# **Datenstrukturen und Algorithmen**

**Exercise 6** 

FS 2020

# **Program of today**

1 Feedback of last exercise

- 2 Repetition theory
  - Binary Trees
- **3** Repetition Theory
  - AVL Condition
  - AVL Insert
  - Quadtrees

• 
$$h'(k) = \lceil \ln(k+1) \rceil \mod q$$

• 
$$h'(k) = \lceil \ln(k+1) \rceil \mod q \rightarrow \text{not suitable:} \ (k=0) \mapsto 0$$

• 
$$h'(k) = \lceil \ln(k+1) \rceil \mod q \rightarrow \text{not suitable:} \ (k=0) \mapsto 0$$
  
•  $s(j,k) = k^j \mod p$ 

• 
$$h'(k) = \lceil \ln(k+1) \rceil \mod q \rightarrow \text{not suitable:} (k=0) \mapsto 0$$
  
•  $s(j,k) = k^j \mod p \rightarrow \text{not suitable:} (k=0) \mapsto 0, (k=1) \mapsto 1$ 

• 
$$h'(k) = \lceil \ln(k+1) \rceil \mod q \rightarrow \text{not suitable:} (k=0) \mapsto 0$$
  
•  $s(j,k) = k^j \mod p \rightarrow \text{not suitable:} (k=0) \mapsto 0, (k=1) \mapsto 1$   
•  $s(j,k) = ((k \cdot j) \mod q) + 1$ 

#### Coocoo hashing

Coocoo hashing

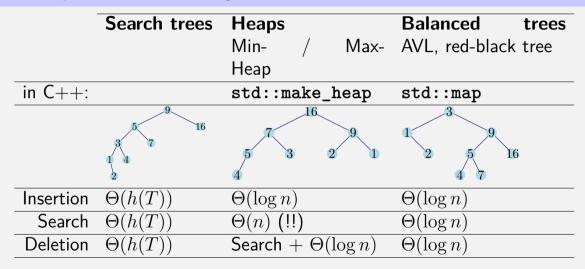
*h*<sub>1</sub>(*k*) = *k* mod 5, *h*<sub>2</sub>(*k*) = ⌊*k*/5⌋ mod 5
 add 7: infinite loop

```
Finding a Sub-Array
// calculating hash a, hash b, c to k
It1 window end = from;
for(It2 current = begin; current != end;
   ++current, ++window end) {
  if (window end == to) return to;
 hash b = (C * hash b \% M + *current) \% M;
 hash a = (C * hash a \% M + *window end) \% M;
 c to k = c to k * C % M:
}
```

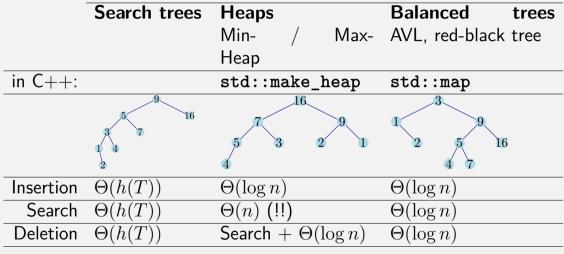
```
Finding a Sub-Array
// looking for b and updating hash a
for(It1 window begin = from; ;
   ++window_begin, ++window_end) {
 if(hash a == hash b)
   if(std::equal(window_begin, window_end, begin, end))
     return window begin:
 if (window end == to) return to;
 hash_a = (C * hash_a % M + *window_end
          + (M - c to k) * *window_begin % M) % M;
ጉ
```

# 2. Repetition theory

# **Comparison of binary Trees**



# **Comparison of binary Trees**



**Recall:**  $\Theta(\log n) \le \Theta(h(T)) \le \Theta(n)$ 

#### **Binary Search Trees**

- Search for Key.
- Insert at the reached empty leaf (null).

- Insert at the very back of the Array.
- Restore Heap-Condition: siftUp (climb successively).

#### **Binary Search Trees**

- Search for Key.
- Insert at the reached empty leaf (null).

### MinHeap

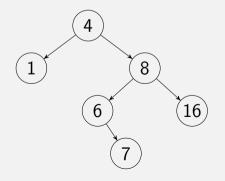
- Insert at the very back of the Array.
- Restore Heap-Condition: siftUp (climb successively).

#### **Exercise:** Insert 4, 8, 16, 1, 6, 7 into empty Tree/Heap.

#### **Binary Search Trees**

- Search for Key.
- Insert at the reached empty leaf (null).

- Insert at the very back of the Array.
- Restore Heap-Condition: siftUp (climb successively).



16

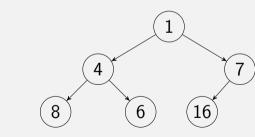
### **Binary Search Trees**

- Search for Key.
- Insert at the reached empty leaf (null).

4

8

- Insert at the very back of the Array.
- Restore Heap-Condition: siftUp (climb successively).





### **Binary Search Trees**

- Replace key k by symmetric successor n.
- Careful: What about right child of n?

- Replace key by last element of the array.
- Restore Heap-Condition: siftDown or siftUp.

### **Binary Search Trees**

- Replace key k by symmetric successor n.
- Careful: What about right child of n?

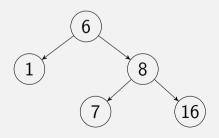
### MinHeap

- Replace key by last element of the array.
- Restore Heap-Condition: siftDown or siftUp.

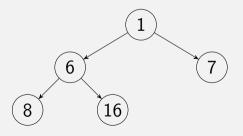
#### **Exercise:** Delete 4 from Example Tree/Heap.

### **Binary Search Trees**

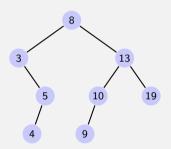
- Replace key k by symmetric successor n.
- Careful: What about right child of n?



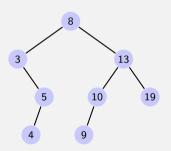
- Replace key by last element of the array.
- Restore Heap-Condition: siftDown or siftUp.



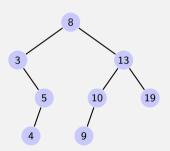
- **preorder**: v, then  $T_{\text{left}}(v)$ , then  $T_{\text{right}}(v)$ .
- postorder:  $T_{\text{left}}(v)$ , then  $T_{\text{right}}(v)$ , then v.
- inorder:  $T_{\text{left}}(v)$ , then v, then  $T_{\text{right}}(v)$ .



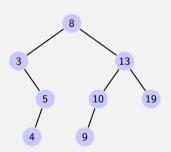
• inorder:  $T_{\text{left}}(v)$ , then v, then  $T_{\text{right}}(v)$ .



preorder: v, then T<sub>left</sub>(v), then T<sub>right</sub>(v).
8, 3, 5, 4, 13, 10, 9, 19
postorder: T<sub>left</sub>(v), then T<sub>right</sub>(v), then v.
4, 5, 3, 9, 10, 19, 13, 8
inorder: T<sub>left</sub>(v), then v, then T<sub>right</sub>(v).



preorder: v, then T<sub>left</sub>(v), then T<sub>right</sub>(v).
8, 3, 5, 4, 13, 10, 9, 19
postorder: T<sub>left</sub>(v), then T<sub>right</sub>(v), then v.
4, 5, 3, 9, 10, 19, 13, 8
inorder: T<sub>left</sub>(v), then v, then T<sub>right</sub>(v).
3, 4, 5, 8, 9, 10, 13, 19



Draw a binary search tree each that represents the following traversals. Is the tree unique?

inorder	12345678
preorder	43128657
postorder	13256874

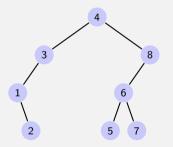
Provide for each order a sequence of numbers from  $\{1, \ldots, 4\}$  such that it cannot result from a valid binary search tree

inorder: any binary search tree with numbers  $\{1, \ldots, 8\}$  is valid. The tree is not unique There is no search tree for any non-sorted sequence. Counterexample

1243

### Answers

preorder 4 3 1 2 8 6 5 7

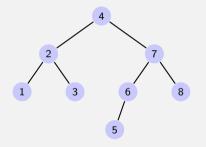


Tree is unique

It mus hold recursively that first there is a group of numbers with lower and then with higher number than the first value. Counterexample:  $3\ 1\ 4\ 2$ 

### Answers

postorder 1 3 2 5 6 8 7 4

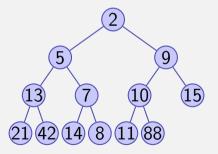


Tree is unique

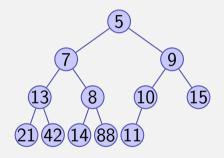
Construction here: https://www.techiedelight.com/ build-binary-search-tree-from-postorder-sequence/, similar argument as before, but backwards. Counterexample 4 2 1 3

### Неар

On the following Min-Heap, perform an extract-min operation, including re-establishing the heap-condition, as shown in class. What does the heap look like after the operation?

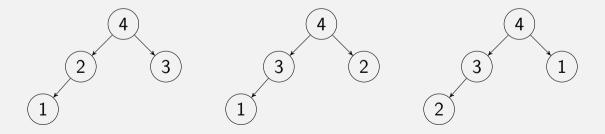


# **Solution**



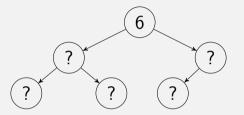
### Number of MaxHeaps on n distinct keys

Let N(n) denote the number of distinct Max-Heaps which can be built from all the keys 1, 2, ..., n. For example we have N(1) = 1, N(2) = 1, N(3) = 2, N(4) = 3 und N(5) = 8. Find the values N(6) and N(7).



# Number of MaxHeaps on n distinct keys

A MaxHeap containing the elements 1, 2, 3, 4, 5, 6 has the structure:

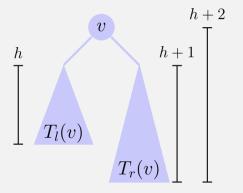


Number of combinations to choose elements for the left subtree:  $\binom{5}{3}$ .

$$\Rightarrow N(6) = {5 \choose 3} \cdot N(3) \cdot N(2) 10 \cdot 2 \cdot 1 = 20.$$
  
and  $N(7) = {6 \choose 3} \cdot N(3) \cdot N(3) = 20 \cdot 2 \cdot 2 = 80.$ 

# **AVL Condition**

# AVL Condition: for each node v of a tree $bal(v) \in \{-1, 0, 1\}$

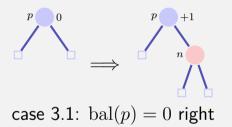


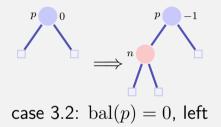
### **Balance at Insertion Point**



Finished in both cases because the subtree height did not change

#### **Balance at Insertion Point**





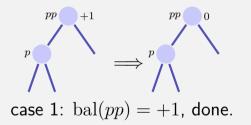
Not finished in both case. Call of upin(p)

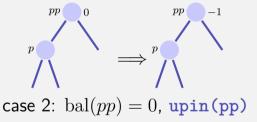
#### When upin(p) is called it holds that

■ the subtree from p is grown and
■ bal(p) ∈ {-1, +1}

# upin(p)

Assumption: p is left son of  $pp^1$ 



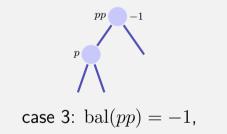


#### In both cases the AVL-Condition holds for the subtree from pp

 $<sup>^1\</sup>mathrm{lf}\ p$  is a right son: symmetric cases with exchange of +1 and -1

# upin(p)

Assumption: p is left son of pp

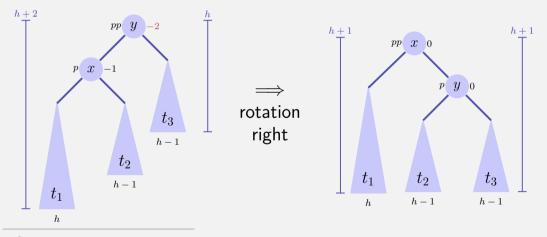


This case is problematic: adding n to the subtree from pp has violated the AVL-condition. Re-balance!

Two cases  $\operatorname{bal}(p) = -1$ ,  $\operatorname{bal}(p) = +1$ 

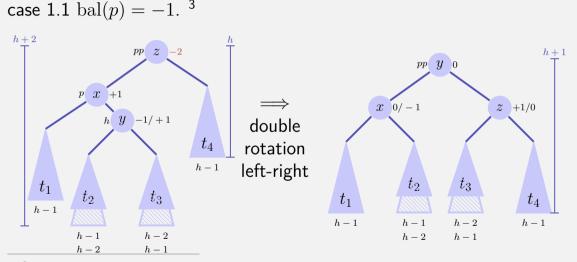
# **Rotations**

case 1.1 bal
$$(p) = -1$$
.<sup>2</sup>



<sup>2</sup>p right son:  $\Rightarrow$  bal(pp) = bal(p) = +1, left rotation

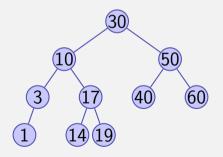
### **Rotations**



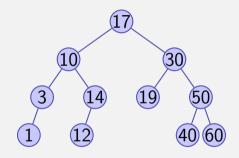
 ${}^{3}p$  right son  $\Rightarrow$  bal(pp) = +1, bal(p) = -1, double rotation right left



In the following AVL tree, insert key 12 and rebalance (as shown in class). What does the AVL tree look like after the operation that has been shown in class?



# Solution



# Minimization of a functional for signal segmentation

 $\begin{array}{ll} \mathcal{P} \mbox{ Partition } & \gamma \geq 0 \mbox{ regularization parameter} \\ f_{\mathcal{P}} \mbox{ approxmation } & z \mbox{ image} = \mbox{ 'data'} \end{array}$ 

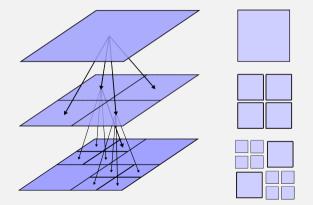
#### Goal: Efficient mimization of the functional

$$H_{\gamma,z}: \mathfrak{S} \to \mathbb{R}, \quad (\mathcal{P}, f_{\mathcal{P}}) \mapsto \gamma \cdot |\mathcal{P}| + ||z - f_{\mathcal{P}}||_2^2.$$

Result  $(\hat{\mathcal{P}}, \hat{f}_{\hat{\mathcal{P}}}) \in \operatorname{argmin}_{(\mathcal{P}, f_{\mathcal{P}})} H_{\gamma, z}$  can be interpreted as *optimal* compromise between regularity and fidelity to data.

## **Minimization of a Functional using Quadtrees**

Separation of a two-dimensional range into 4 equally seized parts.

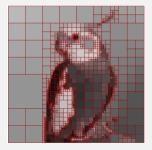


# Algorithmus: Minimize(z,r, $\gamma$ )

**Input:** Image data  $z \in \mathbb{R}^S$ , rectangle  $r \subset S$ , regularization  $\gamma > 0$ **Output:**  $\min_T \gamma |L(T)| + ||z - \mu_{L(T)}||_2^2$ if |r| = 0 then return 0  $m \leftarrow \gamma + \sum_{s \in r} \left( z_s - \mu_r \right)^2$ if |r| > 1 then Split r into  $r_{11}, r_{1r}, r_{ul}, r_{ur}$  $m_1 \leftarrow \text{Minimize}(z, r_{ll}, \gamma); m_2 \leftarrow \text{Minimize}(z, r_{lr}, \gamma)$  $m_3 \leftarrow \text{Minimize}(z, r_{ul}, \gamma); m_4 \leftarrow \text{Minimize}(z, r_{ur}, \gamma)$  $m' \leftarrow m_1 + m_2 + m_3 + m_4$ else  $m' \leftarrow \infty$ if m' < m then  $m \leftarrow m'$ return m

## **Minimization of a Functional using Quadtrees**





# Questions?