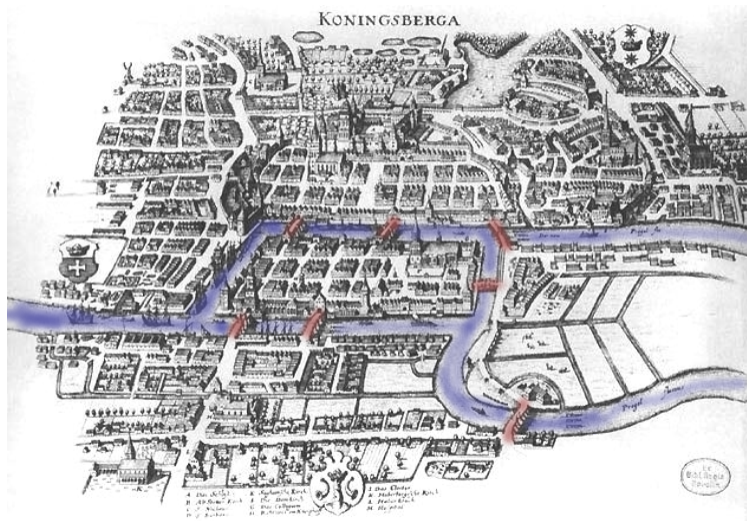


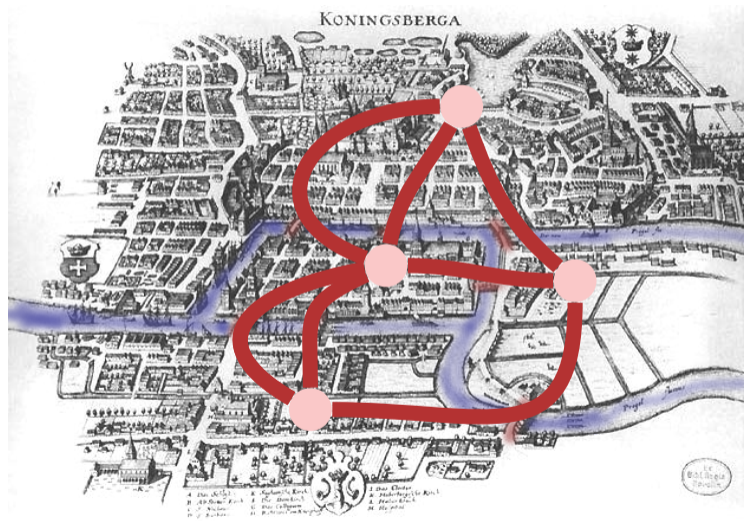
25. Graphs

Notation, Representation, Graph Traversal (DFS, BFS), Topological Sorting , Reflexive transitive closure, Connected components [Ottman/Widmayer, Kap. 9.1 - 9.4, Cormen et al, Kap. 22]

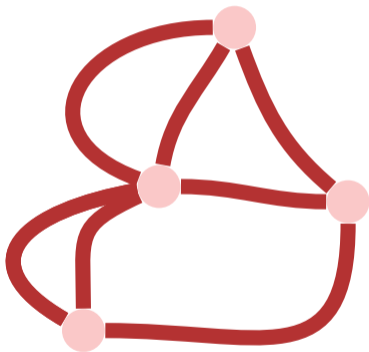
Königsberg 1736



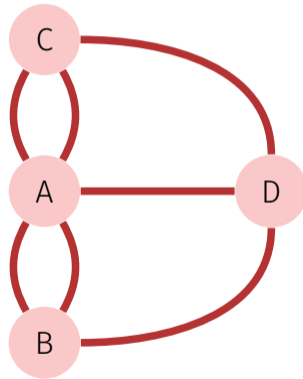
Königsberg 1736



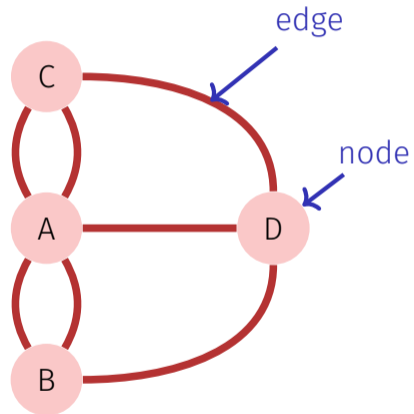
Königsberg 1736



[Multi]Graph

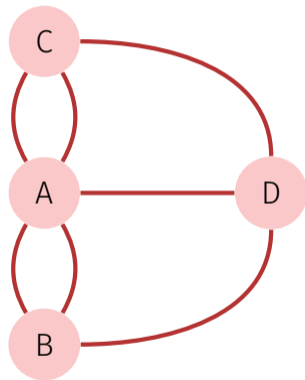


[Multi]Graph



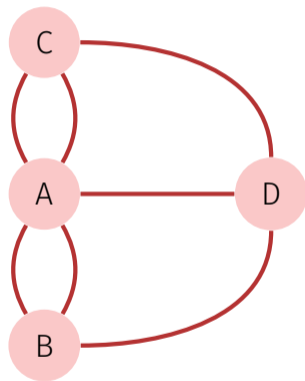
Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?



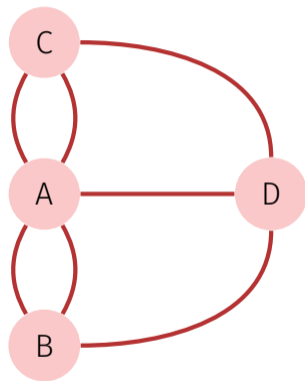
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- Euler (1736): no.



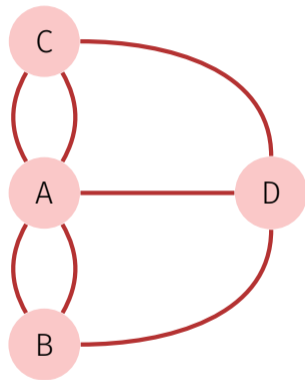
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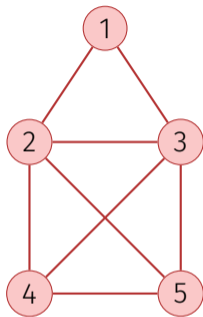


Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?
- Euler (1736): no.
- Such a *cycle* is called *Eulerian path*.
- Eulerian path \Leftrightarrow each node provides an even number of edges (each node is of an *even degree*).
' \Rightarrow ' is straightforward, " \Leftarrow " is a bit more difficult but still elementary.



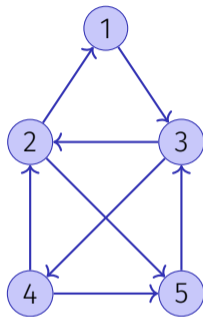
Notation



undirected

$$V = \{1, 2, 3, 4, 5\}$$

$$E = \{\{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \\ \{2, 5\}, \{3, 4\}, \{3, 5\}, \{4, 5\}\}$$



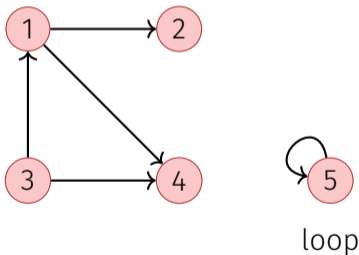
directed

$$V = \{1, 2, 3, 4, 5\}$$

$$E = \{(1, 2), (1, 3), (2, 1), (2, 3), (2, 5), (3, 2), \\ (3, 4), (3, 5), (4, 2), (4, 5), (5, 3)\}$$

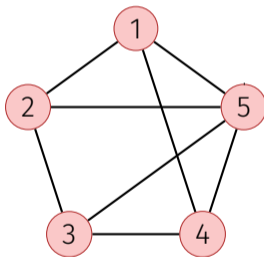
Notation

A **directed graph** consists of a set $V = \{v_1, \dots, v_n\}$ of nodes (*Vertices*) and a set $E \subseteq V \times V$ of Edges. The same edges may not be contained more than once.



Notation

An **undirected graph** consists of a set $V = \{v_1, \dots, v_n\}$ of nodes and a set $E \subseteq \{\{u, v\} | u, v \in V\}$ of edges. Edges may not be contained more than once.⁴¹

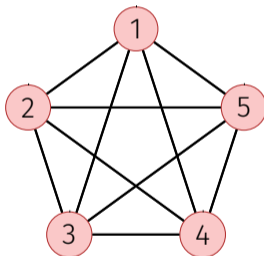


undirected graph

⁴¹As opposed to the introductory example – it is then called multi-graph.

Notation

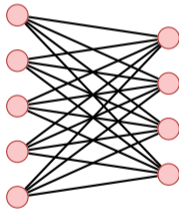
An undirected graph $G = (V, E)$ without loops where E comprises all edges between pairwise different nodes is called **complete**.



a complete undirected graph

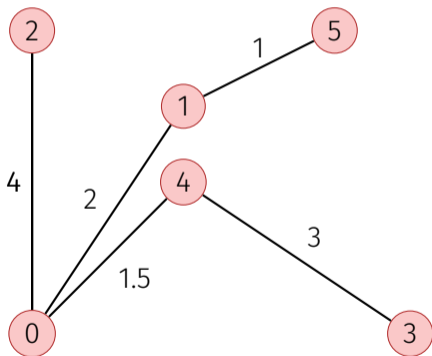
Notation

A graph where V can be partitioned into disjoint sets U and W such that each $e \in E$ provides a node in U and a node in W is called **bipartite**.



Notation

A **weighted graph** $G = (V, E, c)$ is a graph $G = (V, E)$ with an **edge weight function** $c : E \rightarrow \mathbb{R}$. $c(e)$ is called **weight** of the edge e .



Notation

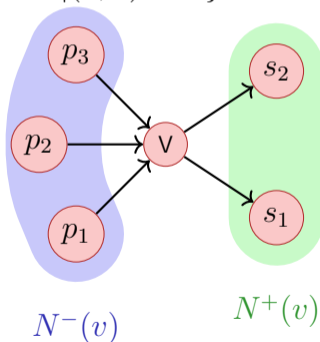
For directed graphs $G = (V, E)$

- $w \in V$ is called adjacent to $v \in V$, if $(v, w) \in E$

Notation

For directed graphs $G = (V, E)$

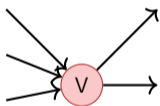
- $w \in V$ is called adjacent to $v \in V$, if $(v, w) \in E$
- **Predecessors** of $v \in V$: $N^-(v) := \{u \in V \mid (u, v) \in E\}$.
Successors: $N^+(v) := \{u \in V \mid (v, u) \in E\}$



Notation

For directed graphs $G = (V, E)$

- **In-Degree:** $\deg^-(v) = |N^-(v)|$,
Out-Degree: $\deg^+(v) = |N^+(v)|$



$$\deg^-(v) = 3, \deg^+(v) = 2$$



$$\deg^-(w) = 1, \deg^+(w) = 1$$

Notation

For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$

Notation

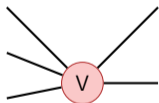
For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$
- **Neighbourhood** of $v \in V$: $N(v) = \{w \in V \mid \{v, w\} \in E\}$

Notation

For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$
- **Neighbourhood** of $v \in V$: $N(v) = \{w \in V \mid \{v, w\} \in E\}$
- **Degree** of v : $\deg(v) = |N(v)|$ with a special case for the loops: increase the degree by 2.



$$\deg(v) = 5$$



$$\deg(w) = 2$$

Relationship between node degrees and number of edges

For each graph $G = (V, E)$ it holds

1. $\sum_{v \in V} \deg^-(v) = \sum_{v \in V} \deg^+(v) = |E|$, for G directed
2. $\sum_{v \in V} \deg(v) = 2|E|$, for G undirected.

Paths

- **Path:** a sequence of nodes $\langle v_1, \dots, v_{k+1} \rangle$ such that for each $i \in \{1 \dots k\}$ there is an edge from v_i to v_{i+1} .

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- **Simple path:** path without repeating vertices

Connectedness

- An undirected graph is called **connected**, if for each pair $v, w \in V$ there is a connecting path.
- A directed graph is called **strongly connected**, if for each pair $v, w \in V$ there is a connecting path.
- A directed graph is called **weakly connected**, if the corresponding undirected graph is connected.

Simple Observations

- generally: $0 \leq |E| \in \mathcal{O}(|V|^2)$
- connected graph: $|E| \in \Omega(|V|)$
- complete graph: $|E| = \frac{|V| \cdot (|V| - 1)}{2}$ (undirected)
- Maximally $|E| = |V|^2$ (directed), $|E| = \frac{|V| \cdot (|V| + 1)}{2}$ (undirected)

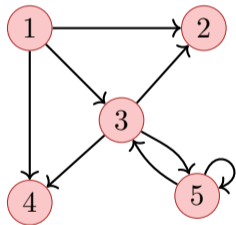
Cycles

- **Cycle:** path $\langle v_1, \dots, v_{k+1} \rangle$ with $v_1 = v_{k+1}$
- **Simple cycle:** Cycle with pairwise different v_1, \dots, v_k , that does not use an edge more than once.
- **Acyclic:** graph without any cycles.

Conclusion: undirected graphs cannot contain cycles with length 2 (loops have length 1)

Representation using a Matrix

Graph $G = (V, E)$ with nodes $v_1 \dots, v_n$ stored as **adjacency matrix**
 $A_G = (a_{ij})_{1 \leq i, j \leq n}$ with entries from $\{0, 1\}$. $a_{ij} = 1$ if and only if edge from v_i to v_j .

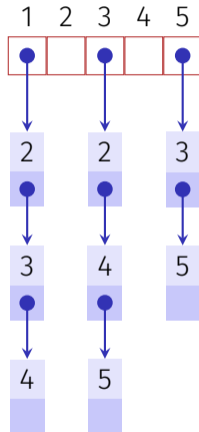
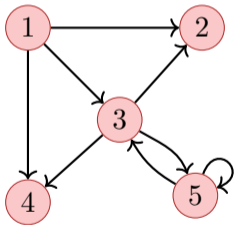


$$\begin{pmatrix} 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}$$

Memory consumption $\Theta(|V|^2)$. A_G is symmetric, if G undirected.

Representation with a List

Many graphs $G = (V, E)$ with nodes v_1, \dots, v_n provide much less than n^2 edges. Representation with **adjacency list**: Array $A[1], \dots, A[n]$, A_i comprises a linked list of nodes in $N^+(v_i)$.



Memory Consumption $\Theta(|V| + |E|)$.

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$		
find $v \in V$ without neighbour/successor		
$(u, v) \in E$?		
Insert edge		
Delete edge		

Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	
find $v \in V$ without neighbour/successor		
$(u, v) \in E$?		
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Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor		
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Runtimes of simple Operations

Operation	Matrix	List
Find neighbours/successors of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour/successor	$\Theta(n^2)$	
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Runtimes of simple Operations

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$(u, v) \in E ?$	$\Theta(1)$	
Insert edge		
Delete edge		

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Runtimes of simple Operations

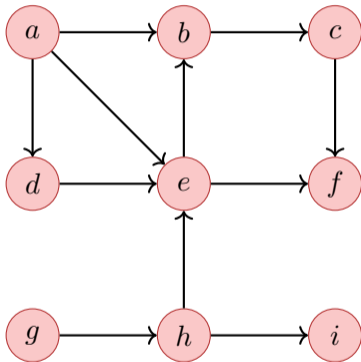
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Runtimes of simple Operations

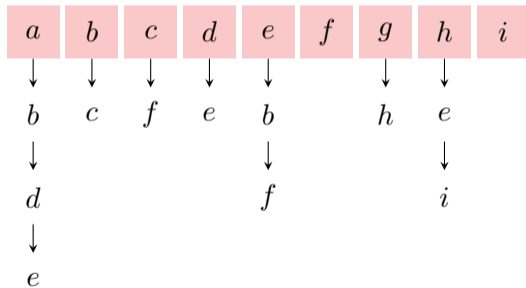
Operation	Matrix	List
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Insert edge	$\Theta(1)$	$\Theta(1)$
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Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.

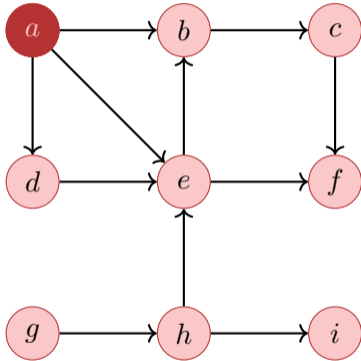


Adjazenzliste

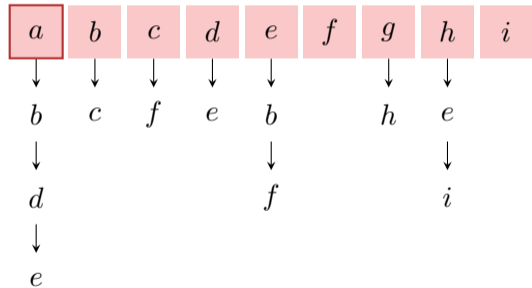


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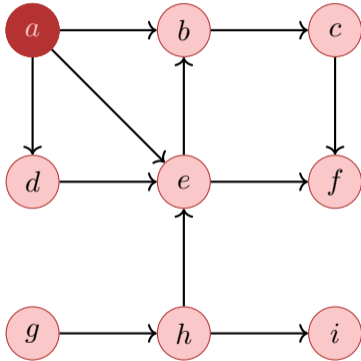


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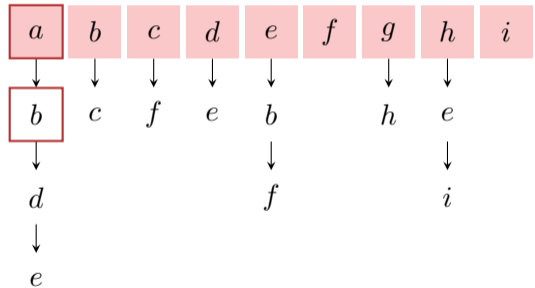


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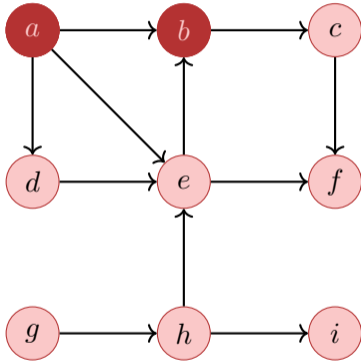


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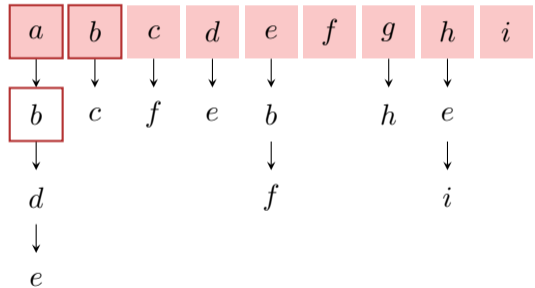


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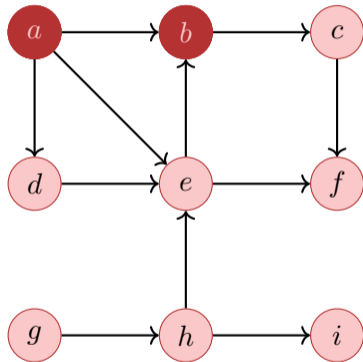


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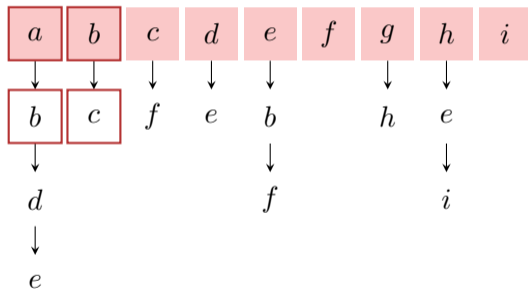


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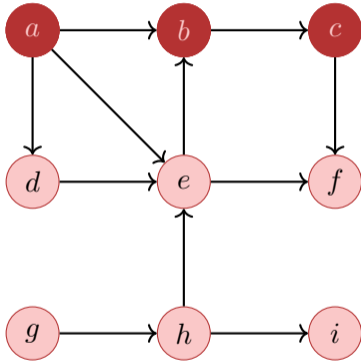


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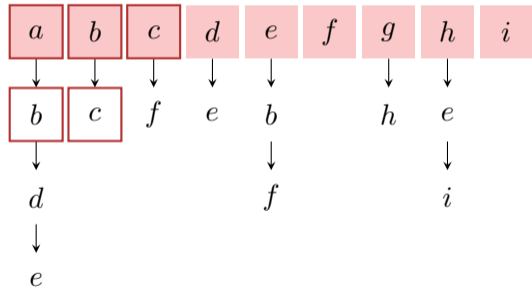


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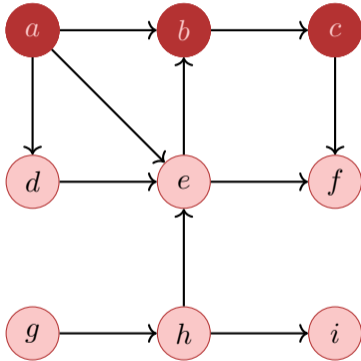


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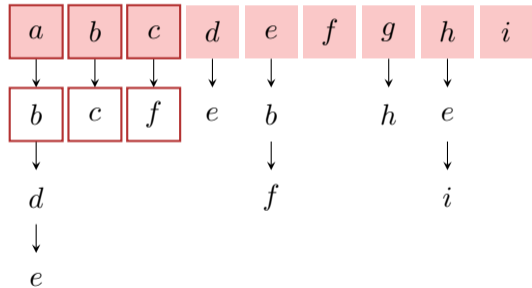


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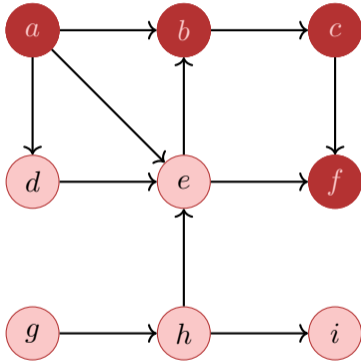


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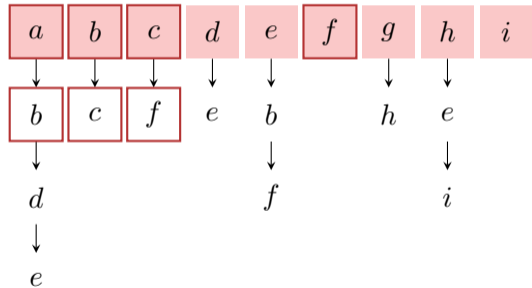


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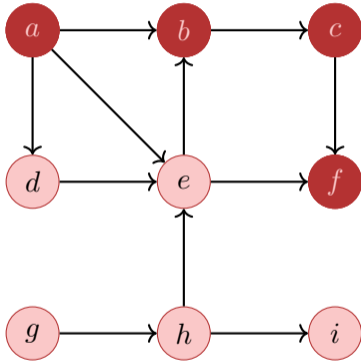


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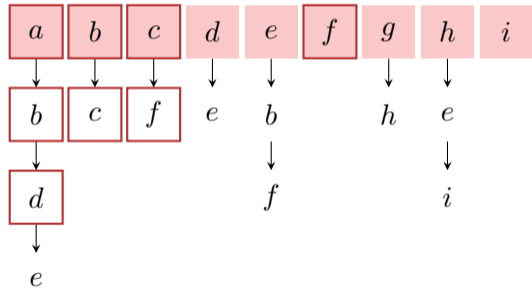


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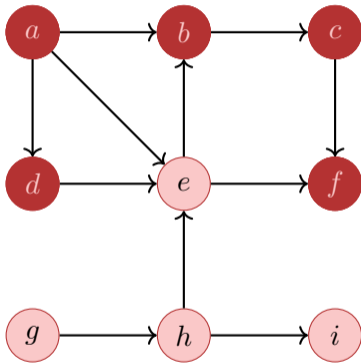


Adjazenzliste

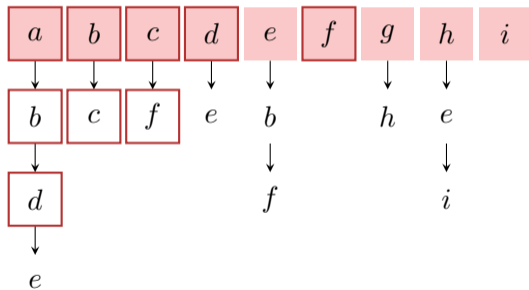


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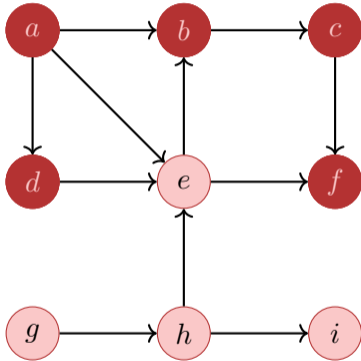


Adjazenzliste

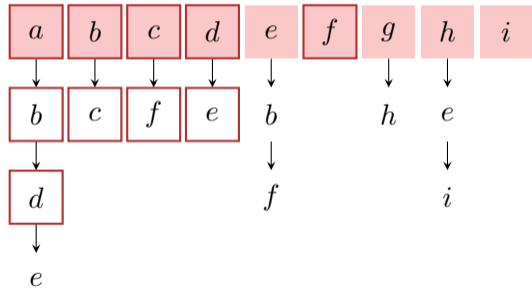


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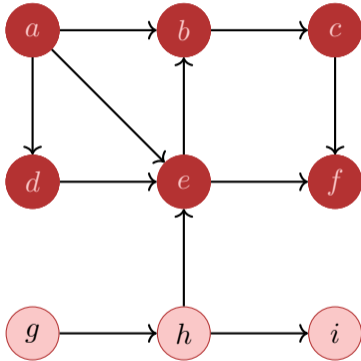


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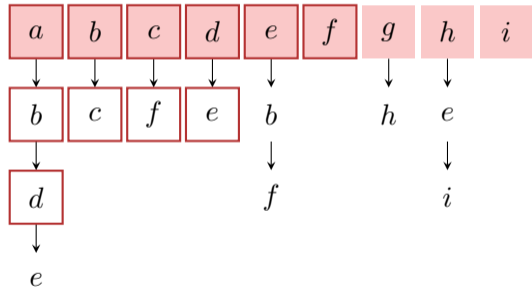


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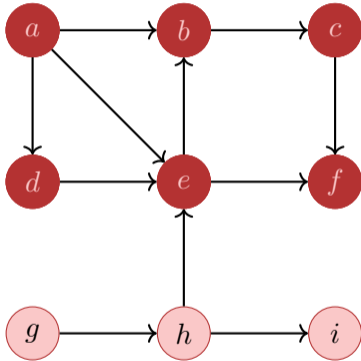


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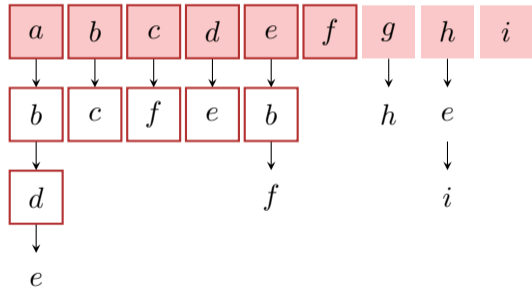


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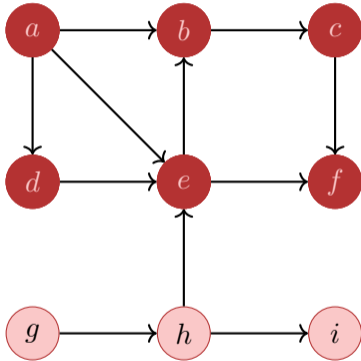


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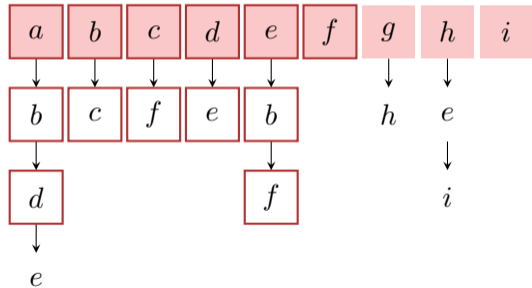


Graph Traversal: Depth First Search

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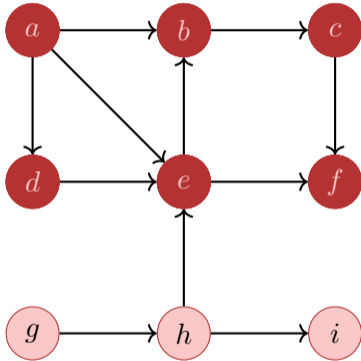


Adjazenzliste

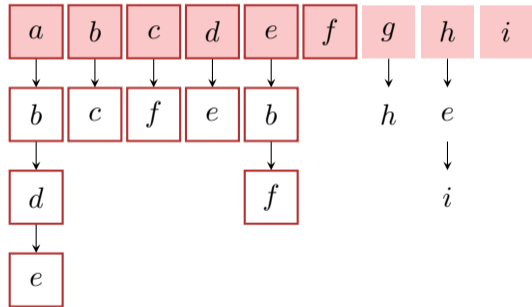


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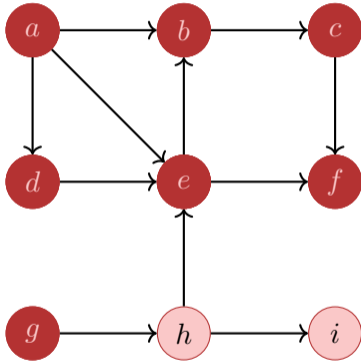


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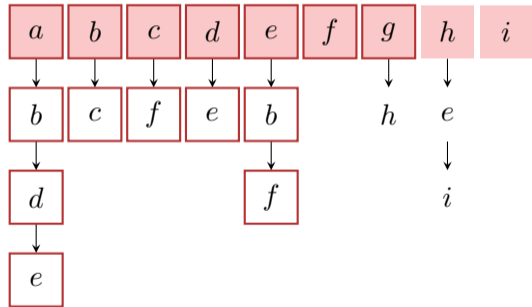


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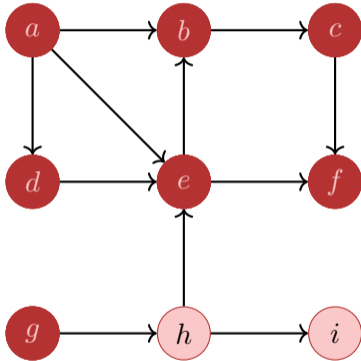


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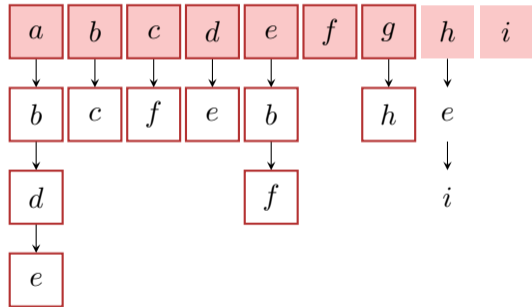


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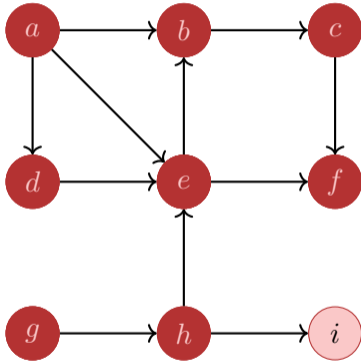


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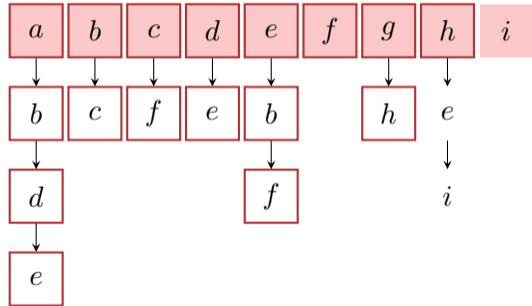


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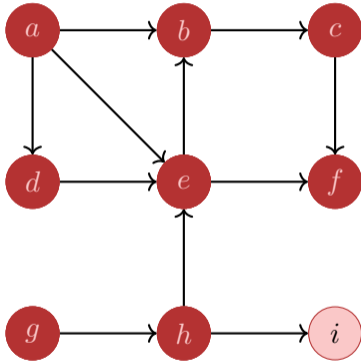


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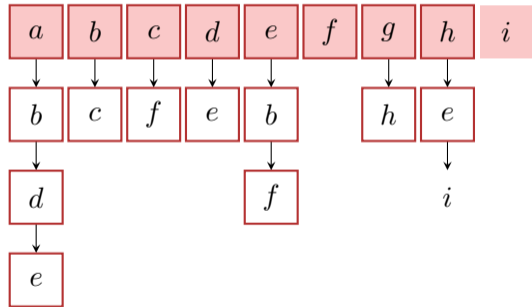


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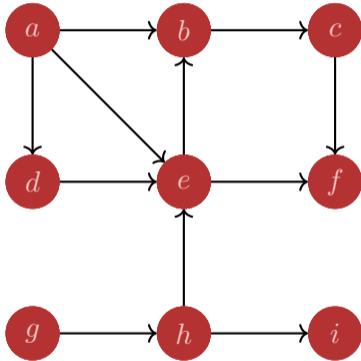


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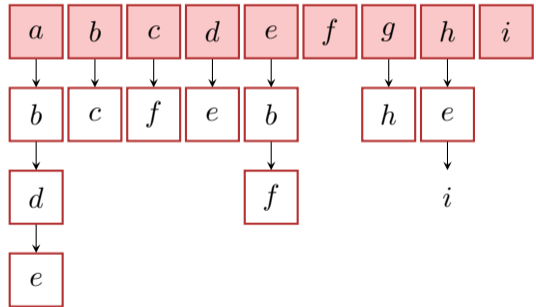
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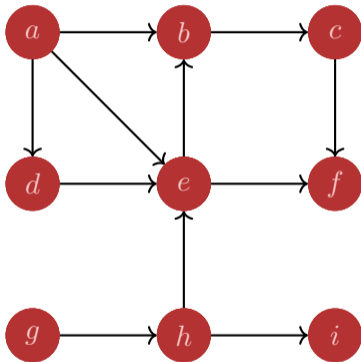
Order $a, b, c, f, d, e, g, h, i$

Adjazenzliste



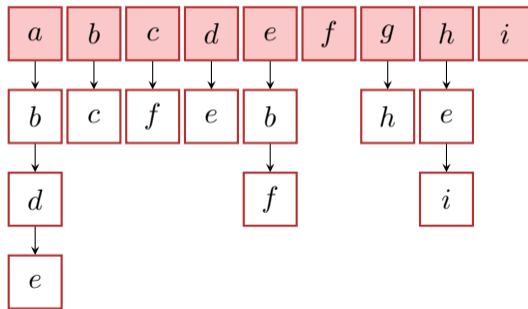
Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.



Order $a, b, c, f, d, e, g, h, i$

Adjazenzliste



Conceptual coloring of nodes

- **white:** node has not been discovered yet.
- **grey:** node has been discovered and is marked for traversal / being processed.
- **black:** node was discovered and entirely processed.

Algorithm Depth First visit DFS-Visit(G, v)

Input: graph $G = (V, E)$, Knoten v .

$v.color \leftarrow \text{grey}$

foreach $w \in N^+(v)$ **do**

if $w.color = \text{white}$ **then**
 └ DFS-Visit(G, w)

$v.color \leftarrow \text{black}$

Depth First Search starting from node v . Running time (without recursion):
 $\Theta(\text{deg}^+ v)$

Algorithm Depth First visit DFS-Visit(G)

Input: graph $G = (V, E)$

foreach $v \in V$ **do**

└ $v.color \leftarrow \text{white}$

foreach $v \in V$ **do**

└ **if** $v.color = \text{white}$ **then**
└ DFS-Visit(G, v)

Depth First Search for all nodes of a graph. Running time:

$$\Theta(|V| + \sum_{v \in V} (\deg^+(v) + 1)) = \Theta(|V| + |E|).$$

Iterative DFS-Visit(G, v)

Input: graph $G = (V, E)$, $v \in V$ with $v.color = \text{white}$

Stack $S \leftarrow \emptyset$

$v.color \leftarrow \text{grey}$; $S.push(v)$ // invariant: grey nodes always on stack

while $S \neq \emptyset$ **do**

$w \leftarrow \text{nextWhiteSuccessor}(v)$ // code: next slide

if $w \neq \text{null}$ **then**

$w.color \leftarrow \text{grey}$; $S.push(w)$

$v \leftarrow w$ // work on w . parent remains on the stack

else

$v.color \leftarrow \text{black}$ // no grey successors, v becomes black

if $S \neq \emptyset$ **then**

$v \leftarrow S.pop()$ // visit/revisit next node

if $v.color = \text{grey}$ **then** $S.push(v)$

Memory Consumption Stack $\Theta(|V|)$

nextWhiteSuccessor(v)

Input: node $v \in V$

Output: Successor node u of v with $u.color = \text{white}$, null otherwise

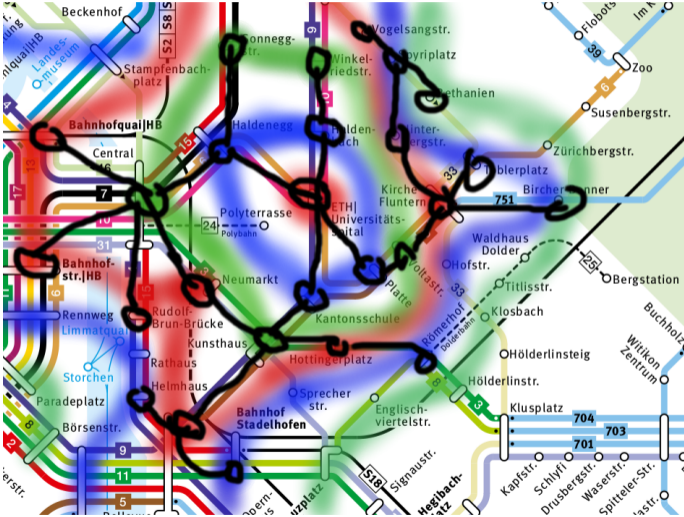
```
foreach  $u \in N^+(v)$  do
  if  $u.color = \text{white}$  then
    return  $u$ 
return null
```

Interpretation of the Colors

When traversing the graph, a tree (or Forest) is built. When nodes are discovered there are three cases

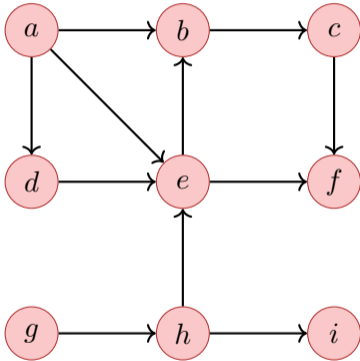
- White node: new tree edge
- Grey node: Zyklus (“back-edge”)
- Black node: forward- / cross edge

Breadth First Search

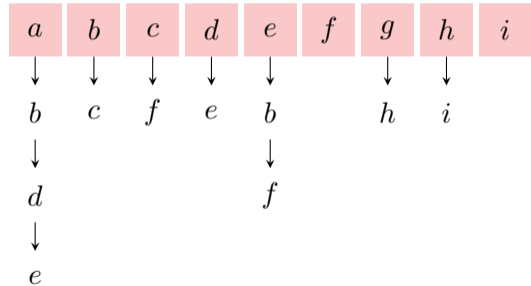


Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.

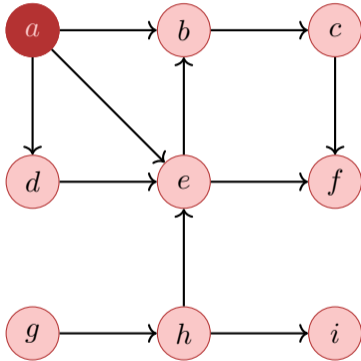


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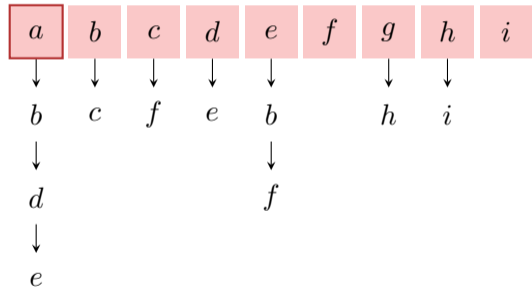


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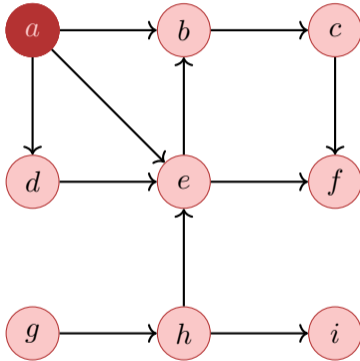


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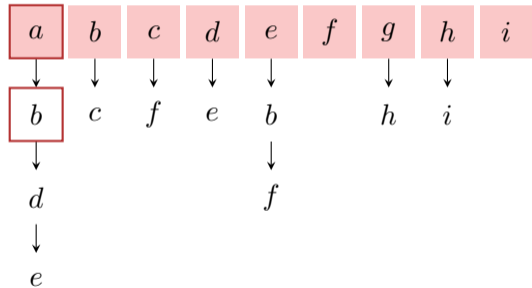


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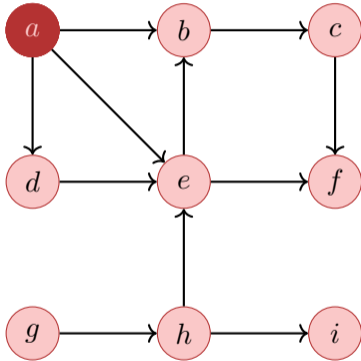


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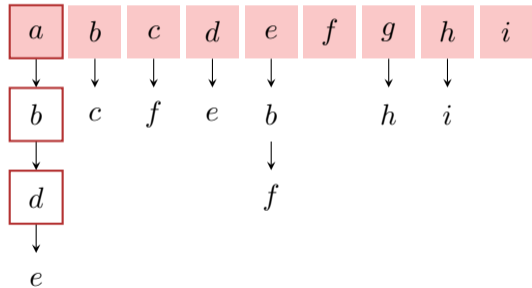


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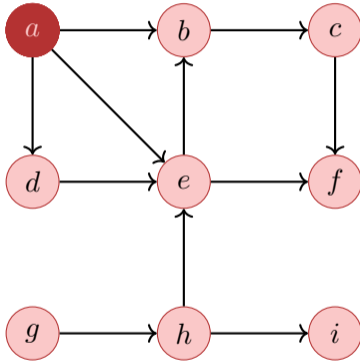


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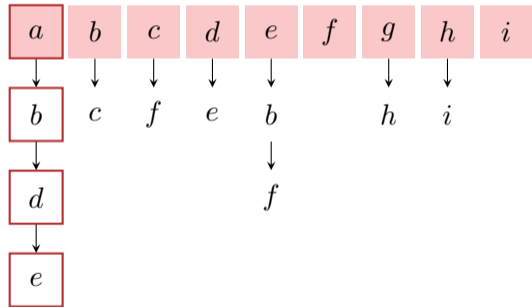


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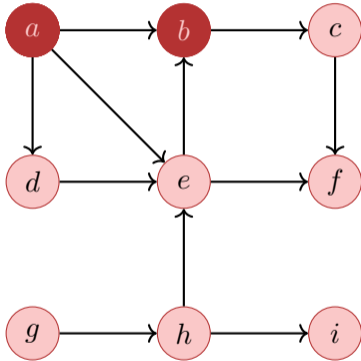


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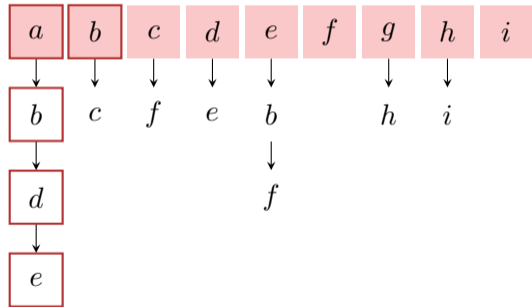


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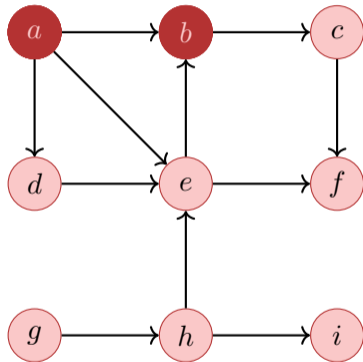


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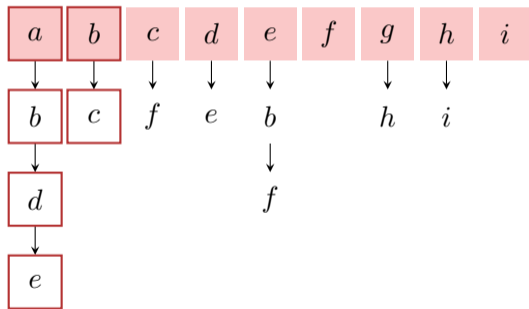


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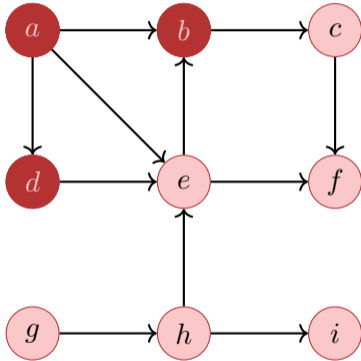


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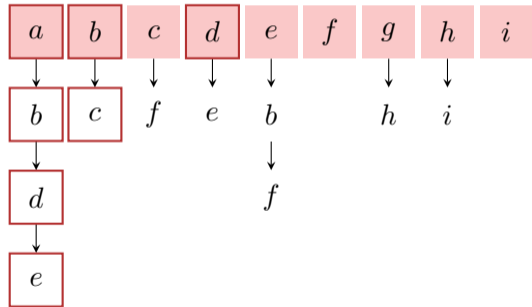


Graph Traversal: Breadth First Search

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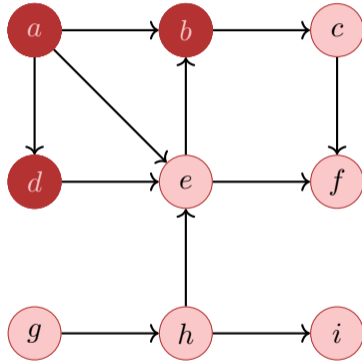


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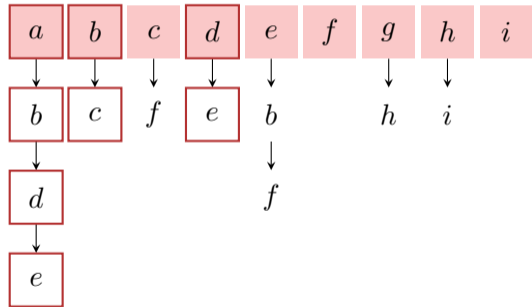


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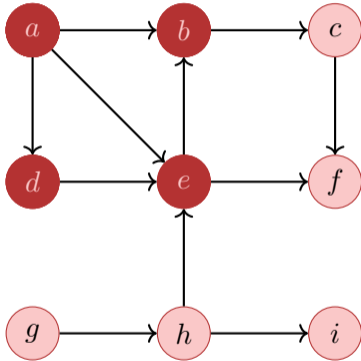


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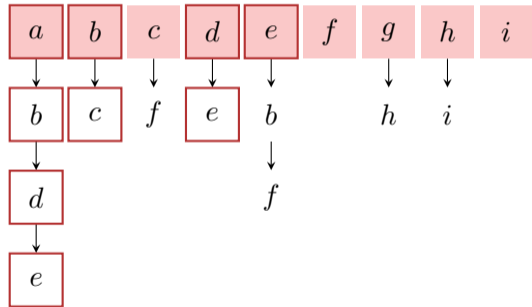


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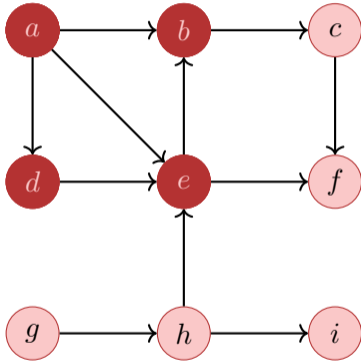


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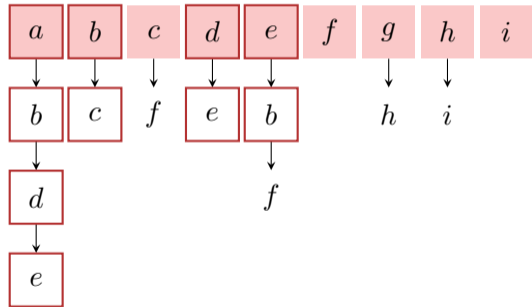


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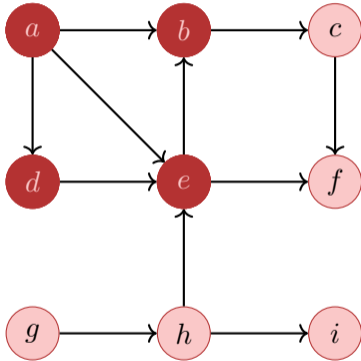


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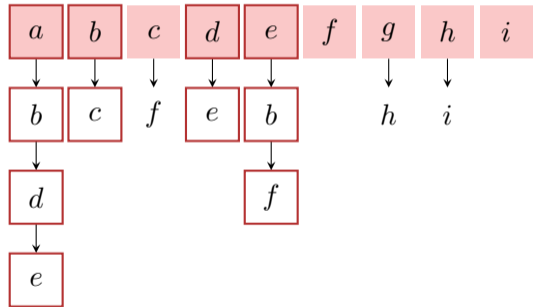


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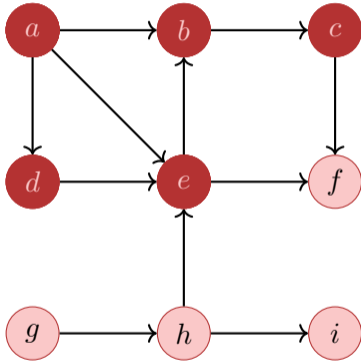


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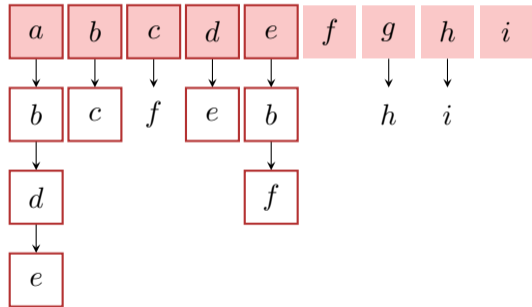


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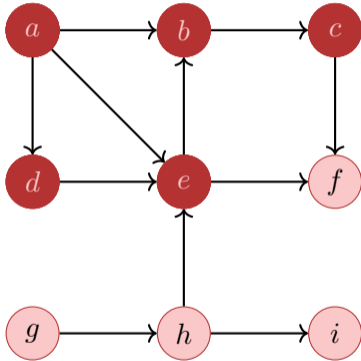


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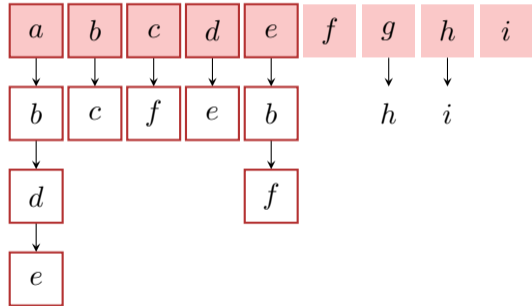


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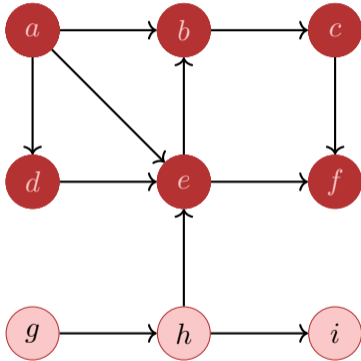


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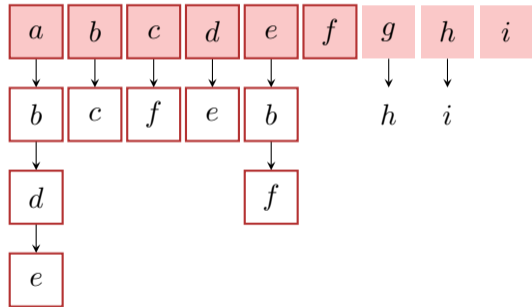


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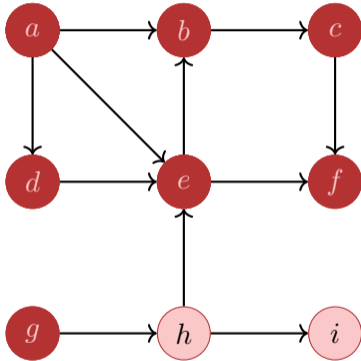


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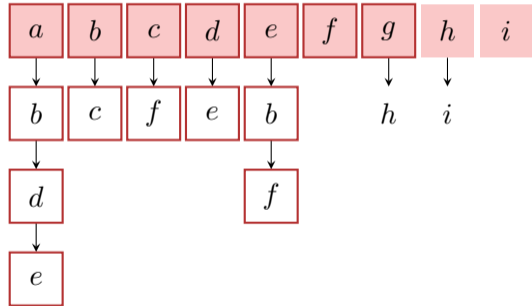


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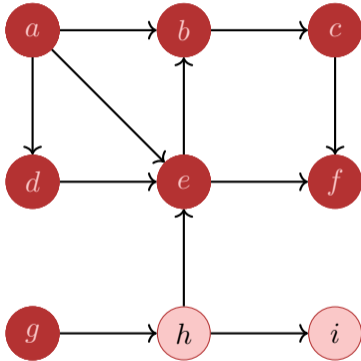


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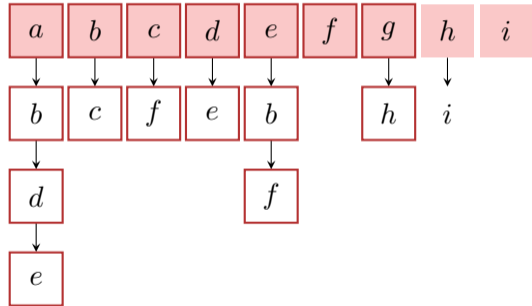


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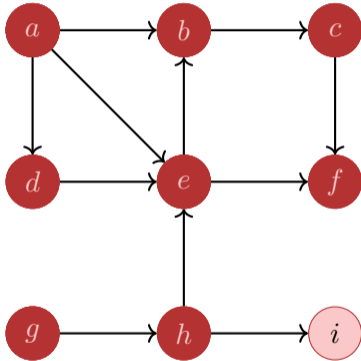


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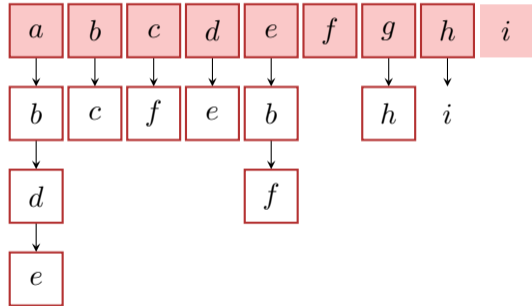


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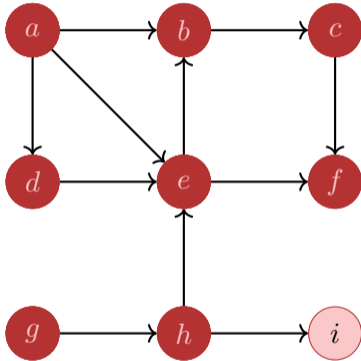


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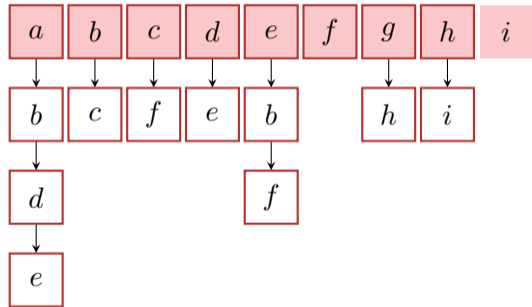


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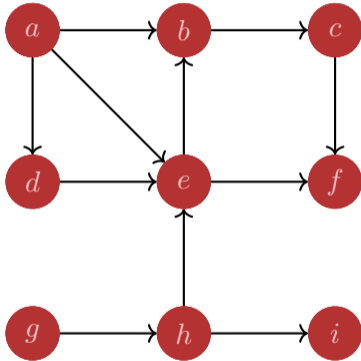


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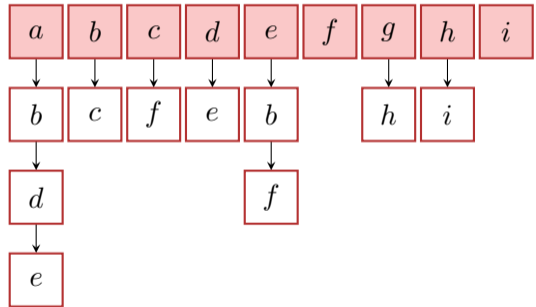
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Order $a, b, d, e, c, f, g, h, i$

Adjazenzliste



(Iterative) BFS-Visit(G, v)

Input: graph $G = (V, E)$

Queue $Q \leftarrow \emptyset$

$v.color \leftarrow \text{grey}$

enqueue(Q, v)

while $Q \neq \emptyset$ **do**

$w \leftarrow \text{dequeue}(Q)$

foreach $c \in N^+(w)$ **do**

if $c.color = \text{white}$ **then**

$c.color \leftarrow \text{grey}$

 enqueue(Q, c)

$w.color \leftarrow \text{black}$

Algorithm requires extra space of $\mathcal{O}(|V|)$.

Main program BFS-Visit(G)

Input: graph $G = (V, E)$

foreach $v \in V$ **do**

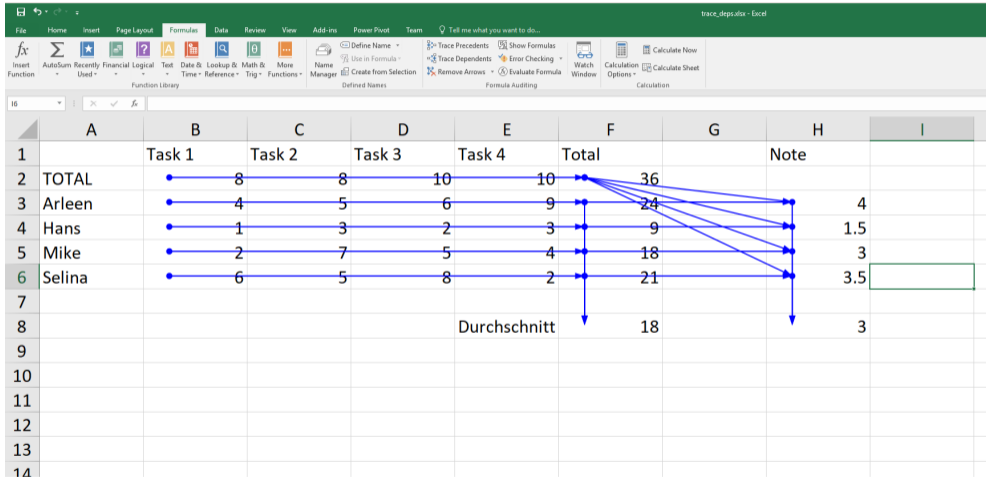
└ $v.color \leftarrow \text{white}$

foreach $v \in V$ **do**

└ **if** $v.color = \text{white}$ **then**
└└ BFS-Visit(G, v)

Breadth First Search for all nodes of a graph. Running time: $\Theta(|V| + |E|)$.

Topological Sorting



Evaluation Order?

Topological Sorting

Topological Sorting of an acyclic directed graph $G = (V, E)$:

Bijjective mapping

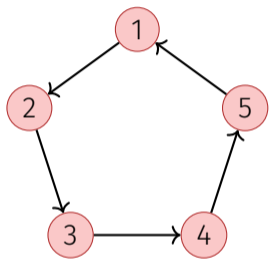
$$\text{ord} : V \rightarrow \{1, \dots, |V|\}$$

such that

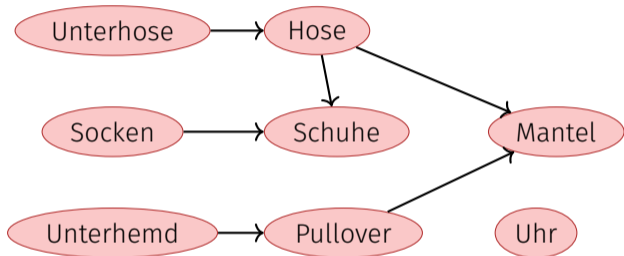
$$\text{ord}(v) < \text{ord}(w) \forall (v, w) \in E.$$

Identify i with Element $v_i := \text{ord}^{-1}(i)$. Topological sorting $\hat{=} \langle v_1, \dots, v_{|V|} \rangle$.

(Counter-)Examples



Cyclic graph: cannot be sorted topologically.



A possible topological sorting of the graph:
Unterhemd,Pullover,Unterhose,Uhr,Hose,Mantel,Socken,S

Observation

Theorem 22

A directed graph $G = (V, E)$ permits a topological sorting if and only if it is acyclic.

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A directed graph $G = (V, E)$ permits a topological sorting if and only if it is acyclic.

Proof “ \Rightarrow ”: If G contains a cycle it cannot permit a topological sorting, because in a cycle $\langle v_{i_1}, \dots, v_{i_m} \rangle$ it would hold that $v_{i_1} < \dots < v_{i_m} < v_{i_1}$.

Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, $\text{setord}(v_1) = 1$.

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- Step ($n \rightarrow n + 1$):
 1. G contains a node v_q with in-degree $\text{deg}^-(v_q) = 0$. Otherwise iteratively follow edges backwards – after at most $n + 1$ iterations a node would be revisited. Contradiction to the cycle-freeness.
 2. Graph without node v_q and without its edges can be topologically sorted by the hypothesis. Now use this sorting and set $\text{ord}(v_i) \leftarrow \text{ord}(v_i) + 1$ for all $i \neq q$ and set $\text{ord}(v_q) \leftarrow 1$.

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.

Worst case runtime:

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3. Set $\text{ord}(v_q) \leftarrow d$.
4. Remove v_q and his edges from G .

Worst case runtime:

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

1. Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
2. If no node with in-degree 0 found after n steps, then the graph has a cycle.
3. Set $\text{ord}(v_q) \leftarrow d$.
4. Remove v_q and his edges from G .
5. If $V \neq \emptyset$, then $d \leftarrow d + 1$, go to step 1.

Worst case runtime:

Preliminary Sketch of an Algorithm

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Worst case runtime: $\Theta(|V|^2)$.

Improvement

Idea?

Improvement

Idea?

Compute the in-degree of all nodes in advance and traverse the nodes with in-degree 0 while correcting the in-degrees of following nodes.

Algorithm Topological-Sort(G)

Input: graph $G = (V, E)$.

Output: Topological sorting ord

Stack $S \leftarrow \emptyset$

foreach $v \in V$ **do** $A[v] \leftarrow 0$

foreach $(v, w) \in E$ **do** $A[w] \leftarrow A[w] + 1$ // Compute in-degrees

foreach $v \in V$ with $A[v] = 0$ **do** $\text{push}(S, v)$ // Memorize nodes with in-degree 0

$i \leftarrow 1$

while $S \neq \emptyset$ **do**

$v \leftarrow \text{pop}(S)$; $\text{ord}[v] \leftarrow i$; $i \leftarrow i + 1$ // Choose node with in-degree 0

foreach $(v, w) \in E$ **do** // Decrease in-degree of successors

$A[w] \leftarrow A[w] - 1$

if $A[w] = 0$ **then** $\text{push}(S, w)$

if $i = |V| + 1$ **then return** ord **else return** "Cycle Detected"

Algorithm Correctness

Theorem 23

Let $G = (V, E)$ be a directed acyclic graph. Algorithm `TopologicalSort(G)` computes a topological sorting `ord` for G with runtime $\Theta(|V| + |E|)$.

Algorithm Correctness

Theorem 23

Let $G = (V, E)$ be a directed acyclic graph. Algorithm `TopologicalSort(G)` computes a topological sorting `ord` for G with runtime $\Theta(|V| + |E|)$.

Proof: follows from previous theorem:

1. Decreasing the in-degree corresponds with node removal.
2. In the algorithm it holds for each node v with $A[v] = 0$ that either the node has in-degree 0 or that previously all predecessors have been assigned a value $\text{ord}[u] \leftarrow i$ and thus $\text{ord}[v] > \text{ord}[u]$ for all predecessors u of v . Nodes are put to the stack only once.
3. Runtime: inspection of the algorithm (with some arguments like with graph traversal)

Algorithm Correctness

Theorem 24

Let $G = (V, E)$ be a directed graph containing a cycle. Algorithm `TopologicalSort` terminates within $\Theta(|V| + |E|)$ steps and detects a cycle.

Algorithm Correctness

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Let $G = (V, E)$ be a directed graph containing a cycle. Algorithm `TopologicalSort` terminates within $\Theta(|V| + |E|)$ steps and detects a cycle.

Proof: let $\langle v_{i_1}, \dots, v_{i_k} \rangle$ be a cycle in G . In each step of the algorithm remains $A[v_{i_j}] \geq 1$ for all $j = 1, \dots, k$. Thus k nodes are never pushed on the stack and therefore at the end it holds that $i \leq V + 1 - k$.

The runtime of the second part of the algorithm can become shorter. But the computation of the in-degree costs already $\Theta(|V| + |E|)$.

Alternative: Algorithm DFS-Topsort(G, v)

Input: graph $G = (V, E)$, node v , node list L .

if $v.color = \text{grey}$ **then**

 | stop (Cycle)

if $v.color = \text{black}$ **then**

 | **return**

$v.color \leftarrow \text{grey}$

foreach $w \in N^+(v)$ **do**

 | DFS-Topsort(G, w)

$v.color \leftarrow \text{black}$

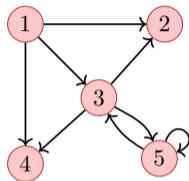
Add v to head of L

Call this algorithm for each node that has not yet been visited. Asymptotic

Running Time $\Theta(|V| + |E|)$.

Adjacency Matrix Product

$$B := A_G^2 = \begin{pmatrix} 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}^2 = \begin{pmatrix} 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 2 \end{pmatrix}$$



Theorem 25

Let $G = (V, E)$ be a graph and $k \in \mathbb{N}$. Then the element $a_{i,j}^{(k)}$ of the matrix $(a_{i,j}^{(k)})_{1 \leq i,j \leq n} = (A_G)^k$ provides the number of paths with length k from v_i to v_j .

Proof

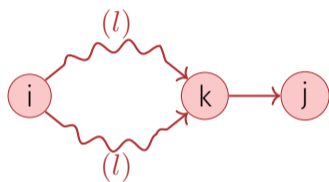
By Induction.

Base case: straightforward for $k = 1$. $a_{i,j} = a_{i,j}^{(1)}$.

Hypothesis: claim is true for all $k \leq l$

Step ($l \rightarrow l + 1$):

$$a_{i,j}^{(l+1)} = \sum_{k=1}^n a_{i,k}^{(l)} \cdot a_{k,j}$$



$a_{k,j} = 1$ iff edge k to j , 0 otherwise. Sum counts the number paths of length l from node v_i to all nodes v_k that provide a direct direction to node v_j , i.e. all paths with length $l + 1$.

Example: Shortest Path

Question: is there a path from i to j ? How long is the shortest path?

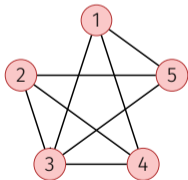
Example: Shortest Path

Question: is there a path from i to j ? How long is the shortest path?

Answer: exponentiate A_G until for some $k < n$ it holds that $a_{i,j}^{(k)} > 0$. k provides the path length of the shortest path. If $a_{i,j}^{(k)} = 0$ for all $1 \leq k < n$, then there is no path from i to j .

Example: Number triangles

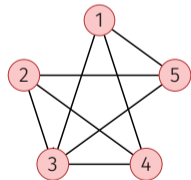
Question: How many triangular path does an undirected graph contain?



Example: Number triangles

Question: How many triangular path does an undirected graph contain?

Answer: Remove all cycles (diagonal entries). Compute A_G^3 . $a_{ii}^{(3)}$ determines the number of paths of length 3 that contain i .

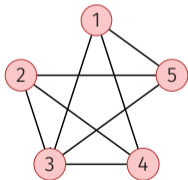


$$\begin{pmatrix} 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \end{pmatrix}^3 = \begin{pmatrix} 4 & 4 & 8 & 8 & 8 \\ 4 & 4 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 4 & 4 \\ 8 & 8 & 8 & 4 & 4 \end{pmatrix}$$

Example: Number triangles

Question: How many triangular path does an undirected graph contain?

Answer: Remove all cycles (diagonal entries). Compute A_G^3 . $a_{ii}^{(3)}$ determines the number of paths of length 3 that contain i . There are 6 different permutations of a triangular path. Thus for the number of triangles:
 $\sum_{i=1}^n a_{ii}^{(3)} / 6$.



$$\begin{pmatrix} 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \end{pmatrix}^3 = \begin{pmatrix} 4 & 4 & 8 & 8 & 8 \\ 4 & 4 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 4 & 4 \\ 8 & 8 & 8 & 4 & 4 \end{pmatrix} \Rightarrow 24/6 = 4 \text{ Dreiecke.}$$

Relation

Given a finite set V

(Binary) **Relation** R on V : Subset of the cartesian product

$$V \times V = \{(a, b) | a \in V, b \in V\}$$

Relation $R \subseteq V \times V$ is called

- **reflexive**, if $(v, v) \in R$ for all $v \in V$
- **symmetric**, if $(v, w) \in R \Rightarrow (w, v) \in R$
- **transitive**, if $(v, x) \in R, (x, w) \in R \Rightarrow (v, w) \in R$

The (Reflexive) Transitive Closure R^* of R is the smallest extension $R \subseteq R^* \subseteq V \times V$ such that R^* is reflexive and transitive.

Graphs and Relations

Graph $G = (V, E)$

adjacencies $A_G \hat{=} \text{Relation } E \subseteq V \times V \text{ over } V$

Graphs and Relations

Graph $G = (V, E)$

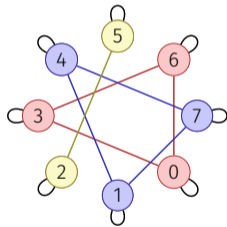
adjacencies $A_G \hat{=} \text{Relation } E \subseteq V \times V \text{ over } V$

- **reflexive** $\Leftrightarrow a_{i,i} = 1$ for all $i = 1, \dots, n$. (loops)
- **symmetric** $\Leftrightarrow a_{i,j} = a_{j,i}$ for all $i, j = 1, \dots, n$ (undirected)
- **transitive** $\Leftrightarrow (u, v) \in E, (v, w) \in E \Rightarrow (u, w) \in E$. (reachability)

Example: Equivalence Relation

Equivalence relation \Leftrightarrow symmetric, transitive, reflexive relation \Leftrightarrow collection of complete, undirected graphs where each element has a loop.

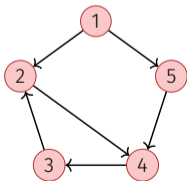
Example: Equivalence classes of the numbers $\{0, \dots, 7\}$ modulo 3



Reflexive Transitive Closure

Reflexive transitive closure of $G \Leftrightarrow$ **Reachability relation** E^* : $(v, w) \in E^*$
iff \exists path from node v to w .

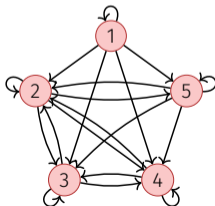
$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$



$G = (V, E)$



$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 \end{bmatrix}$$



$G^* = (V, E^*)$

Computation of the Reflexive Transitive Closure

Goal: computation of $B = (b_{ij})_{1 \leq i, j \leq n}$ with $b_{ij} = 1 \Leftrightarrow (v_i, v_j) \in E^*$

Observation: $a_{ij} = 1$ already implies $(v_i, v_j) \in E^*$.

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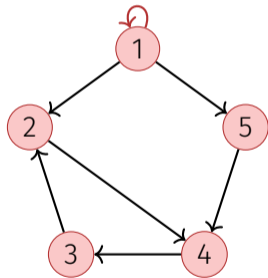
Observation: $a_{ij} = 1$ already implies $(v_i, v_j) \in E^*$.

First idea:

- Start with $B \leftarrow A$ and set $b_{ii} = 1$ for each i (Reflexivity).
- Iterate over i, j, k and set $b_{ij} = 1$, if $b_{ik} = 1$ and $b_{kj} = 1$. Then all paths with length 1 and 2 taken into account.
- Repeated iteration \Rightarrow all paths with length 1 ... 4 taken into account.
- $\lceil \log_2 n \rceil$ iterations required. \Rightarrow running time $n^3 \lceil \log_2 n \rceil$

Improvement: Algorithm of Warshall (1962)

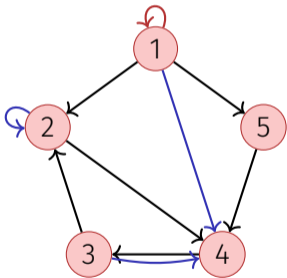
Inductive procedure: all paths known over nodes from $\{v_i : i < k\}$. Add node v_k .



$$\begin{bmatrix} 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Improvement: Algorithm of Warshall (1962)

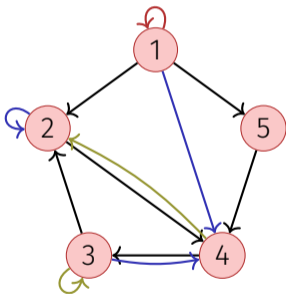
Inductive procedure: all paths known over nodes from $\{v_i : i < k\}$. Add node v_k .



$$\begin{bmatrix} 1 & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Improvement: Algorithm of Warshall (1962)

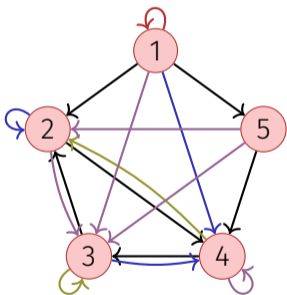
Inductive procedure: all paths known over nodes from $\{v_i : i < k\}$. Add node v_k .



$$\begin{bmatrix} 1 & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Improvement: Algorithm of Warshall (1962)

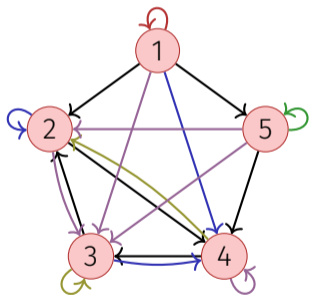
Inductive procedure: all paths known over nodes from $\{v_i : i < k\}$. Add node v_k .



$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{bmatrix}$$

Improvement: Algorithm of Warshall (1962)

Inductive procedure: all paths known over nodes from $\{v_i : i < k\}$. Add node v_k .



$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 \end{bmatrix}$$

Algorithm TransitiveClosure(A_G)

Input: Adjacency matrix $A_G = (a_{ij})_{i,j=1\dots n}$

Output: Reflexive transitive closure $B = (b_{ij})_{i,j=1\dots n}$ of G

$B \leftarrow A_G$

for $k \leftarrow 1$ **to** n **do**

$a_{kk} \leftarrow 1$

// Reflexivity

for $i \leftarrow 1$ **to** n **do**

for $j \leftarrow 1$ **to** n **do**

$b_{ij} \leftarrow \max\{b_{ij}, b_{ik} \cdot b_{kj}\}$

// All paths via v_k

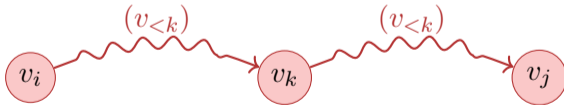
return B

Runtime $\Theta(n^3)$.

Correctness of the Algorithm (Induction)

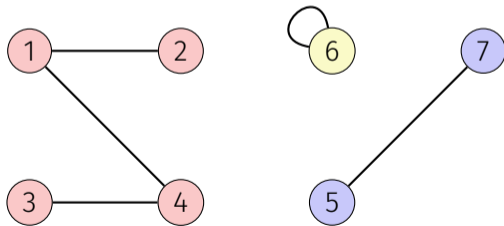
Invariant (k): all paths via nodes with maximal index $< k$ considered.

- **Base case ($k = 1$):** All directed paths (all edges) in A_G considered.
- **Hypothesis:** invariant (k) fulfilled.
- **Step ($k \rightarrow k + 1$):** For each path from v_i to v_j via nodes with maximal index k : by the hypothesis $b_{ik} = 1$ and $b_{kj} = 1$. Therefore in the k -th iteration: $b_{ij} \leftarrow 1$.



Connected Components

Connected components of an undirected graph G : equivalence classes of the reflexive, transitive closure of G . Connected component = subgraph $G' = (V', E')$, $E' = \{\{v, w\} \in E \mid v, w \in V'\}$ with $\{\{v, w\} \in E \mid v \in V' \vee w \in V'\} = E = \{\{v, w\} \in E \mid v \in V' \wedge w \in V'\}$



Graph with connected components $\{1, 2, 3, 4\}$, $\{5, 7\}$, $\{6\}$.

Computation of the Connected Components

- Computation of a partitioning of V into pairwise disjoint subsets V_1, \dots, V_k
- such that each V_i contains the nodes of a connected component.
- Algorithm: depth-first search or breadth-first search. Upon each new start of $\text{DFSSearch}(G, v)$ or $\text{BFSSearch}(G, v)$ a new empty connected component is created and all nodes being traversed are added.