

# Datenstrukturen und Algorithmen

## Exercise 11

FS 2020

# Program of today

- 1 Feedback of last exercise
- 2 Repetition theory
- 3 MaxFlow
- 4 Two Quizzes

# **1. Feedback of last exercise**

# Closeness Centrality

- Given: an adjacency matrix for an *undirected* graph on  $n$  vertices.
- Output: the *closeness centrality*  $C(v)$  of every vertex  $v$ .

$$C(v) = \sum_{u \in V \setminus \{v\}} d(v, u)$$

- Intuition: If many connected vertices are close to  $v$ , then  $C(v)$  is small.
- “How central is the vertex in its connected component?”

# All Pairs Shortest Paths

```
template<typename Matrix>
void allPairsShortestPaths(unsigned n, Matrix& m){
    for(unsigned k = 0; k < n; ++k) {
        for(unsigned i = 0; i < n; ++i) {
            for(unsigned j = i + 1; j < n; ++j) {
                if(k == i || k == j)
                    continue;
                if(m[i][k] == 0 || m[k][j] == 0)
                    continue; // no connection via k
                if(m[i][j] == 0 || m[i][k] + m[k][j] < m[i][j])
                    m[i][j] = m[j][i] = m[i][k] + m[k][j];
            }
        }
    }
}
```

# Closeness Centrality

```
vector<vector<unsigned> > adjacencies(n,vector<unsigned>(n, 0));
vector<string> names(n);
// ...
allPairsShortestPaths(n, adjacencies);
for(unsigned i = 0; i < n; ++i) {
    cout << names[i] << ": "; unsigned centrality = 0;
    for(unsigned j = 0; j < n; ++j) {
        if(j == i) continue;
        centrality += adjacencies[i][j];
    }
    cout << centrality << endl;
}
```

# Exercise Union-Find

```
class UnionFind{
    std::vector<size_t> parents_;
public:
    UnionFind(size_t size) : parents_(size, size) { };

    size_t find(size_t index){
        while(parents_[index] != parents_.size())
            index = parents_[index];
        return index;
    }

    void unite(size_t a, size_t b){
        parents_[find(a)] = b;
    }
};
```

# Exercise Kruskal

```
class Edge{
public:
    size_t u_, v_;
    int c_;
    Edge(size_t u, int v, int c) : u_(u), v_(v), c_(c) {}

    bool operator<(const Edge& other) const {
        return c_ < other.c_;
    }
};
```



# Exercise Kruskal

```
std::vector<Edge> edges;
```

```
...
```

```
UnionFind uf(n_ + 1);  
sort(edges.begin(), edges.end());  
for(auto e : edges){  
    size_t i=uf.find(e.u_);  
    size_t j=uf.find(e.v_);  
    if(i != j){  
        out.addEdge(e);  
        uf.unite(i, j);  
    }  
}
```

## **2. Repetition theory**

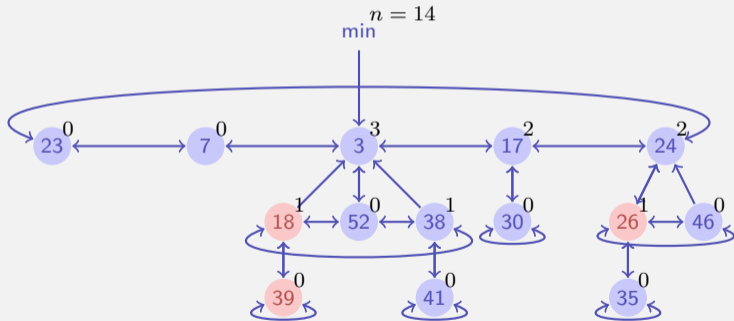
# Fibonacci Heaps

Data structure for elements with key with operations

- **MakeHeap()**: Return new heap without elements
- **Insert( $H, x$ )**: Add  $x$  to  $H$
- **Minimum( $H$ )**: return a pointer to element  $m$  with minimal key
- **ExtractMin( $H$ )**: return and remove (from  $H$ ) pointer to the element  $m$
- **Union( $H_1, H_2$ )**: return a heap merged from  $H_1$  and  $H_2$
- **DecreaseKey( $H, x, k$ )**: decrease the key of  $x$  in  $H$  to  $k$
- **Delete ( $H, x$ )**: remove element  $x$  from  $H$

# Implementation

Doubly linked lists of nodes with a marked-flag and number of children. Pointer to minimal Element and number nodes.



# Simple Operations

- MakeHeap (trivial)
- Minimum (trivial)
- Insert( $H, e$ )
  - 1 Insert new element into root-list
  - 2 If key is smaller than minimum, reset min-pointer.
- Union ( $H_1, H_2$ )
  - 1 Concatenate root-lists of  $H_1$  and  $H_2$
  - 2 Reset min-pointer.
- Delete( $H, e$ )
  - 1 DecreaseKey( $H, e, -\infty$ )
  - 2 ExtractMin( $H$ )

# ExtractMin

- 1 Remove minimal node  $m$  from the root list
- 2 Insert children of  $m$  into the root list
- 3 Merge heap-ordered trees with the same degrees until all trees have a different degree:  
Array of degrees  $a[1, \dots, n]$  of elements, empty at beginning. For each element  $e$  of the root list:
  - a Let  $g$  be the degree of  $e$
  - b If  $a[g] = nil$ :  $a[g] \leftarrow e$ .
  - c If  $e' := a[g] \neq nil$ : Merge  $e$  with  $e'$  resulting in  $e''$  and set  $a[g] \leftarrow nil$ . Set  $e''$  unmarked. Re-iterate with  $e \leftarrow e''$  having degree  $g + 1$ .

# DecreaseKey ( $H, e, k$ )

- 1 Remove  $e$  from its parent node  $p$  (if existing) and decrease the degree of  $p$  by one.
- 2 Insert( $H, e$ )
- 3 Avoid too thin trees:
  - a If  $p = nil$  then done.
  - b If  $p$  is unmarked: mark  $p$  and done.
  - c If  $p$  marked: unmark  $p$  and cut  $p$  from its parent  $pp$ . Insert ( $H, p$ ). Iterate with  $p \leftarrow pp$ .

# Runtimes

	Binary Heap (worst-Case)	Fibonacci Heap (amortized)
MakeHeap	$\Theta(1)$	$\Theta(1)$
Insert	$\Theta(\log n)$	$\Theta(1)$
Minimum	$\Theta(1)$	$\Theta(1)$
ExtractMin	$\Theta(\log n)$	$\Theta(\log n)$
Union	$\Theta(n)$	$\Theta(1)$
DecreaseKey	$\Theta(\log n)$	$\Theta(1)$
Delete	$\Theta(\log n)$	$\Theta(\log n)$



# 3. MaxFlow

# Flow

A *Flow*  $f : V \times V \rightarrow \mathbb{R}$  fulfills the following conditions:

- *Bounded Capacity:*

For all  $u, v \in V$ :  $f(u, v) \leq c(u, v)$ .

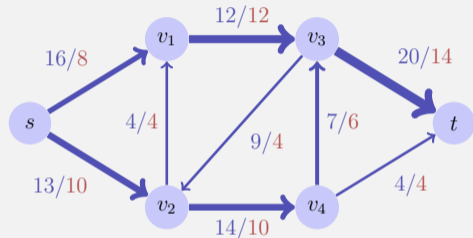
- *Skew Symmetry:*

For all  $u, v \in V$ :  $f(u, v) = -f(v, u)$ .

- *Conservation of flow:*

For all  $u \in V \setminus \{s, t\}$ :

$$\sum_{v \in V} f(u, v) = 0.$$



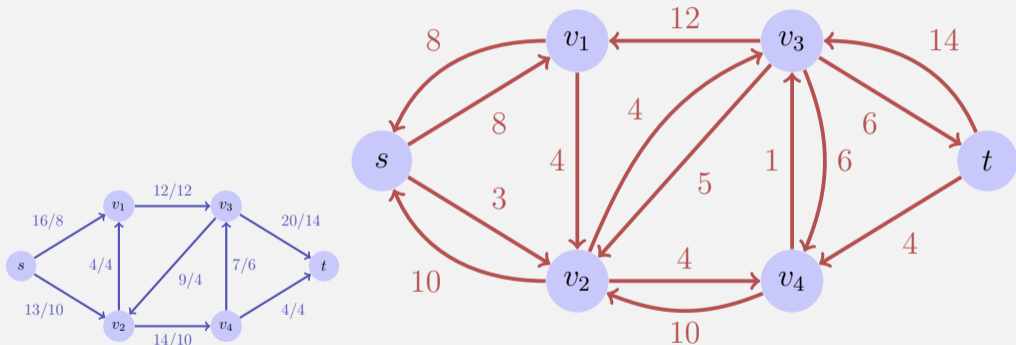
*Value* of the flow:

$$|f| = \sum_{v \in V} f(s, v).$$

Here  $|f| = 18$ .

# Rest Network

*Rest network*  $G_f$  provided by the edges with positive rest capacity:



Rest networks provide the same kind of properties as flow networks with the exception of permitting antiparallel edges

# Augmenting Paths

*expansion path*  $p$ : simple path from  $s$  to  $t$  in the rest network  $G_f$ .

*Rest capacity*  $c_f(p) = \min\{c_f(u, v) : (u, v) \text{ edge in } p\}$

# Max-Flow Min-Cut Theorem

## Theorem

Let  $f$  be a flow in a flow network  $G = (V, E, c)$  with source  $s$  and sink  $t$ . The following statements are equivalent:

- 1  $f$  is a maximal flow in  $G$
- 2 The rest network  $G_f$  does not provide any expansion paths
- 3 It holds that  $|f| = c(S, T)$  for a cut  $(S, T)$  of  $G$ .

# Algorithm Ford-Fulkerson( $G, s, t$ )

**Input:** Flow network  $G = (V, E, c)$

**Output:** Maximal flow  $f$ .

**for**  $(u, v) \in E$  **do**

$f(u, v) \leftarrow 0$

**while** Exists path  $p : s \rightsquigarrow t$  in rest network  $G_f$  **do**

$c_f(p) \leftarrow \min\{c_f(u, v) : (u, v) \in p\}$

**foreach**  $(u, v) \in p$  **do**

**if**  $(u, v) \in E$  **then**

$f(u, v) \leftarrow f(u, v) + c_f(p)$

**else**

$f(v, u) \leftarrow f(v, u) + c_f(p)$

# Edmonds-Karp Algorithm

Choose in the Ford-Fulkerson-Method for finding a path in  $G_f$  the expansion path of shortest possible length (e.g. with BFS)

## Theorem

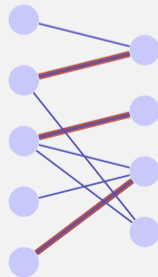
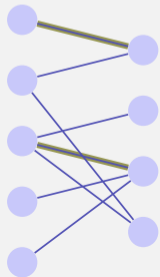
*When the Edmonds-Karp algorithm is applied to some integer valued flow network  $G = (V, E)$  with source  $s$  and sink  $t$  then the number of flow increases applied by the algorithm is in  $\mathcal{O}(|V| \cdot |E|)$   
 $\Rightarrow$  Overall asymptotic runtime:  $\mathcal{O}(|V| \cdot |E|^2)$*

# Application: maximal bipartite matching

Given: bipartite undirected graph  $G = (V, E)$ .

**Matching**  $M$ :  $M \subseteq E$  such that  $|\{m \in M : v \in m\}| \leq 1$  for all  $v \in V$ .

**Maximal Matching**  $M$ : Matching  $M$ , such that  $|M| \geq |M'|$  for each matching  $M'$ .

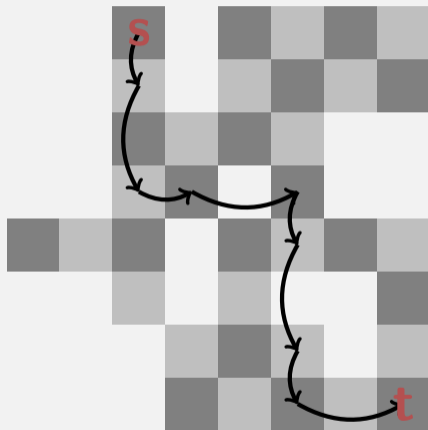
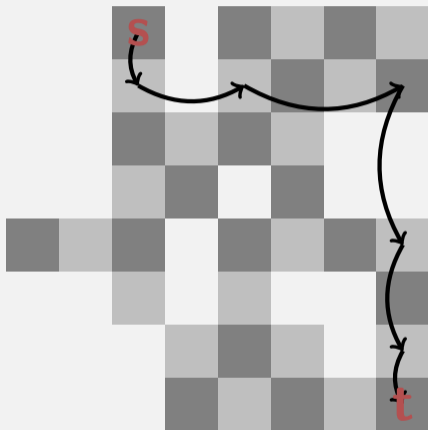




## 4. Two Quizzes

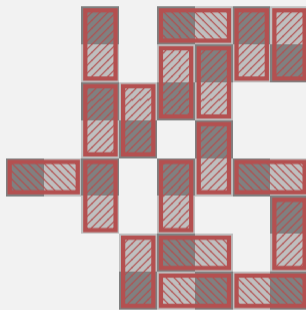
[Exam 2018.01], Tasks 4 and 5

# Shortest Path Question



Most important question: What is the corresponding state space?

# Max Flow Question



Most important question: How to map this to a max-flow (matching) setup?

Questions?