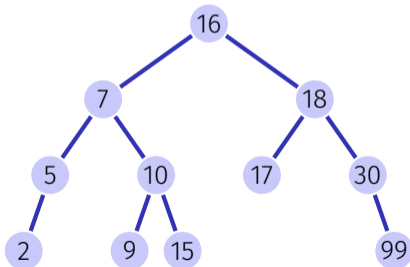
```
class SearchNode:  
    # implicit entries key, left, right  
  
    def __init__(self, k, l=None, r=None):  
        # Constructor that takes a key k,  
        # and optionally a left and right node.  
        self.key = k  
        self.left, self.right = l, r
```



# Binary search tree

A **binary search tree** is a binary tree that fulfils the **search tree property**:

- Every node  $v$  stores a key
- Keys in left subtree  $v.\text{left}$  are smaller than  $v.\text{key}$
- Keys in right subtree  $v.\text{right}$  are greater than  $v.\text{key}$



# Searching

**Input:** Binary search tree with root  $r$ , key  $k$

**Output:** Node  $v$  with  $v.key = k$  or **null**

$v \leftarrow r$

**while**  $v \neq \text{null}$  **do**

**if**  $k = v.key$  **then**

        | **return**  $v$

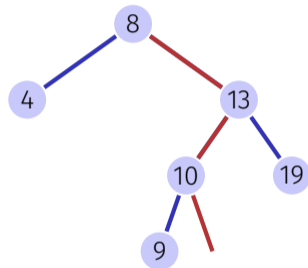
**else if**  $k < v.key$  **then**

        |  $v \leftarrow v.left$

**else**

        |  $v \leftarrow v.right$

**return null**



Search (12)  $\rightarrow$  **null**

# Searching in Python

```
def findNode(root, key):  
    n = root  
    while n != None and n.key != key:  
        if key < n.key:  
            n = n.left  
        else:  
            n = n.right  
    return n
```

# Height of a tree

The height  $h(T)$  of a binary tree  $T$  with root  $r$  is given by

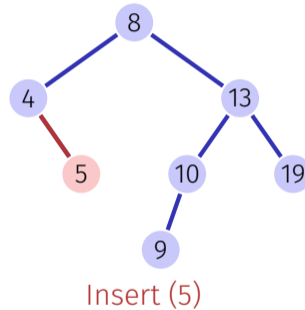
$$h(r) = \begin{cases} 0 & \text{if } r = \mathbf{null} \\ 1 + \max\{h(r.\text{left}), h(r.\text{right})\} & \text{otherwise.} \end{cases}$$

The worst case run time of the search is thus  $\mathcal{O}(h(T))$

# Insertion of a key

Insertion of the key  $k$

- Search for  $k$
- If successful search: e.g. output error
- Of no success: insert the key at the leaf reached



# Insert Nodes in Python

```
def addNode(root, key):  
    n = root  
    if n == None:  
        root = Node(key)  
    while n.key != key:  
        if key < n.key:  
            if n.left == None:  
                n.left = Node(key)  
            n = n.left  
        else:  
            if n.right == None:  
                n.right = Node(key)  
            n = n.right  
    return root
```

# Tree in Python

```
class Tree:
    def __init__(self):
        self.root = None

    def find(self, key):
        return findNode(self.root, key)

    def has(self, key):
        return self.find(key) != None

    def add(self, key):
        self.root = addNode(self.root, key)

# ....
```

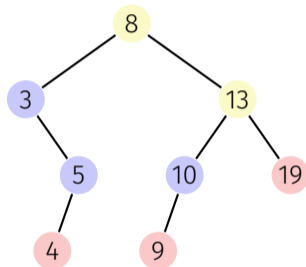


# Remove node

Three cases possible:

- Node has no children
- Node has one child
- Node has two children

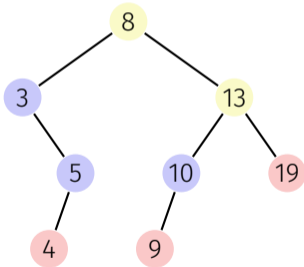
[Leaves do not count here]



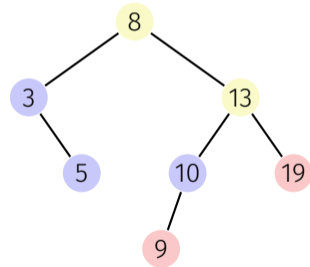
# Remove node

Node has no children

Simple case: replace node by leaf.



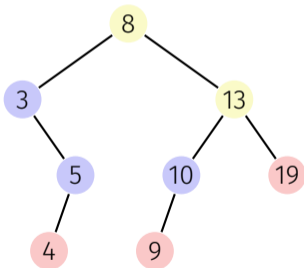
*remove(4)*  
→



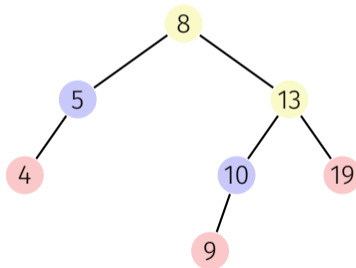
# Remove node

Node has one child

Also simple: replace node by single child.



*remove(3)*  
→



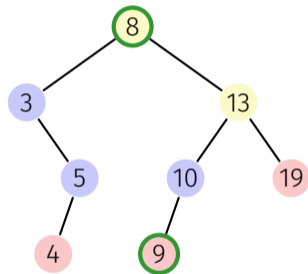
# Remove node

Node  $v$  has two children

The following observation helps: the smallest key in the right subtree  $v.right$  (the **symmetric successor** of  $v$ )

- is smaller than all keys in  $v.right$
- is greater than all keys in  $v.left$
- and cannot have a left child.

Solution: replace  $v$  by its symmetric successor.

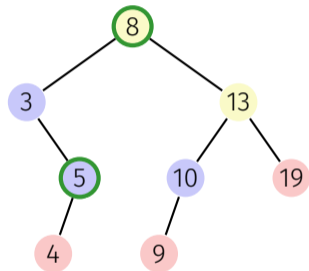


# By symmetry...

Node  $v$  has two children

Also possible: replace  $v$  by its symmetric predecessor.

Implementation: devil is in the detail!



# Algorithm SymmetricSuccessor( $v$ )

**Input:** Node  $v$  of a binary search tree.

**Output:** Symmetric successor of  $v$

$w \leftarrow v.\text{right}$

$x \leftarrow w.\text{left}$

**while**  $x \neq \text{null}$  **do**

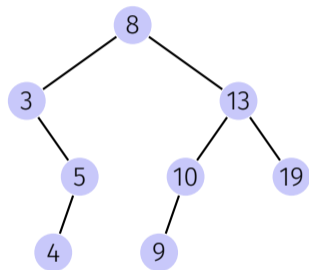
$w \leftarrow x$

$x \leftarrow x.\text{left}$

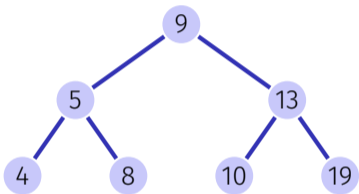
**return**  $w$

# Traversal possibilities

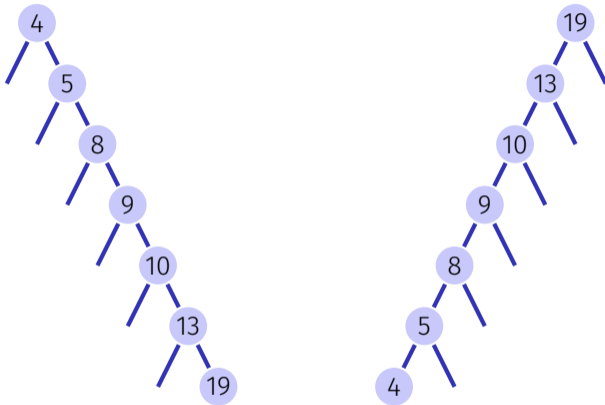
- preorder:  $v$ , then  $T_{\text{left}}(v)$ , then  $T_{\text{right}}(v)$ .  
8, 3, 5, 4, 13, 10, 9, 19
- postorder:  $T_{\text{left}}(v)$ , then  $T_{\text{right}}(v)$ , then  $v$ .  
4, 5, 3, 9, 10, 19, 13, 8
- inorder:  $T_{\text{left}}(v)$ , then  $v$ , then  $T_{\text{right}}(v)$ .  
3, 4, 5, 8, 9, 10, 13, 19



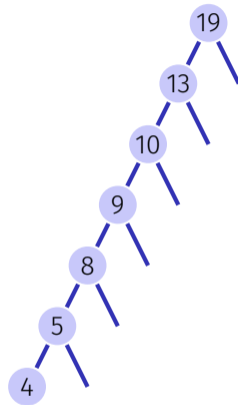
# Degenerated search trees



Insert 9,5,13,4,8,10,19  
ideally balanced



Insert 4,5,8,9,10,13,19  
linear list



Insert 19,13,10,9,8,5,4  
linear list



# Probabilistically

A search tree constructed from a random sequence of numbers provides an an expected path length of  $\mathcal{O}(\log n)$ .

Attention: this only holds for insertions. If the tree is constructed by random insertions and deletions, the expected path length is  $\mathcal{O}(\sqrt{n})$ .

*Balanced* trees make sure (e.g. with *rotations*) during insertion or deletion that the tree stays balanced and provide a  $\mathcal{O}(\log n)$  Worst-case guarantee.

## 9. Heaps

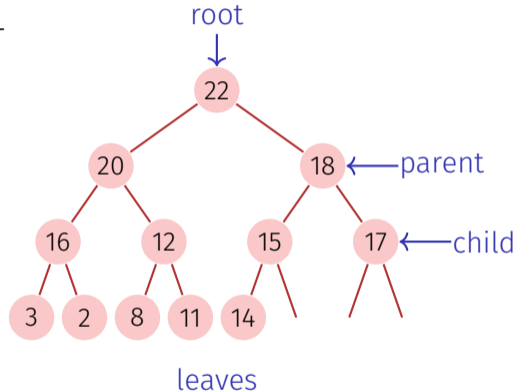
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Datenstruktur optimiert zum schnellen Extrahieren von Minimum oder Maximum und Sortieren. [Ottman/Widmayer, Kap. 2.3, Cormen et al, Kap. 6]

# [Max-]Heap\*

Binary tree with the following properties

1. complete up to the lowest level
2. Gaps (if any) of the tree in the last level to the right
3. **Heap-Condition:**  
Max-(Min-)Heap: key of a child smaller (greater) than that of the parent node



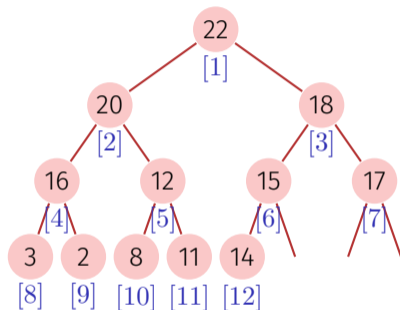
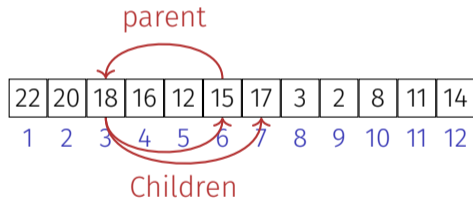
\*Heap(data structure), not: as in “heap and stack” (memory allocation)

# Heap as Array

Tree  $\rightarrow$  Array:

■  $\text{children}(i) = \{2i, 2i + 1\}$

■  $\text{parent}(i) = \lfloor i/2 \rfloor$



Depends on the starting index<sup>4</sup>

<sup>4</sup>For array that start at 0:  $\{2i, 2i + 1\} \rightarrow \{2i + 1, 2i + 2\}$ ,  $\lfloor i/2 \rfloor \rightarrow \lfloor (i - 1)/2 \rfloor$

# Height of a Heap

What is the height  $H(n)$  of Heap with  $n$  nodes? On the  $i$ -th level of a binary tree there are at most  $2^i$  nodes. Up to the last level of a heap all levels are filled with values.

$$H(n) = \min\{h \in \mathbb{N} : \sum_{i=0}^{h-1} 2^i \geq n\}$$

with  $\sum_{i=0}^{h-1} 2^i = 2^h - 1$ :

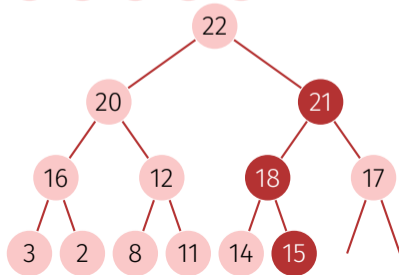
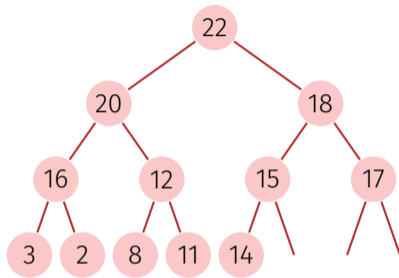
$$H(n) = \min\{h \in \mathbb{N} : 2^h \geq n + 1\},$$

thus

$$H(n) = \lceil \log_2(n + 1) \rceil.$$

# Insert

- Insert new element at the first free position. Potentially violates the heap property.
- Reestablish heap property: climb successively
- Worst case number of operations:  $\mathcal{O}(\log n)$



# Algorithm Sift-Up( $A, m$ )

**Input:** Array  $A$  with at least  $m$  elements and Max-Heap-Structure on  $A[1, \dots, m-1]$

**Output:** Array  $A$  with Max-Heap-Structure on  $A[1, \dots, m]$ .

$v \leftarrow A[m]$  // value

$c \leftarrow m$  // current position (child)

$p \leftarrow \lfloor c/2 \rfloor$  // parent node

**while**  $c > 1$  and  $v > A[p]$  **do**

$A[c] \leftarrow A[p]$  // Value parent node  $\rightarrow$  current node

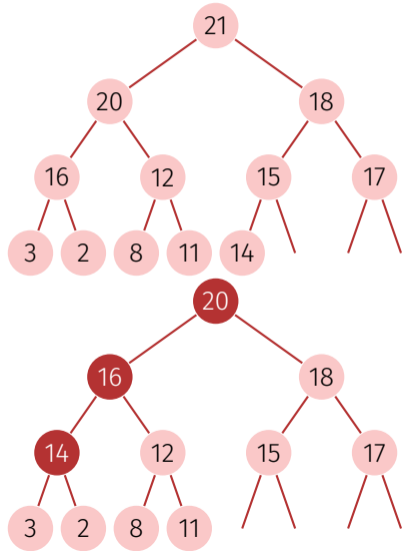
$c \leftarrow p$  // parent node  $\rightarrow$  current node

$p \leftarrow \lfloor c/2 \rfloor$

$A[c] \leftarrow v$  // value  $\rightarrow$  root of the (sub)tree

# Remove the maximum

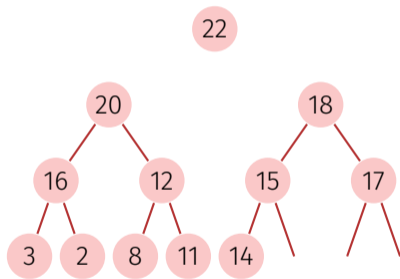
- Replace the maximum by the lower right element
- Reestablish heap property: sink successively (in the direction of the greater child)
- Worst case number of operations:  $\mathcal{O}(\log n)$





# Why this is correct: Recursive heap structure

A heap consists of two heaps:



# Algorithm SiftDown( $A, i, m$ )

**Input:** Array  $A$  with heap structure for the children of  $i$ . Last element  $m$ .

**Output:** Array  $A$  with heap structure for  $i$  with last element  $m$ .

**while**  $2i \leq m$  **do**

$j \leftarrow 2i$ ; //  $j$  left child

**if**  $j < m$  and  $A[j] < A[j + 1]$  **then**

$j \leftarrow j + 1$ ; //  $j$  right child with greater key

**if**  $A[i] < A[j]$  **then**

        swap( $A[i], A[j]$ )

$i \leftarrow j$ ; // keep sinking down

**else**

$i \leftarrow m$ ; // sift down finished

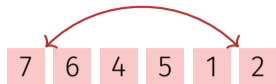
# Sort heap

$A[1, \dots, n]$  is a Heap.

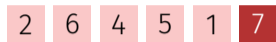
While  $n > 1$

- $\text{swap}(A[1], A[n])$
- $\text{SiftDown}(A, 1, n - 1);$
- $n \leftarrow n - 1$

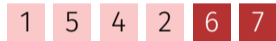
swap  $\Rightarrow$



siftDown  $\Rightarrow$



swap  $\Rightarrow$



siftDown  $\Rightarrow$



swap  $\Rightarrow$



siftDown  $\Rightarrow$



swap  $\Rightarrow$



siftDown  $\Rightarrow$



swap  $\Rightarrow$



# Heap creation

**Observation:** Every leaf of a heap is trivially a correct heap.

**Consequence:** Induction from below!

# Algorithm HeapSort( $A, n$ )

**Input:** Array  $A$  with length  $n$ .

**Output:**  $A$  sorted.

// Build the heap.

**for**  $i \leftarrow n/2$  **downto** 1 **do**

└ SiftDown( $A, i, n$ );

// Now  $A$  is a heap.

**for**  $i \leftarrow n$  **downto** 2 **do**

└ swap( $A[1], A[i]$ )

└ SiftDown( $A, 1, i - 1$ )

// Now  $A$  is sorted.

# Analysis: sorting a heap

SiftDown traverses at most  $\log n$  nodes. For each node 2 key comparisons.  
 $\Rightarrow$  sorting a heap costs in the worst case  $2 \log n$  comparisons.  
Number of memory movements of sorting a heap also  $\mathcal{O}(n \log n)$ .

# Analysis: creating a heap

Calls to siftDown:  $n/2$ .

Thus number of comparisons and movements:  $v(n) \in \mathcal{O}(n \log n)$ .

But mean length of the sift-down paths is much smaller:

We use that  $h(n) = \lceil \log_2 n + 1 \rceil = \lfloor \log_2 n \rfloor + 1$  für  $n > 0$

$$\begin{aligned} v(n) &= \sum_{l=0}^{\lfloor \log_2 n \rfloor} \underbrace{2^l}_{\text{number heaps on level } l} \cdot \underbrace{(\lfloor \log_2 n \rfloor + 1 - l - 1)}_{\text{height heaps on level } l} = \sum_{k=0}^{\lfloor \log_2 n \rfloor} 2^{\lfloor \log_2 n \rfloor - k} \cdot k \\ &= 2^{\lfloor \log_2 n \rfloor} \cdot \sum_{k=0}^{\lfloor \log_2 n \rfloor} \frac{k}{2^k} \leq n \cdot \sum_{k=0}^{\infty} \frac{k}{2^k} \leq n \cdot 2 \in \mathcal{O}(n) \end{aligned}$$

with  $s(x) := \sum_{k=0}^{\infty} kx^k = \frac{x}{(1-x)^2}$  ( $0 < x < 1$ ) and  $s(\frac{1}{2}) = 2$