



# Exercise Session 13

Data Structures and Algorithms, D-MATH, ETH Zurich

# Program of today

Feedback of last exercise

Repetition theory

Next Exercise

## 1. Feedback of last exercise

## Exercise: Sum of a vector

```
void sum_par( Iterator beg, Iterator end, int& result ) {
    const int nThreads = std::thread::hardware_concurrency();
    std::vector<std::thread> myThreads;
    std::vector<int> sums( nThreads, 0 );
    const int partSize = (end-beg)/nThreads;

    for( int i=0; i<nThreads-1; ++i ){
        myThreads.emplace_back(
            std::thread(sum_ser, beg, beg + partSize, std::ref(sums[i])));
        beg += partSize;
    }
    // ...
    for( auto& t:myThreads ) t.join();
    sum_ser( sums.begin(), sums.end(), result );
}
```

# Exercise: Sum of a vector

```
void sum_ser(
    Iterator from,
    Iterator to,
    int& result ) {

    int local = 0;
    for( ;from != to; ++from )
        local += *from;
    result = local;
}
```

```
void sum_ser(
    Iterator from,
    Iterator to,
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Difference?

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Difference?

execution time: 0.468879 ms

execution time: 0.944031 ms

# Exercise: Sum of a vector – False Sharing!

```
void sum_ser(
    Iterator from,
    Iterator to,
    int& result ) {

    int local = 0;
    for( ;from != to; ++from )
        local += *from;
    result = local;
}
```

```
void sum_ser(
    Iterator from,
    Iterator to,
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    result = 0;
    for( ;from != to; ++from )
        result += *from;
}
```

Difference?

execution time: 0.468879 ms

execution time: 0.944031 ms

# Exercise: Mergesort (2-threads)

```
void mergesort_par( std::vector<int> & v ) {  
    int n = v.size();  
    int partSize = n / 2;  
  
    std::thread t1( mergesort, std::ref(v), 0, partSize-1 );  
    std::thread t2( mergesort, std::ref(v), partSize, n-1 );  
    t1.join();  
    t2.join();  
    merge( v, 0, partSize-1, n-1 );  
}
```

analogously with  $n$  threads

# Exercise: Mergesort Recursively

```
void mergesort_par(std::vector<int> & v, int cutoff, int l, int r) {  
    if (r-l < cutoff){ // sequential base case  
        mergesort( v, l, r );  
    } else {  
        int m = ( l+r )/2 ;  
        std::thread t (mergesort_par,std::ref(v),cutoff,l,m);  
        mergesort_par(v,cutoff,m+1,r); // avoid forking another thread  
        t.join();  
        merge(v,l,m,r);  
    }  
}
```

## 2. Repetition theory

# Parallel Performance

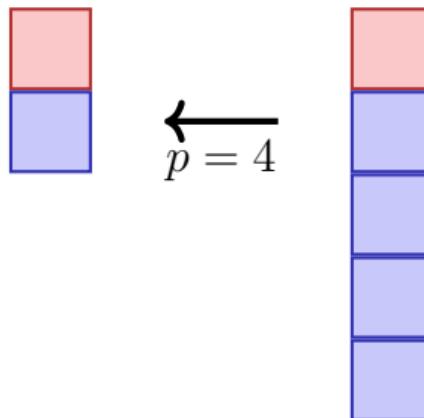
Given

- fixed amount of computing work  $W$  (number computing steps)
- Sequential execution time  $T_1$
- Parallel execution time on  $p$  CPUs

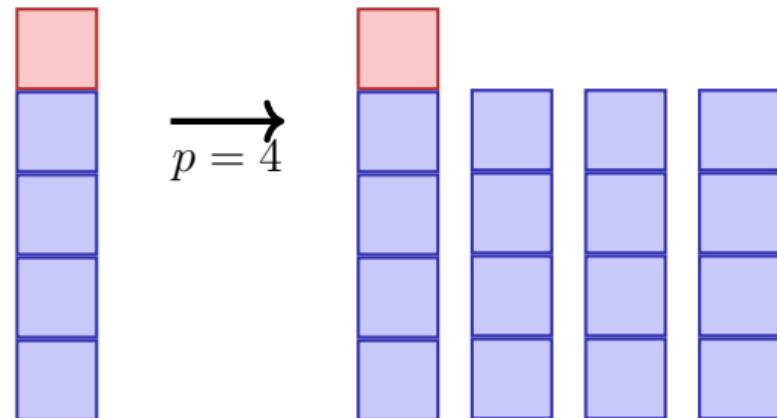
	runtime	speedup	efficiency
perfection (linear)	$T_p = T_1/p$	$S_p = p$	$E_p = 1$
loss (sublinear)	$T_p > T_1/p$	$S_p < p$	$E_p < 1$
sorcery (superlinear)	$T_p < T_1/p$	$S_p > p$	$E_p > 1$

# Amdahl vs. Gustafson

Amdahl



Gustafson



# Amdahl vs. Gustafson, or why do we care?

<b>Amdahl</b>	<b>Gustafson</b>
pessimist	optimist
strong scaling	weak scaling

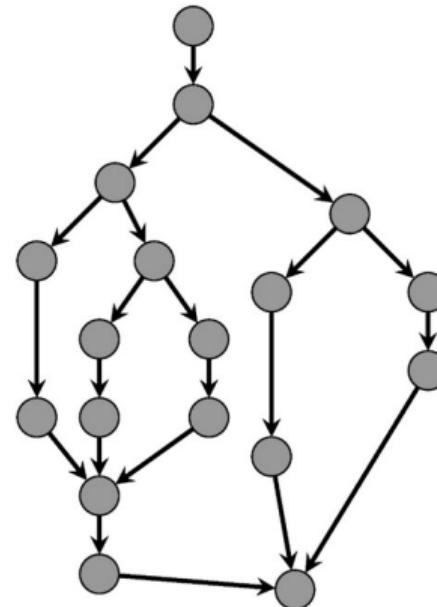
# Amdahl vs. Gustafson, or why do we care?

<b>Amdahl</b>	<b>Gustafson</b>
pessimist	optimist
strong scaling	weak scaling

⇒ need to develop methods with small sequential portion as possible.

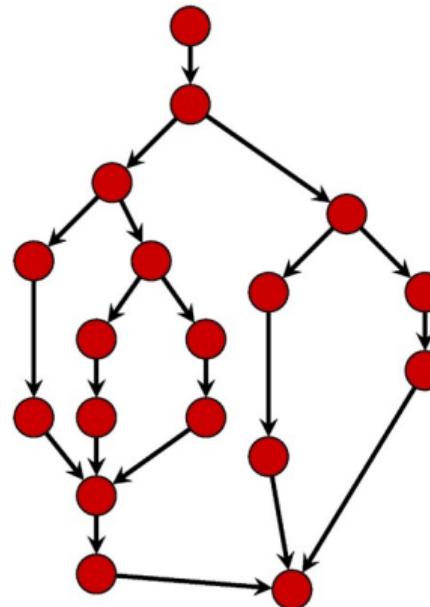
# Task Parallelism: Performance Model

- $p$  processors
- Dynamic scheduling
- $T_p$ : Execution time on  $p$  processors



# Performance Model

- $T_p$ : Execution time on  $p$  processors
- $T_1$ : **work**: time for executing total work on one processor
- $T_1/T_p$ : Speedup

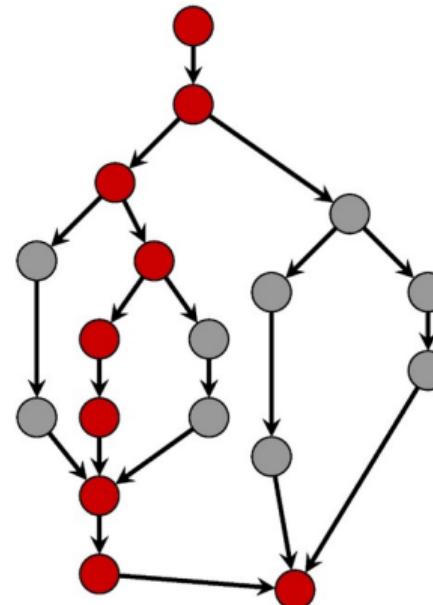


# Performance Model

- $T_\infty$ : **span**: critical path, execution time on  $\infty$  processors. Longest path from root to sink.
- $T_1/T_\infty$ : **Parallelism**: wider is better
- Lower bounds:

$$T_p \geq T_1/p \quad \text{Work law}$$

$$T_p \geq T_\infty \quad \text{Span law}$$



# Greedy Scheduler

Greedy scheduler: at each time it schedules as many as available tasks.

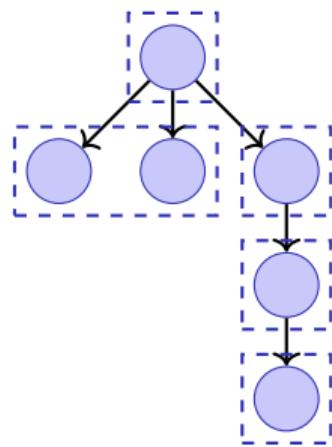
## Theorem 1

*On an ideal parallel computer with  $p$  processors, a greedy scheduler executes a multi-threaded computation with work  $T_1$  and span  $T_\infty$  in time*

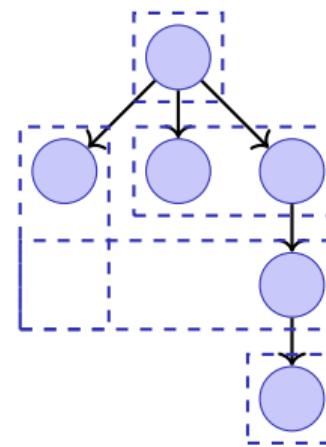
$$T_p \leq T_1/p + T_\infty$$

# Beispiel

Assume  $p = 2$ .



$$T_p = 5$$



$$T_p = 4$$

# Race Conditions

**Data Race** (low-level Race-Conditions) Erroneous program behavior caused by insufficiently synchronized accesses of a shared resource by multiple threads, e.g. Simultaneous read/write or write/write of the same memory location

**Bad Interleaving** (High Level Race Condition) Erroneous program behavior caused by an unfavorable execution order of a multithreaded algorithm, even if that makes use of otherwise well synchronized resources.

# Memory Models

When and if effects of memory operations become visible for threads, depends on hardware, runtime system and programming language.

A **memory model** (e.g. that of C++) provides minimal guarantees for the effect of memory operations

- leaving open possibilities for optimisation
- containing guidelines for writing thread-safe programs

For instance, C++ provides **guarantees when synchronisation with a mutex is used.**

# Counter Problem

```
std::vector<std::thread> tv(10);
int counter {0};
for (auto & t:tv)
    t = std::thread([&]{
        for (int i =0; i<100000; ++i){counter++;} // race!!
    });
for (auto & t:tv)
    t.join();
std::cout << "count= "<< counter << std::endl;
```

# Counter Solution 1

```
std::vector<std::thread> tv(10);
std::mutex lock;
int counter {0};
for (auto & t:tv)
    t = std::thread([&]{
        for (int i =0; i<100000; ++i){
            mutex.lock(); counter++; mutex.unlock(); // synchronized!
        }});
for (auto & t:tv)
    t.join();
std::cout << "count= "<< counter << std::endl;
```

# Counter Solution II

```
std::vector<std::thread> tv(10);
std::atomic<int> counter {0};
for (auto & t:tv)
    t = std::thread([&]{
        for (int i =0; i<100000; ++i){counter++;} // atomic!!
    });
for (auto & t:tv)
    t.join();
std::cout << "count= "<< counter << std::endl;
```

# Quiz:What's wrong with this code?

```
void exchangeSecret(Person & a, Person & b) {  
    a.getMutex()->lock();  
    b.getMutex()->lock();  
    Secret s = a.getSecret();  
    b.setSecret(s);  
    a.getMutex()->unlock();  
    b.getMutex()->unlock()  
}
```

# Deadlock

Thread 1:

```
exchangeSecret(p1, p2);
```

Thread 2:

```
exchangeSecret(p2, p1);
```

# Deadlock

Thread 1:

```
exchangeSecret(p1, p2);
```

Thread 2:

```
exchangeSecret(p2, p1);
```

How to resolve?

# Possible Solution

```
void exchangeSecret(Person & a, Person & b) {  
    std::mutex* first;  
    std::mutex* second;  
    if (a.name < b.name){  
        first = a.getMutex(); second = b.getMutex();  
    } else {  
        first = b.getMutex(); second = a.getMutex();  
    }  
    first->lock();  
    second->lock();  
    Secret s = a.getSecret();  
    b.setSecret(s);  
    first->unlock();  
    second->unlock();  
}
```

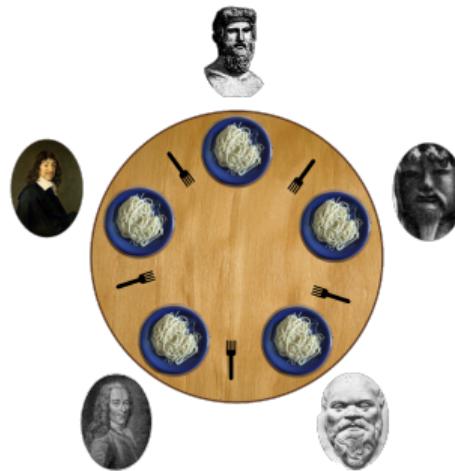
# Deadlocks and Races

- Not easy to spot
- Hard to debug
- Might happen only very rarely
- Testing usually not good enough
- Reasoning about code is required

Lesson learned: Need to be careful when programming with locks!

### 3. Next Exercise

# Dining Philosophers



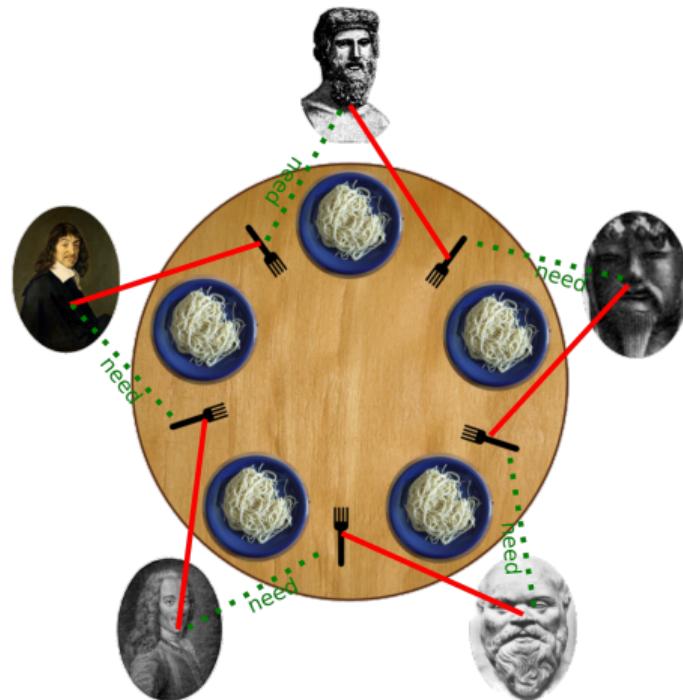
- Philosophers only think and eat. Each needs two forks to eat.
- Philosophers = threads, forks = locks.

# Dining Philosophers - pseudocode

```
while(true) {  
    think();  
    acquire_fork_on_left_side();  
    acquire_fork_on_right_side();  
    eat();  
    release_fork_on_right_side();  
    release_fork_on_left_side();  
}
```

- Problems with this code?

# Dining Philosophers - deadlock



■ Solutions?

# Dining Philosophers

- Resolve cyclic dependency
- For instance: Philosopher five takes first the **right** fork.
- General solution: Define lock order. Then, always lock in that order.