

# 7. Sorting I

Simple Sorting

## 7.1 Simple Sorting

Selection Sort, Insertion Sort, Bubblesort [Ottman/Widmayer, Kap. 2.1, Cormen et al, Kap. 2.1, 2.2, Exercise 2.2-2, Problem 2-2

# Problem

**Input:** An array  $A = (A[1], \dots, A[n])$  with length  $n$ .

**Output:** a permutation  $A'$  of  $A$ , that is sorted:  $A'[i] \leq A'[j]$  for all  $1 \leq i \leq j \leq n$ .

# Algorithm: IsSorted( $A$ )

**Input:** Array  $A = (A[1], \dots, A[n])$  with length  $n$ .

**Output:** Boolean decision “sorted” or “not sorted”

**for**  $i \leftarrow 1$  **to**  $n - 1$  **do**

**if**  $A[i] > A[i + 1]$  **then**  
        **return** “not sorted”;

**return** “sorted”;

# Observation

IsSorted( $A$ ): “not sorted”, if  $A[i] > A[i + 1]$  for any  $i$ .

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⇒ idea:

```
for  $j \leftarrow 1$  to  $n - 1$  do
  if  $A[j] > A[j + 1]$  then
    swap( $A[j], A[j + 1]$ );
```

# Give it a try

5  $\longleftrightarrow$  6 2 8 4 1 ( $j = 1$ )



# Give it a try

**5** ↔ **6**   2   8   4   1   ( $j = 1$ )

5   **6** ↔ **2**   8   4   1   ( $j = 2$ )

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5   2   **6** ↔ **8**   4   1   ( $j = 3$ )

# Give it a try

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5   2   6 ↔ 8   4   1   ( $j = 3$ )

5   2   6   8 ↔ 4   1   ( $j = 4$ )

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5   2   6 ↔ 8   4   1   ( $j = 3$ )

5   2   6   8 ↔ 4   1   ( $j = 4$ )

5   2   6   4   8 ↔ 1   ( $j = 5$ )

# Give it a try

5 ↔ 6   2   8   4   1   ( $j = 1$ )

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5   2   6 ↔ 8   4   1   ( $j = 3$ )

5   2   6   8 ↔ 4   1   ( $j = 4$ )

5   2   6   4   8 ↔ 1   ( $j = 5$ )

5   2   6   4   1   8

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5   2   6   8 ↔ 4   1   ( $j = 4$ )

5   2   6   4   8 ↔ 1   ( $j = 5$ )

5   2   6   4   1   8

■ Not sorted! 😞.

# Give it a try

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5   2   6   8 ↔ 4   1   ( $j = 4$ )

5   2   6   4   8 ↔ 1   ( $j = 5$ )

5   2   6   4   1   8

- Not sorted! 😞.
- But the greatest element moves to the right  
⇒ new idea! 😊



# Try it out

5	6	2	8	4	1	$(j = 1, i = 1)$
5	6	2	8	4	1	$(j = 2)$
5	2	6	8	4	1	$(j = 3)$
5	2	6	8	4	1	$(j = 4)$
5	2	6	4	8	1	$(j = 5)$

- Apply the procedure iteratively.

# Try it out

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5	2	6	8	4	1	$(j = 3)$
5	2	6	8	4	1	$(j = 4)$
5	2	6	4	8	1	$(j = 5)$
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- Apply the procedure iteratively.
- For  $A[1, \dots, n]$ ,

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5	2	6	8	4	1	$(j = 4)$
5	2	6	4	8	1	$(j = 5)$
5	2	6	4	1	8	$(j = 1, i = 2)$
2	5	6	4	1	8	$(j = 2)$

- Apply the procedure iteratively.
- For  $A[1, \dots, n]$ ,  
then  $A[1, \dots, n - 1]$ ,

# Try it out

5	6	2	8	4	1	$(j = 1, i = 1)$
5	6	2	8	4	1	$(j = 2)$
5	2	6	8	4	1	$(j = 3)$
5	2	6	8	4	1	$(j = 4)$
5	2	6	4	8	1	$(j = 5)$
5	2	6	4	1	8	$(j = 1, i = 2)$
2	5	6	4	1	8	$(j = 2)$
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- Apply the procedure iteratively.
- For  $A[1, \dots, n]$ , then  $A[1, \dots, n - 1]$ ,

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- Apply the procedure iteratively.
- For  $A[1, \dots, n]$ ,  
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then  $A[1, \dots, n - 2]$ ,

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2	4	1	5	6	8	$(j = 1, i = 4)$

- Apply the procedure iteratively.
- For  $A[1, \dots, n]$ ,  
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2	4	5	1	6	8	$(j = 3)$
2	4	1	5	6	8	$(j = 1, i = 4)$
2	4	1	5	6	8	$(j = 2)$
2	1	4	5	6	8	$(i = 1, j = 5)$
1	2	4	5	6	8	

- Apply the procedure iteratively.
- For  $A[1, \dots, n]$ ,  
then  $A[1, \dots, n - 1]$ ,  
then  $A[1, \dots, n - 2]$ ,  
etc.



# Algorithm: Bubblesort

**Input:** Array  $A = (A[1], \dots, A[n])$ ,  $n \geq 0$ .

**Output:** Sorted Array  $A$

```
for  $i \leftarrow 1$  to  $n - 1$  do  
  for  $j \leftarrow 1$  to  $n - i$  do  
    if  $A[j] > A[j + 1]$  then  
      swap( $A[j]$ ,  $A[j + 1]$ );
```

# Analysis

Number key comparisons  $\sum_{i=1}^{n-1} (n - i) = \frac{n(n-1)}{2} = \Theta(n^2)$ .

Number swaps in the worst case:  $\Theta(n^2)$

② What is the worst case?

# Analysis

Number key comparisons  $\sum_{i=1}^{n-1} (n - i) = \frac{n(n-1)}{2} = \Theta(n^2)$ .

Number swaps in the worst case:  $\Theta(n^2)$

❓ What is the worst case?

❗ If  $A$  is sorted in decreasing order.

# Selection Sort

5 6 2 8 4 1 ( $i = 1$ )  
↑

- Selection of the smallest element by search in the unsorted part  $A[i..n]$  of the array.

# Selection Sort

5 6 2 8 4 1 ( $i = 1$ )  
↑

- Selection of the smallest element by search in the unsorted part  $A[i..n]$  of the array.
- Swap the smallest element with the first element of the unsorted part.

# Selection Sort



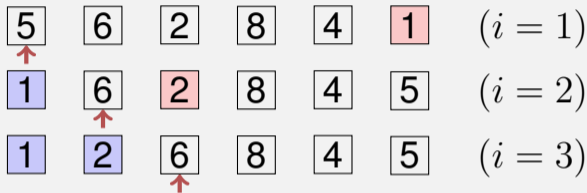
- Selection of the smallest element by search in the unsorted part  $A[i..n]$  of the array.
- Swap the smallest element with the first element of the unsorted part.
- Unsorted part decreases in size by one element ( $i \rightarrow i + 1$ ). Repeat until all is sorted. ( $i = n$ )

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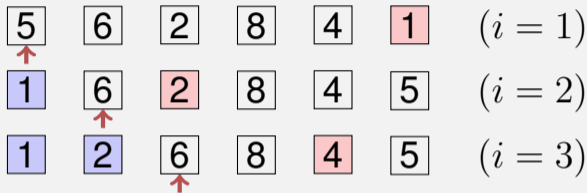
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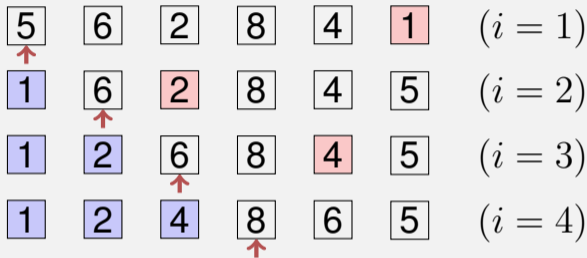


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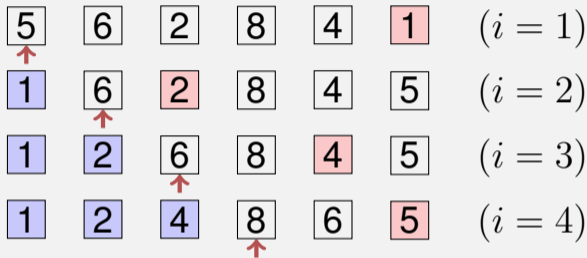
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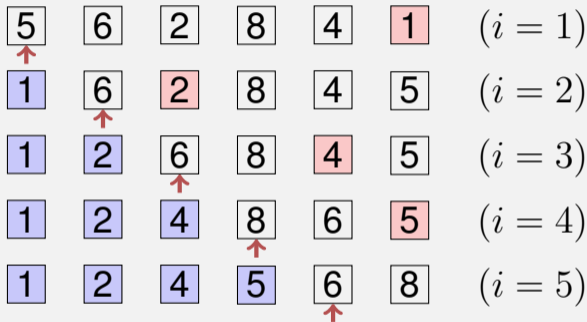
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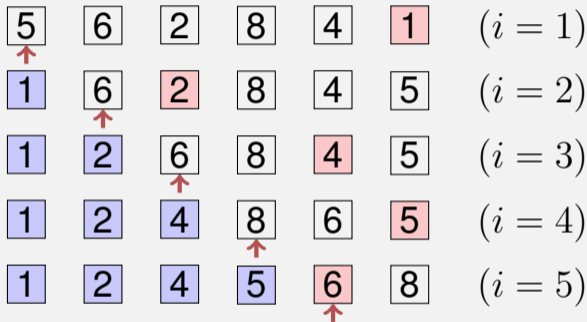
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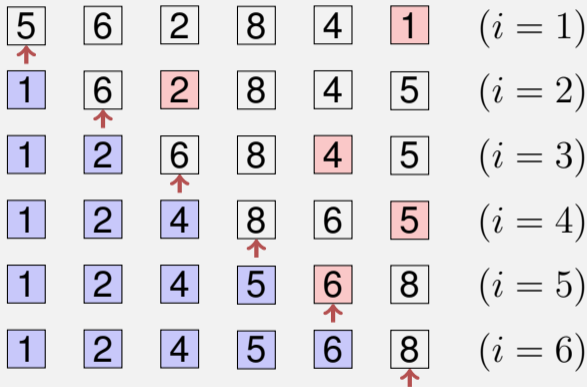
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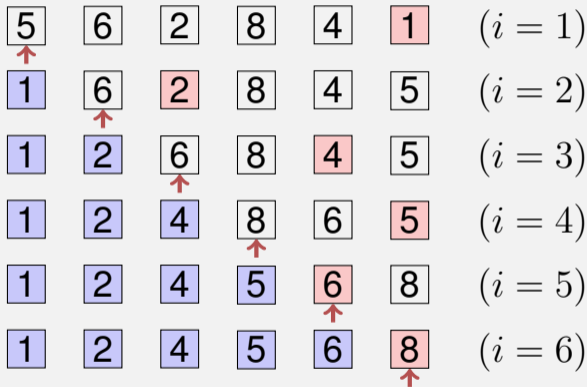
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# Algorithm: Selection Sort

**Input:** Array  $A = (A[1], \dots, A[n])$ ,  $n \geq 0$ .

**Output:** Sorted Array  $A$

```
for  $i \leftarrow 1$  to  $n - 1$  do  
     $p \leftarrow i$   
    for  $j \leftarrow i + 1$  to  $n$  do  
        if  $A[j] < A[p]$  then  
             $p \leftarrow j$ ;  
    swap( $A[i], A[p]$ )
```

# Analysis

Number comparisons in worst case:

# Analysis

Number comparisons in worst case:  $\Theta(n^2)$ .

Number swaps in the worst case:

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Number comparisons in worst case:  $\Theta(n^2)$ .

Number swaps in the worst case:  $n - 1 = \Theta(n)$

# Insertion Sort

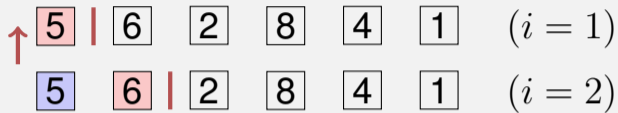
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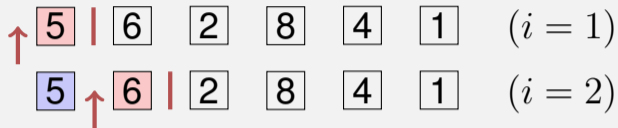
- Iterative procedure:  
 $i = 1 \dots n$

# Insertion Sort



- Iterative procedure:  
 $i = 1 \dots n$
- Determine insertion position for element  $i$ .

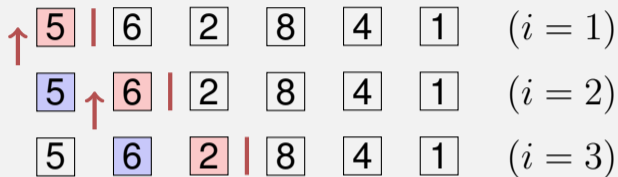
# Insertion Sort



- Iterative procedure:  
 $i = 1 \dots n$
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# Insertion Sort



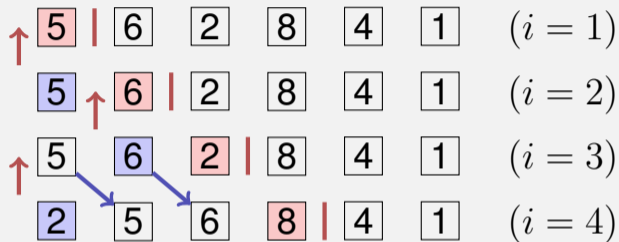
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# Insertion Sort



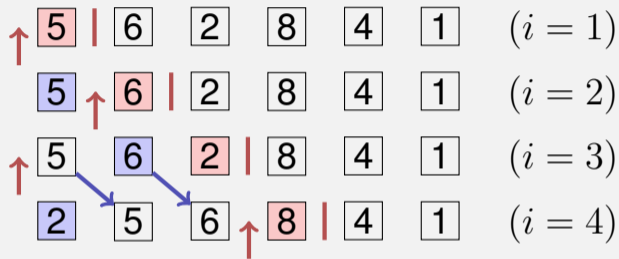
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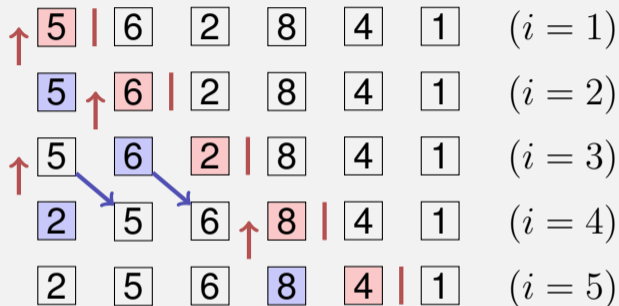
- Iterative procedure:  
 $i = 1 \dots n$
- Determine insertion position for element  $i$ .
- Insert element  $i$  array block movement potentially required

# Insertion Sort



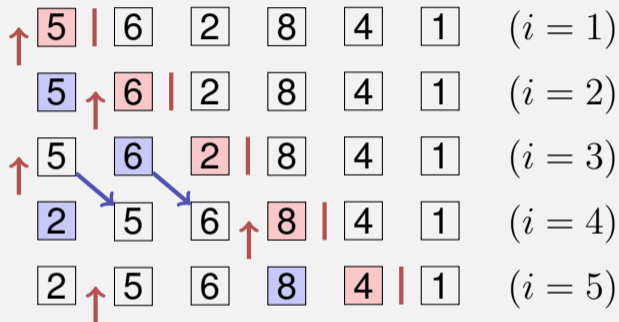
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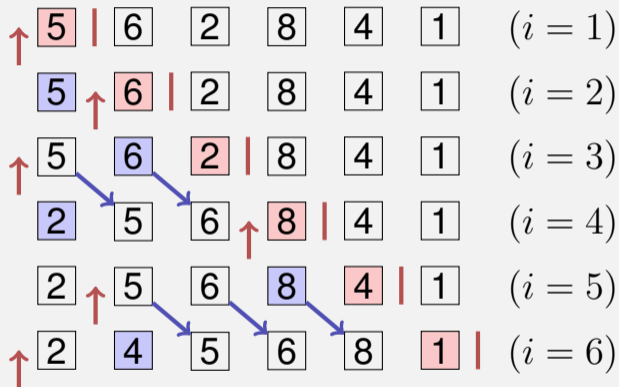
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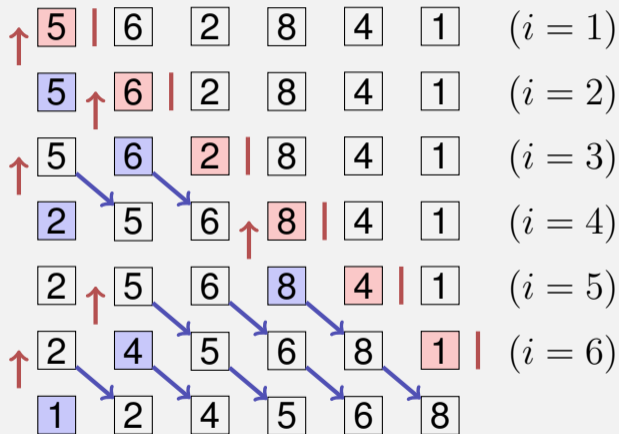
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② What is the disadvantage of this algorithm compared to sorting by selection?

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❗ Many element movements in the worst case.

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❗ Many element movements in the worst case.

❓ What is the advantage of this algorithm compared to selection sort?

❗ The search domain (insertion interval) is already sorted.  
Consequently: binary search possible.

# Algorithm: Insertion Sort

**Input:** Array  $A = (A[1], \dots, A[n])$ ,  $n \geq 0$ .

**Output:** Sorted Array  $A$

**for**  $i \leftarrow 2$  **to**  $n$  **do**

$x \leftarrow A[i]$

$p \leftarrow \text{BinarySearch}(A[1..i-1], x)$ ; // Smallest  $p \in [1, i]$  with  $A[p] \geq x$

**for**  $j \leftarrow i - 1$  **downto**  $p$  **do**

$A[j + 1] \leftarrow A[j]$

$A[p] \leftarrow x$

# Analysis

Number comparisons in the worst case:

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$$\sum_{k=1}^{n-1} a \cdot \log k = a \log((n-1)!) \in \mathcal{O}(n \log n).$$

Number swaps in the worst case

# Analysis

Number comparisons in the worst case:

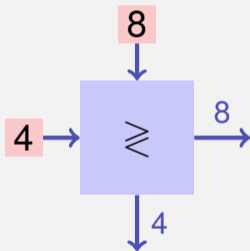
$$\sum_{k=1}^{n-1} a \cdot \log k = a \log((n-1)!) \in \mathcal{O}(n \log n).$$

Number swaps in the worst case  $\sum_{k=2}^n (k-1) \in \Theta(n^2)$



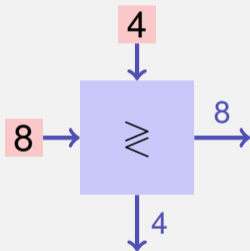
# Different point of view

Sorting node:



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# Different point of view

5

6



2



8



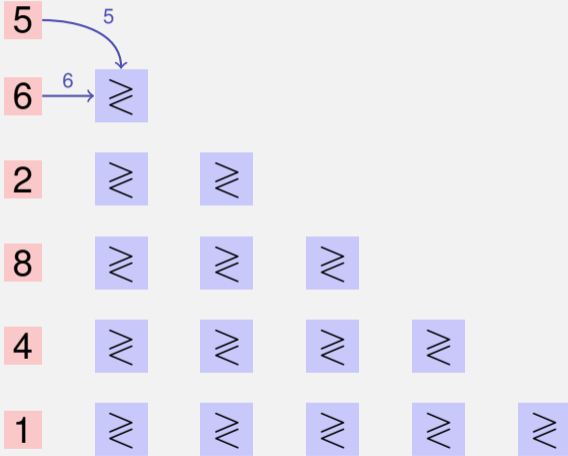
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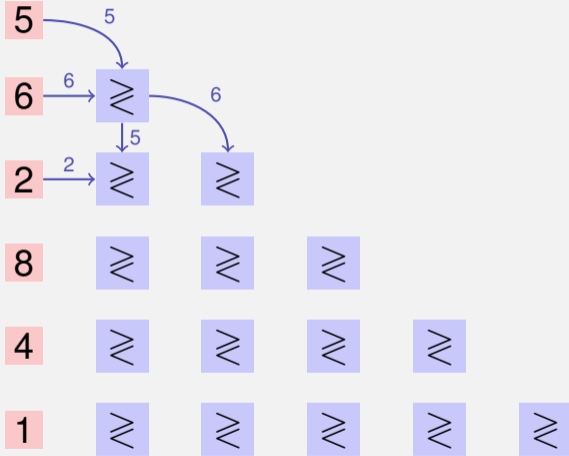
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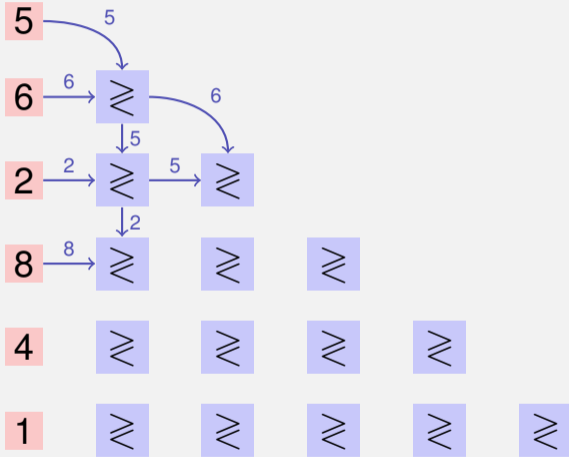
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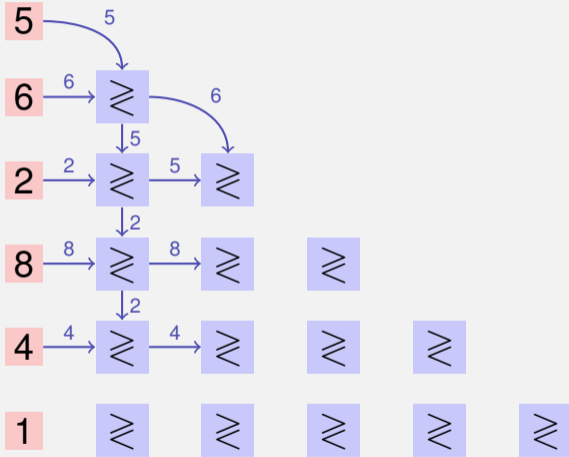
# Different point of view



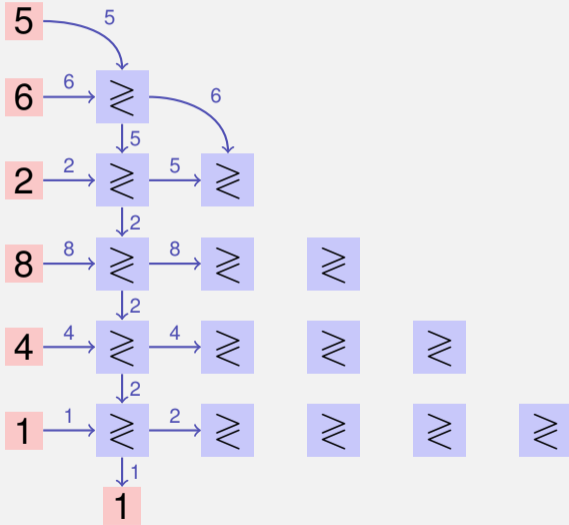
# Different point of view



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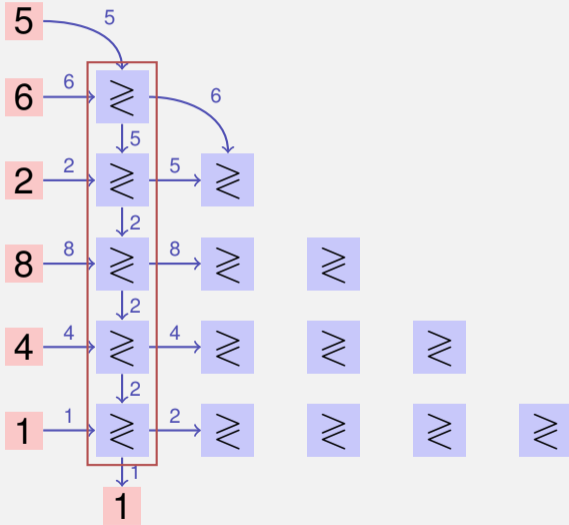


# Different point of view

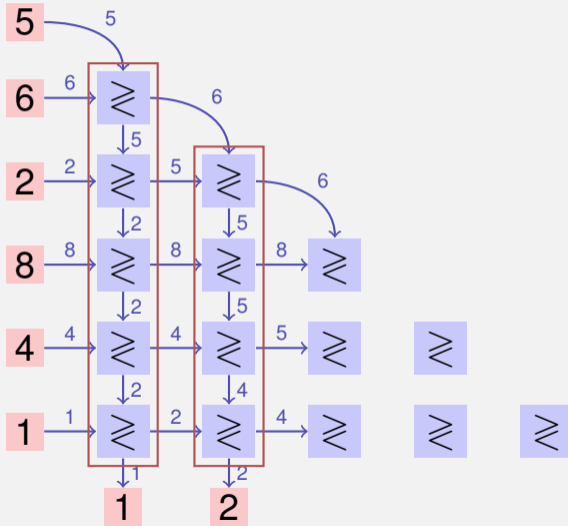




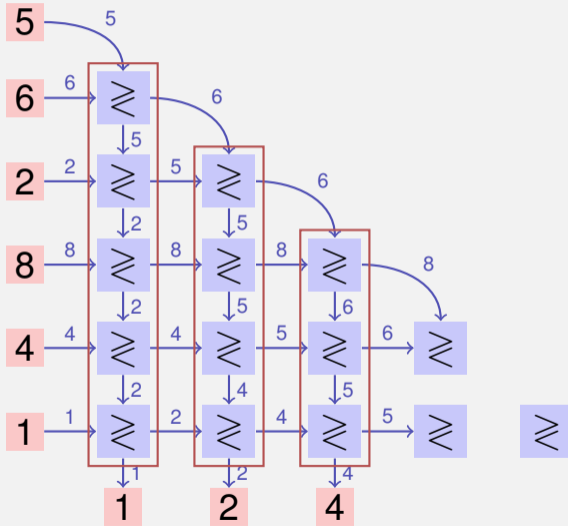
# Different point of view



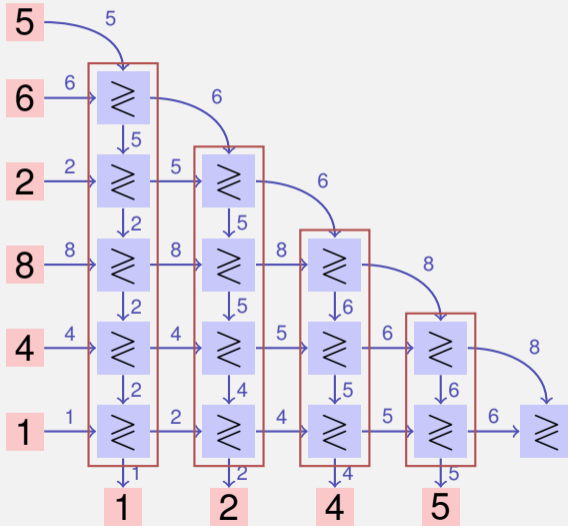
# Different point of view



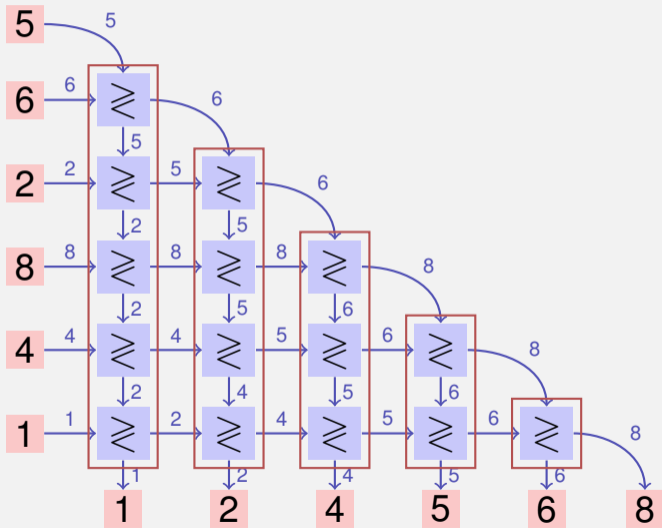
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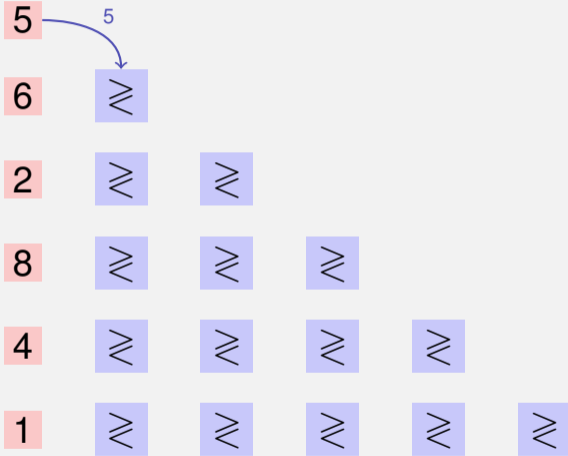


# Different point of view

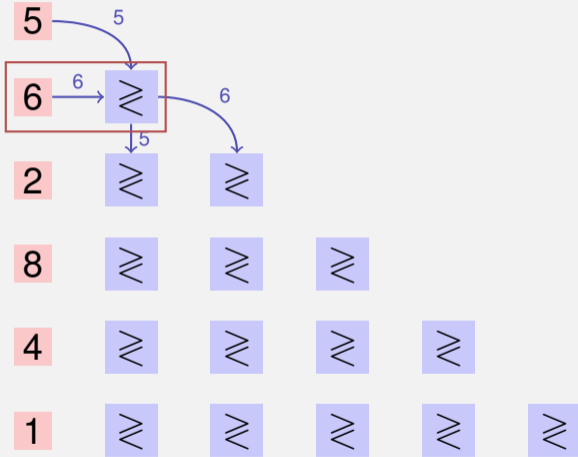


- Like selection sort [and like Bubblesort]

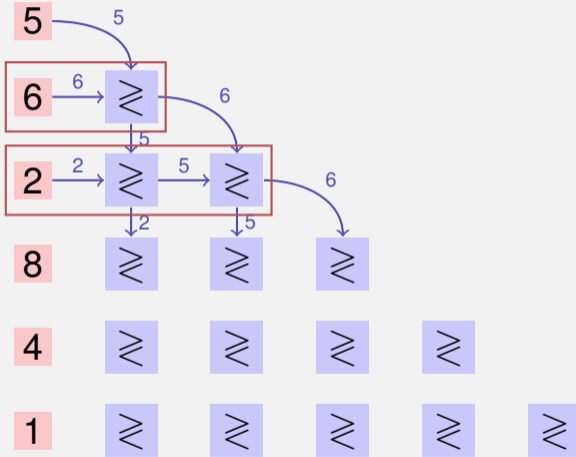
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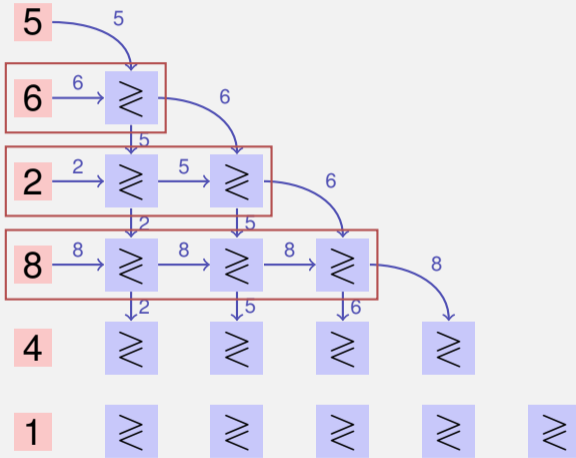


# Different point of view

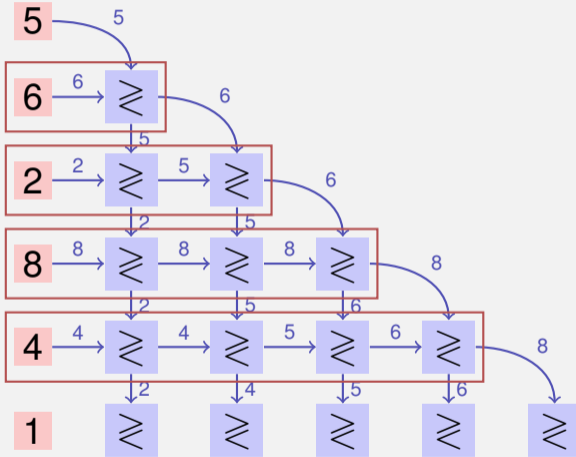




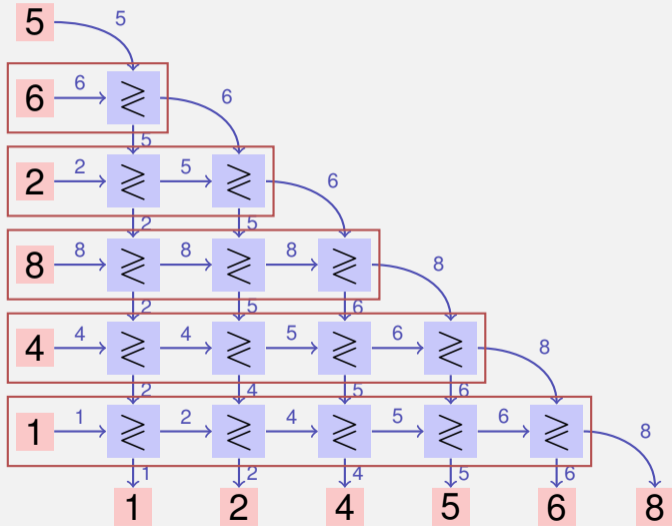
# Different point of view



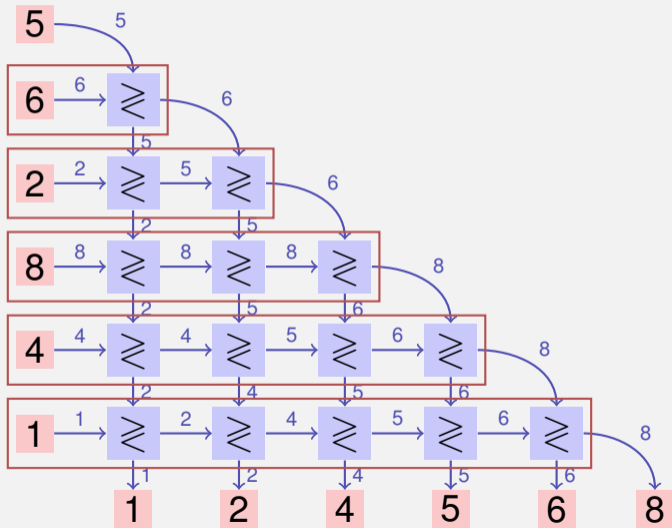
# Different point of view



# Different point of view



# Different point of view



■ Like insertion sort

# Conclusion

In a certain sense, Selection Sort, Bubble Sort and Insertion Sort provide the same kind of sort strategy. Will be made more precise.<sup>6</sup>

---

<sup>6</sup>In the part about parallel sorting networks. For the sequential code of course the observations as described above still hold.

# Shellsort (Donald Shell 1959)

Insertion sort on subsequences of the form  $(A_{k \cdot i})$  ( $i \in \mathbb{N}$ ) with decreasing distances  $k$ . Last considered distance must be  $k = 1$ .

Worst-case performance critically depends on the chosen subsequences

- Original concept with sequence  $1, 2, 4, 8, \dots, 2^k$ . Running time:  $\mathcal{O}(n^2)$
- Sequence  $1, 3, 7, 15, \dots, 2^{k-1}$  (Hibbard 1963).  $\mathcal{O}(n^{3/2})$
- Sequence  $1, 2, 3, 4, 6, 8, \dots, 2^p 3^q$  (Pratt 1971).  $\mathcal{O}(n \log^2 n)$

# Shellsort

9 8 7 6 5 4 3 2 1 0

# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$



# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$

1 0 7 6 5 4 3 2 9 8

# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$

1 0 7 6 5 4 3 2 9 8

1 0 3 6 5 4 7 2 9 8

# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$

1 0 7 6 5 4 3 2 9 8

1 0 3 6 5 4 7 2 9 8

1 0 3 2 5 4 7 6 9 8

# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$

1 0 7 6 5 4 3 2 9 8

1 0 3 6 5 4 7 2 9 8

1 0 3 2 5 4 7 6 9 8

1 0 3 2 5 4 7 6 9 8 insertion sort,  $k = 2$

# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$

1 0 7 6 5 4 3 2 9 8

1 0 3 6 5 4 7 2 9 8

1 0 3 2 5 4 7 6 9 8

1 0 3 2 5 4 7 6 9 8 insertion sort,  $k = 2$

1 0 3 2 5 4 7 6 9 8

# Shellsort

9 8 7 6 5 4 3 2 1 0

1 8 7 6 5 4 3 2 9 0 insertion sort,  $k = 4$

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1 0 3 6 5 4 7 2 9 8

1 0 3 2 5 4 7 6 9 8

1 0 3 2 5 4 7 6 9 8 insertion sort,  $k = 2$

1 0 3 2 5 4 7 6 9 8

0 1 2 3 4 5 6 7 8 9 insertion sort,  $k = 1$

# 8. Sorting II

Heapsort, Quicksort, Mergesort

# 8.1 Heapsort

[Ottman/Widmayer, Kap. 2.3, Cormen et al, Kap. 6]



# Heapsort

Inspiration from selectsort: fast insertion

Inspiration from insertion sort: fast determination of position

② Can we have the best of both worlds?

# Heapsort

Inspiration from selectsort: fast insertion

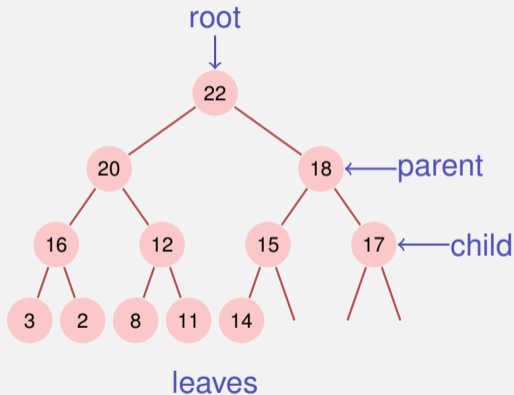
Inspiration from insertion sort: fast determination of position

② Can we have the best of both worlds?

① Yes, but it requires some more thinking...

# [Max-]Heap<sup>7</sup>

Binary tree with the following properties

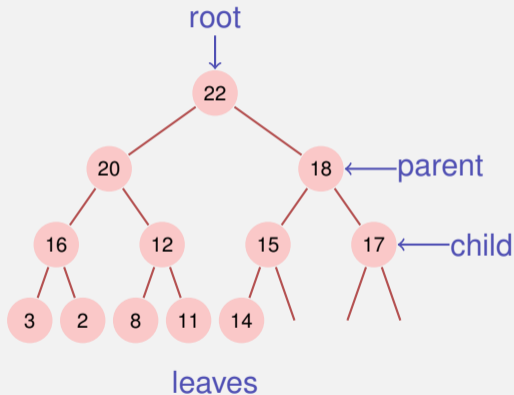


<sup>7</sup>Heap(data structure), not: as in “heap and stack” (memory allocation)

# [Max-]Heap<sup>7</sup>

Binary tree with the following properties

- 1 complete up to the lowest level

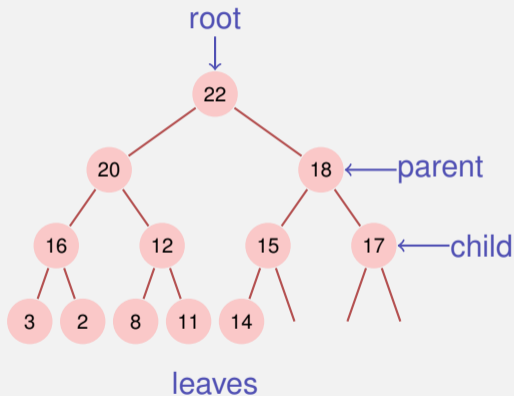


<sup>7</sup>Heap(data structure), not: as in “heap and stack” (memory allocation)

# [Max-]Heap<sup>7</sup>

Binary tree with the following properties

- 1 complete up to the lowest level
- 2 Gaps (if any) of the tree in the last level to the right

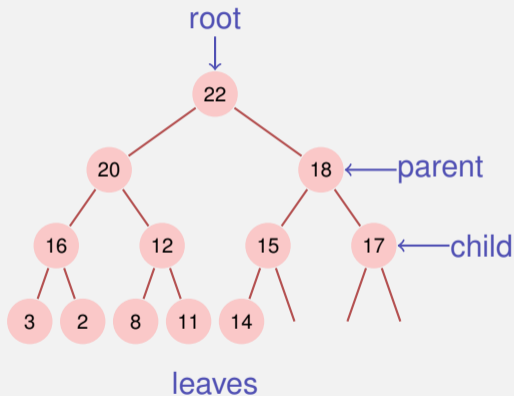


<sup>7</sup>Heap(data structure), not: as in “heap and stack” (memory allocation)

# [Max-]Heap<sup>7</sup>

Binary tree with the following properties

- 1 complete up to the lowest level
- 2 Gaps (if any) of the tree in the last level to the right
- 3 **Heap-Condition:**  
Max-(Min-)Heap: key of a child smaller (greater) than that of the parent node

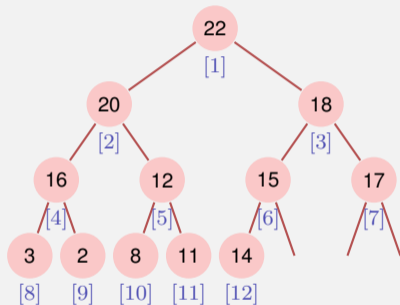
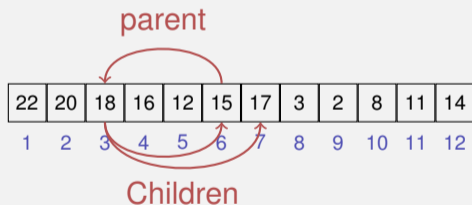


<sup>7</sup>Heap(data structure), not: as in “heap and stack” (memory allocation)

# Heap as Array

Tree  $\rightarrow$  Array:

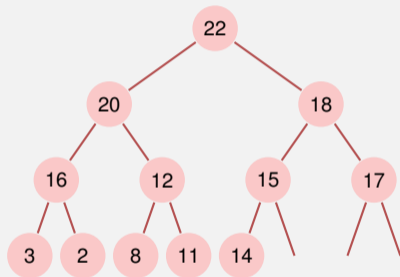
- $\text{children}(i) = \{2i, 2i + 1\}$
- $\text{parent}(i) = \lfloor i/2 \rfloor$



Depends on the starting index<sup>8</sup>

<sup>8</sup>For array that start at 0:  $\{2i, 2i + 1\} \rightarrow \{2i + 1, 2i + 2\}$ ,  $\lfloor i/2 \rfloor \rightarrow \lfloor (i - 1)/2 \rfloor$

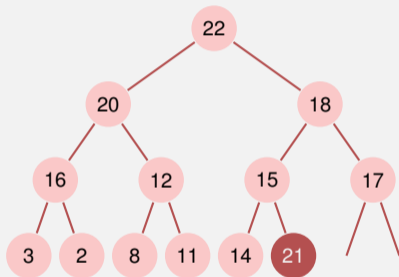
# Insert





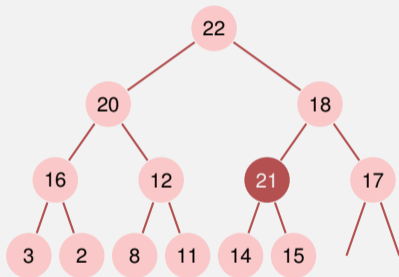
# Insert

- Insert new element at the first free position. Potentially violates the heap property.



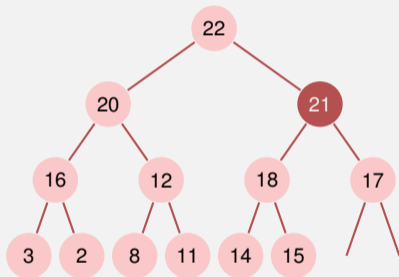
# Insert

- Insert new element at the first free position. Potentially violates the heap property.
- Reestablish heap property: climb successively



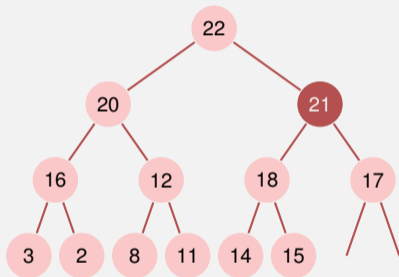
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# Insert

- Insert new element at the first free position. Potentially violates the heap property.
- Reestablish heap property: climb successively
- Worst case number of operations:  $\mathcal{O}(\log n)$



# Algorithm Sift-Up( $A, m$ )

**Input:** Array  $A$  with at least  $m + 1$  and Max-Heap-Structure on  $A[0, \dots, m - 1]$

**Output:** Array  $A$  with Max-Heap-Structure on  $A[0, \dots, m]$ .

$v \leftarrow A[m]$  // value

$c \leftarrow m$  // current position

$p \leftarrow \lfloor (c - 1) / 2 \rfloor$  // parent node

**while**  $c > 0$  and  $v > A[p]$  **do**

$A[c] \leftarrow A[p]$  // Value parent node  $\rightarrow$  current node

$c \leftarrow p$  // parent node  $\rightarrow$  current node

$p \leftarrow \lfloor (c - 1) / 2 \rfloor$

$A[c] \leftarrow v$  // value  $\rightarrow$  current node

# Height of a Heap

A complete binary tree with height<sup>9</sup>  $h$  provides

$$1 + 2 + 4 + 8 + \dots + 2^{h-1} = \sum_{i=0}^{h-1} 2^i = 2^h - 1$$

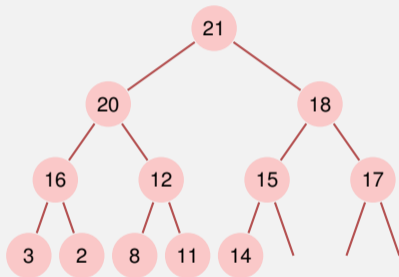
nodes. Thus for a heap with height  $h$ :

$$\begin{aligned} 2^{h-1} - 1 < n \leq 2^h - 1 \\ \Leftrightarrow 2^{h-1} < n + 1 \leq 2^h \end{aligned}$$

Particularly  $h(n) = \lceil \log_2(n + 1) \rceil$  and  $h(n) \in \Theta(\log n)$ .

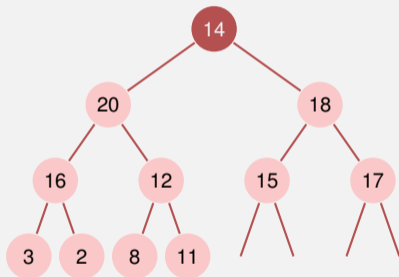
<sup>9</sup>here: number of edges from the root to a leaf

# Remove the maximum



# Remove the maximum

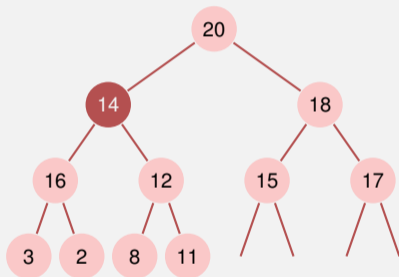
- Replace the maximum by the lower right element





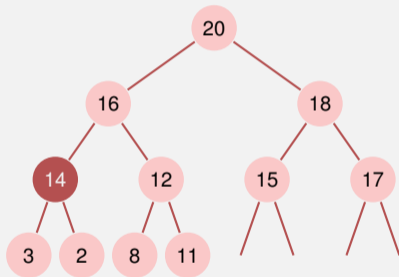
# Remove the maximum

- Replace the maximum by the lower right element
- Reestablish heap property: sink successively (in the direction of the greater child)



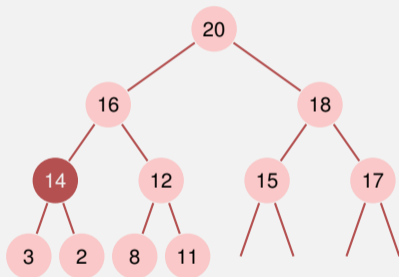
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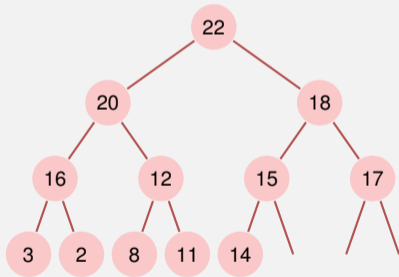
# Remove the maximum

- Replace the maximum by the lower right element
- Reestablish heap property: sink successively (in the direction of the greater child)
- Worst case number of operations:  $\mathcal{O}(\log n)$



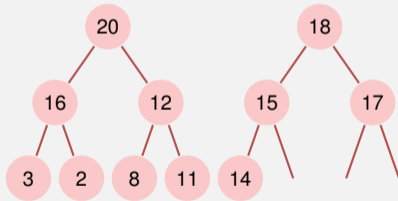
# Why this is correct: Recursive heap structure

A heap consists of two heaps:



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A heap consists of two heaps:



# Algorithm SiftDown( $A, i, m$ )

**Input:** Array  $A$  with heap structure for the children of  $i$ . Last element  $m$ .

**Output:** Array  $A$  with heap structure for  $i$  with last element  $m$ .

**while**  $2i \leq m$  **do**

$j \leftarrow 2i$ ; //  $j$  left child

**if**  $j < m$  and  $A[j] < A[j + 1]$  **then**

$j \leftarrow j + 1$ ; //  $j$  right child with greater key

**if**  $A[i] < A[j]$  **then**

        swap( $A[i], A[j]$ )

$i \leftarrow j$ ; // keep sinking down

**else**

$i \leftarrow m$ ; // sift down finished

# Sort heap



$A[1, \dots, n]$  is a Heap.

While  $n > 1$

- $\text{swap}(A[1], A[n])$
- $\text{SiftDown}(A, 1, n - 1);$
- $n \leftarrow n - 1$

# Sort heap

swap  $\Rightarrow$ 

7	6	4	5	1	2
2	6	4	5	1	7

$A[1, \dots, n]$  is a Heap.

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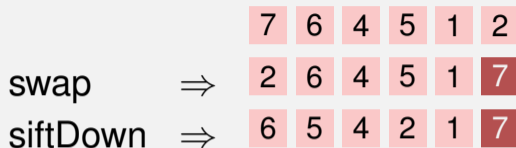


# Sort heap

$A[1, \dots, n]$  is a Heap.

While  $n > 1$

- $\text{swap}(A[1], A[n])$
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$A[1, \dots, n]$  is a Heap.

While  $n > 1$

- $\text{swap}(A[1], A[n])$
- $\text{SiftDown}(A, 1, n - 1);$
- $n \leftarrow n - 1$

swap

$\Rightarrow$

7	6	4	5	1	2
---	---	---	---	---	---

siftDown

$\Rightarrow$

2	6	4	5	1	7
---	---	---	---	---	---

swap

$\Rightarrow$

6	5	4	2	1	7
---	---	---	---	---	---

1	5	4	2	6	7
---	---	---	---	---	---

# Sort heap

$A[1, \dots, n]$  is a Heap.

While  $n > 1$

- $\text{swap}(A[1], A[n])$
- $\text{SiftDown}(A, 1, n - 1);$
- $n \leftarrow n - 1$



# Heap creation

**Observation:** Every leaf of a heap is trivially a correct heap.

**Consequence:**

# Heap creation

**Observation:** Every leaf of a heap is trivially a correct heap.

**Consequence:** Induction from below!

# Algorithm HeapSort( $A, n$ )

**Input:** Array  $A$  with length  $n$ .

**Output:**  $A$  sorted.

// Build the heap.

**for**  $i \leftarrow n/2$  **downto** 1 **do**

└ SiftDown( $A, i, n$ );

// Now  $A$  is a heap.

**for**  $i \leftarrow n$  **downto** 2 **do**

└ swap( $A[1], A[i]$ )

└ SiftDown( $A, 1, i - 1$ )

// Now  $A$  is sorted.

# Analysis: sorting a heap

SiftDown traverses at most  $\log n$  nodes. For each node 2 key comparisons.  $\Rightarrow$  sorting a heap costs in the worst case  $2 \log n$  comparisons.

Number of memory movements of sorting a heap also  $\mathcal{O}(n \log n)$ .

# Analysis: creating a heap

Calls to siftDown:  $n/2$ . Thus number of comparisons and movements:  $v(n) \in \mathcal{O}(n \log n)$ .

---

$$^{10} f(x) = \frac{1}{1-x} = 1 + x + x^2 \dots \Rightarrow f'(x) = \frac{1}{(1-x)^2} = 1 + 2x + \dots$$



# Analysis: creating a heap

Calls to siftDown:  $n/2$ . Thus number of comparisons and movements:  $v(n) \in \mathcal{O}(n \log n)$ .

But mean length of the sift-down paths is much smaller:

$$\begin{aligned} v(n) &= \sum_{l=0}^{\lfloor \log n \rfloor} \underbrace{2^l}_{\text{number heaps on level } l} \cdot \underbrace{(\lfloor \log n \rfloor - l)}_{\text{height heaps on level } l} = \sum_{k=0}^{\lfloor \log n \rfloor} 2^{\lfloor \log n \rfloor - k} \cdot k \\ &\leq \sum_{k=0}^{\lfloor \log n \rfloor} \frac{n}{2^k} \cdot k = n \cdot \sum_{k=0}^{\lfloor \log n \rfloor} \frac{k}{2^k} \in \mathcal{O}(n) \end{aligned}$$

with  $s(x) := \sum_{k=0}^{\infty} kx^k = \frac{x}{(1-x)^2}$  ( $0 < x < 1$ )<sup>10</sup> and  $s(\frac{1}{2}) = 2$

---

<sup>10</sup>  $f(x) = \frac{1}{1-x} = 1 + x + x^2 \dots \Rightarrow f'(x) = \frac{1}{(1-x)^2} = 1 + 2x + \dots$

## Intermediate result

Heapsort:  $\mathcal{O}(n \log n)$  Comparisons and movements.

❓ Disadvantages of heapsort?

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- ❗ Missing locality: heapsort jumps around in the sorted array (negative cache effect).

# Intermediate result

Heapsort:  $\mathcal{O}(n \log n)$  Comparisons and movements.

## ❓ Disadvantages of heapsort?

- ❗ Missing locality: heapsort jumps around in the sorted array (negative cache effect).
- ❗ Two comparisons required before each necessary memory movement.

## 8.2 Mergesort

[Ottman/Widmayer, Kap. 2.4, Cormen et al, Kap. 2.3],

# Mergesort

Divide and Conquer!

- Assumption: two halves of the array  $A$  are already sorted.
- Minimum of  $A$  can be evaluated with two comparisons.
- Iteratively: merge the two presorted halves of  $A$  in  $\mathcal{O}(n)$ .

# Merge

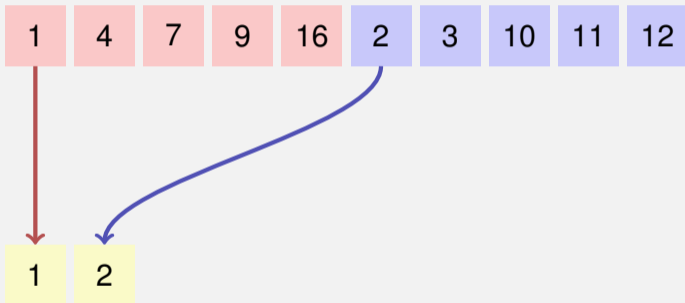


# Merge

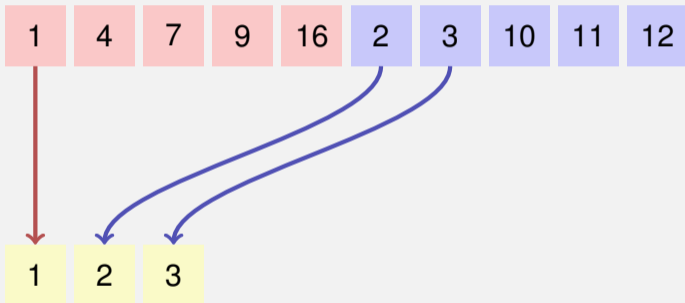




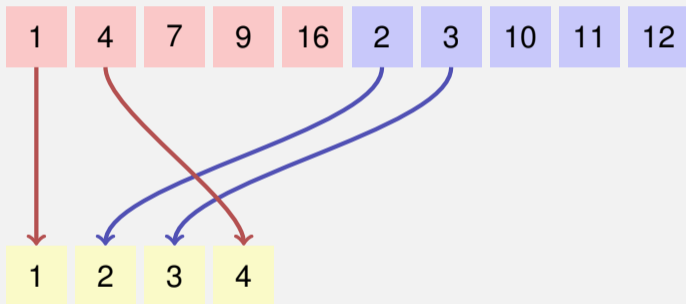
# Merge



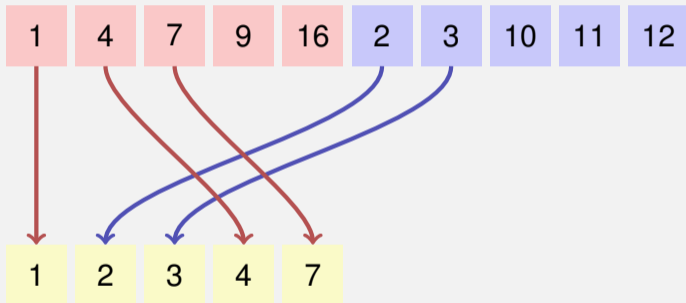
# Merge



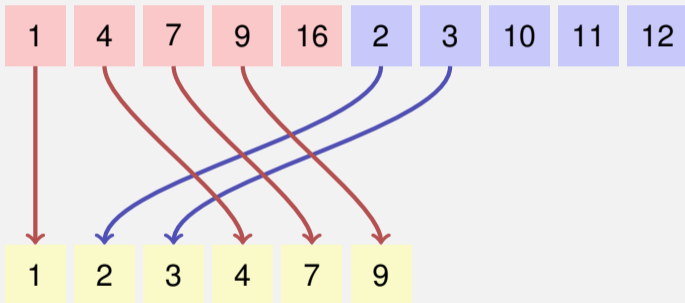
# Merge



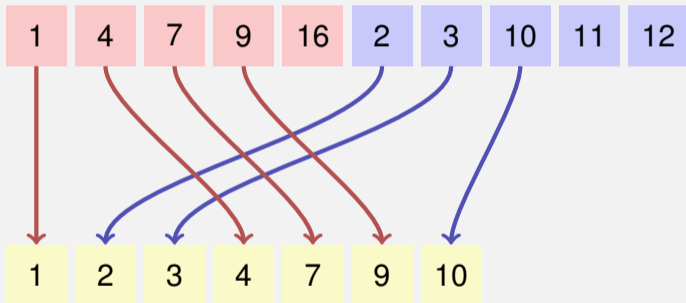
# Merge



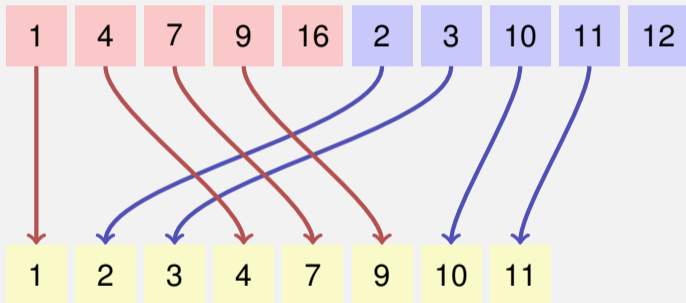
# Merge



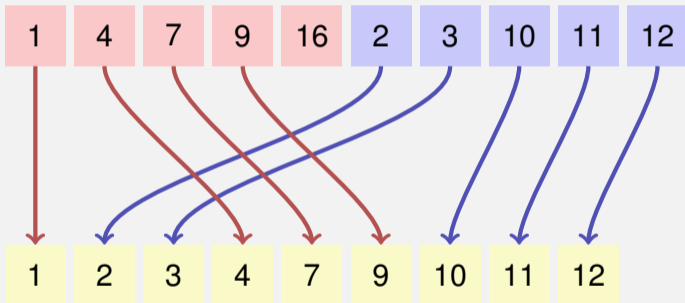
# Merge



# Merge

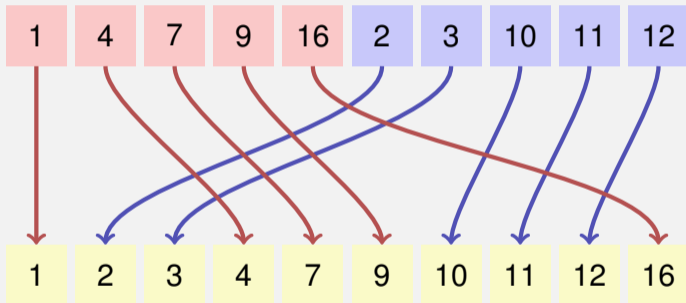


# Merge





# Merge



# Algorithm Merge( $A, l, m, r$ )

**Input:** Array  $A$  with length  $n$ , indexes  $1 \leq l \leq m \leq r \leq n$ .

$A[l, \dots, m]$ ,  $A[m + 1, \dots, r]$  sorted

**Output:**  $A[l, \dots, r]$  sorted

1  $B \leftarrow$  new Array( $r - l + 1$ )

2  $i \leftarrow l$ ;  $j \leftarrow m + 1$ ;  $k \leftarrow 1$

3 **while**  $i \leq m$  and  $j \leq r$  **do**

4     **if**  $A[i] \leq A[j]$  **then**  $B[k] \leftarrow A[i]$ ;  $i \leftarrow i + 1$

5     **else**  $B[k] \leftarrow A[j]$ ;  $j \leftarrow j + 1$

6      $k \leftarrow k + 1$ ;

7 **while**  $i \leq m$  **do**  $B[k] \leftarrow A[i]$ ;  $i \leftarrow i + 1$ ;  $k \leftarrow k + 1$

8 **while**  $j \leq r$  **do**  $B[k] \leftarrow A[j]$ ;  $j \leftarrow j + 1$ ;  $k \leftarrow k + 1$

9 **for**  $k \leftarrow l$  **to**  $r$  **do**  $A[k] \leftarrow B[k - l + 1]$

# Correctness

Hypothesis: after  $k$  iterations of the loop in line 3  $B[1, \dots, k]$  is sorted and  $B[k] \leq A[i]$ , if  $i \leq m$  and  $B[k] \leq A[j]$  if  $j \leq r$ .

Proof by induction:

*Base case:* the empty array  $B[1, \dots, 0]$  is trivially sorted.

*Induction step* ( $k \rightarrow k + 1$ ):

- wlog  $A[i] \leq A[j]$ ,  $i \leq m, j \leq r$ .
- $B[1, \dots, k]$  is sorted by hypothesis and  $B[k] \leq A[i]$ .
- After  $B[k + 1] \leftarrow A[i]$   $B[1, \dots, k + 1]$  is sorted.
- $B[k + 1] = A[i] \leq A[i + 1]$  (if  $i + 1 \leq m$ ) and  $B[k + 1] \leq A[j]$  if  $j \leq r$ .
- $k \leftarrow k + 1, i \leftarrow i + 1$ : Statement holds again.

# Analysis (Merge)

## Lemma

*If: array  $A$  with length  $n$ , indexes  $1 \leq l < r \leq n$ .  $m = \lfloor (l + r)/2 \rfloor$  and  $A[l, \dots, m]$ ,  $A[m + 1, \dots, r]$  sorted.*

*Then: in the call of  $\text{Merge}(A, l, m, r)$  a number of  $\Theta(r - l)$  key movements and comparisons are executed.*

Proof: straightforward (Inspect the algorithm and count the operations.)

# Mergesort

5 2 6 1 8 4 3 9

# Mergesort

5 2 6 1 8 4 3 9

Split

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

Split

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

Split

Split



# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

Split

Split

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

Split

Split

Split

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

Split

Split

Split

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

Split

Split

Split

Merge

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

2 5 1 6 4 8 3 9

Split

Split

Split

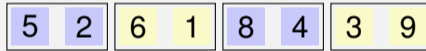
Merge

# Mergesort

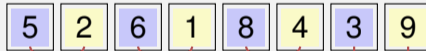
5 2 6 1 8 4 3 9



Split



Split



Split



Merge

Merge

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

2 5 1 6 4 8 3 9

1 2 5 6 3 4 8 9

Split

Split

Split

Merge

Merge

# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

2 5 1 6 4 8 3 9

1 2 5 6 3 4 8 9

Split

Split

Split

Merge

Merge

Merge



# Mergesort

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

5 2 6 1 8 4 3 9

2 5 1 6 4 8 3 9

1 2 5 6 3 4 8 9

1 2 3 4 5 6 8 9

Split

Split

Split

Merge

Merge

Merge

# Algorithm (recursive 2-way) Mergesort( $A, l, r$ )

**Input:** Array  $A$  with length  $n$ .  $1 \leq l \leq r \leq n$

**Output:** Array  $A[l, \dots, r]$  sorted.

**if**  $l < r$  **then**

$m \leftarrow \lfloor (l + r) / 2 \rfloor$            // middle position

    Mergesort( $A, l, m$ )           // sort lower half

    Mergesort( $A, m + 1, r$ )       // sort higher half

    Merge( $A, l, m, r$ )           // Merge subsequences

# Analysis

Recursion equation for the number of comparisons and key movements:

$$T(n) = T\left(\left\lceil \frac{n}{2} \right\rceil\right) + T\left(\left\lfloor \frac{n}{2} \right\rfloor\right) + \Theta(n)$$

# Analysis

Recursion equation for the number of comparisons and key movements:

$$T(n) = T\left(\left\lceil \frac{n}{2} \right\rceil\right) + T\left(\left\lfloor \frac{n}{2} \right\rfloor\right) + \Theta(n) \in \Theta(n \log n)$$

# Algorithm StraightMergesort( $A$ )

*Avoid recursion:* merge sequences of length 1, 2, 4, ... directly

**Input:** Array  $A$  with length  $n$

**Output:** Array  $A$  sorted

$length \leftarrow 1$

**while**  $length < n$  **do** // Iterate over lengths  $n$

$r \leftarrow 0$

**while**  $r + length < n$  **do** // Iterate over subsequences

$l \leftarrow r + 1$

$m \leftarrow l + length - 1$

$r \leftarrow \min(m + length, n)$

        Merge( $A, l, m, r$ )

$length \leftarrow length \cdot 2$

# Analysis

Like the recursive variant, the straight 2-way mergesort always executes a number of  $\Theta(n \log n)$  key comparisons and key movements.

# Natural 2-way mergesort

Observation: the variants above do not make use of any presorting and always execute  $\Theta(n \log n)$  memory movements.

② How can partially presorted arrays be sorted better?

# Natural 2-way mergesort

Observation: the variants above do not make use of any presorting and always execute  $\Theta(n \log n)$  memory movements.

- ② How can partially presorted arrays be sorted better?
- ① Recursive merging of previously sorted parts (*runs*) of  $A$ .



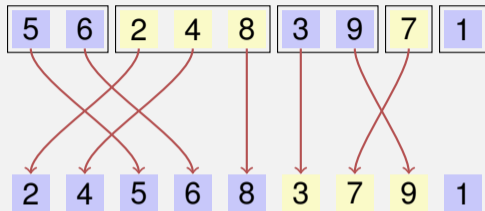
# Natural 2-way mergesort

5 6 2 4 8 3 9 7 1

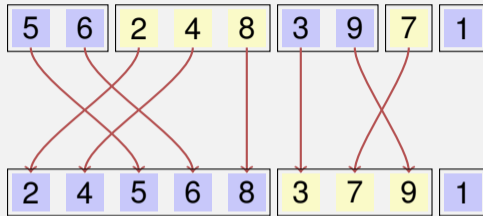
# Natural 2-way mergesort



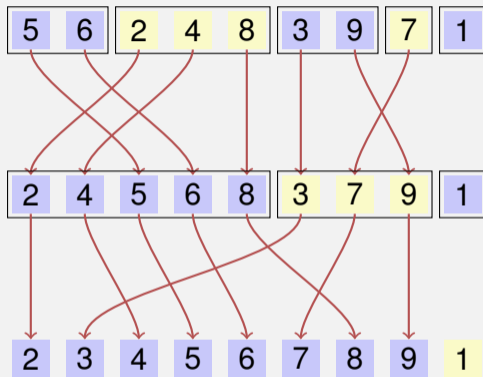
# Natural 2-way mergesort



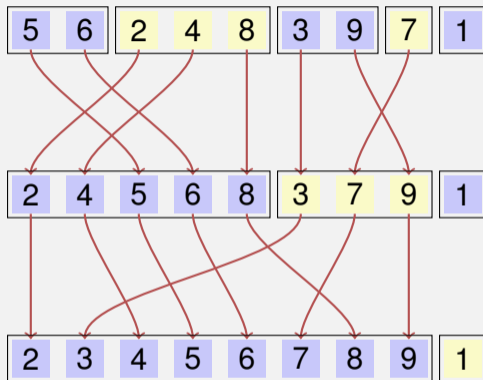
# Natural 2-way mergesort



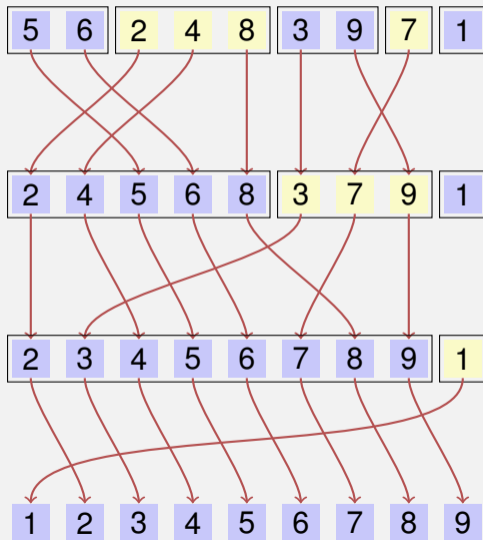
# Natural 2-way mergesort



# Natural 2-way mergesort



# Natural 2-way mergesort



# Algorithm NaturalMergesort( $A$ )

**Input:** Array  $A$  with length  $n > 0$

**Output:** Array  $A$  sorted

**repeat**

$r \leftarrow 0$

**while**  $r < n$  **do**

$l \leftarrow r + 1$

$m \leftarrow l$ ; **while**  $m < n$  **and**  $A[m + 1] \geq A[m]$  **do**  $m \leftarrow m + 1$

**if**  $m < n$  **then**

$r \leftarrow m + 1$ ; **while**  $r < n$  **and**  $A[r + 1] \geq A[r]$  **do**  $r \leftarrow r + 1$

            Merge( $A, l, m, r$ );

**else**

$r \leftarrow n$

**until**  $l = 1$



# Analysis

② Is it also asymptotically better than StraightMergesort on average?

# Analysis

② Is it also asymptotically better than StraightMergesort on average?

⚠ No. Given the assumption of pairwise distinct keys, on average there are  $n/2$  positions  $i$  with  $k_i > k_{i+1}$ , i.e.  $n/2$  runs. Only one iteration is saved on average.

Natural mergesort executes in the worst case and on average a number of  $\Theta(n \log n)$  comparisons and memory movements.

## 8.3 Quicksort

[Ottman/Widmayer, Kap. 2.2, Cormen et al, Kap. 7]

# Quicksort

② What is the disadvantage of Mergesort?

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② How?

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② How could we reduce the merge costs?

⚠ Make sure that the left part contains only smaller elements than the right part.

② How?

⚠ Pivot and Partition!



# Use a pivot



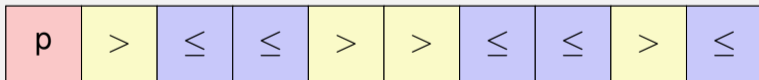
# Use a pivot

- 1 Choose a (an arbitrary) *pivot*  $p$



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- 1 Choose a (an arbitrary) *pivot*  $p$
- 2 Partition  $A$  in two parts, one part  $L$  with the elements with  $A[i] \leq p$  and another part  $R$  with  $A[i] > p$



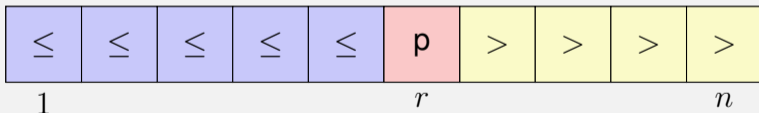
# Use a pivot

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- 3 Quicksort: Recursion on parts  $L$  and  $R$



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- 3 Quicksort: Recursion on parts  $L$  and  $R$



# Algorithm Partition( $A[l..r], p$ )

**Input:** Array  $A$ , that contains the pivot  $p$  in the interval  $[l, r]$  at least once.

**Output:** Array  $A$  partitioned in  $[l..r]$  around  $p$ . Returns position of  $p$ .

**while**  $l \leq r$  **do**

**while**  $A[l] < p$  **do**

$l \leftarrow l + 1$

**while**  $A[r] > p$  **do**

$r \leftarrow r - 1$

    swap( $A[l], A[r]$ )

**if**  $A[l] = A[r]$  **then**

$l \leftarrow l + 1$

**return**  $l-1$

# Algorithm Quicksort( $A[l, \dots, r]$ )

**Input:** Array  $A$  with length  $n$ .  $1 \leq l \leq r \leq n$ .

**Output:** Array  $A$ , sorted between  $l$  and  $r$ .

**if**  $l < r$  **then**

    Choose pivot  $p \in A[l, \dots, r]$

$k \leftarrow \text{Partition}(A[l, \dots, r], p)$

    Quicksort( $A[l, \dots, k - 1]$ )

    Quicksort( $A[k + 1, \dots, r]$ )

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1



# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

1 2 3 4 5 8 7 9 6

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

1 2 3 4 5 8 7 9 6

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

1 2 3 4 5 8 7 9 6

1 2 3 4 5 6 7 9 8

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

1 2 3 4 5 8 7 9 6

1 2 3 4 5 6 7 9 8

# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

1 2 3 4 5 8 7 9 6

1 2 3 4 5 6 7 9 8

1 2 3 4 5 6 7 8 9



# Quicksort (arbitrary pivot)

2 4 5 6 8 3 7 9 1

2 1 3 6 8 5 7 9 4

1 2 3 4 5 8 7 9 6

1 2 3 4 5 6 7 9 8

1 2 3 4 5 6 7 8 9

1 2 3 4 5 6 7 8 9

# Analysis: number comparisons

*Worst case.*

# Analysis: number comparisons

*Worst case.* Pivot = min or max; number comparisons:

$$T(n) = T(n - 1) + c \cdot n, T(1) = 0 \quad \Rightarrow \quad T(n) \in \Theta(n^2)$$

# Analysis: number swaps

Result of a call to partition (pivot 3):

2 1 3 6 8 5 7 9 4

① How many swaps have taken place?

# Analysis: number swaps

Result of a call to partition (pivot 3):

2 1 3 6 8 5 7 9 4

② How many swaps have taken place?

① 2. The maximum number of swaps is given by the number of keys in the smaller part.

# Analysis: number swaps

*Thought experiment*

# Analysis: number swaps

## *Thought experiment*

- Each key from the smaller part pays a coin when it is being swapped.

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- Each key from the smaller part pays a coin when it is being swapped.
- After a key has paid a coin the domain containing the key decreases to half its previous size.



# Analysis: number swaps

## *Thought experiment*

- Each key from the smaller part pays a coin when it is being swapped.
- After a key has paid a coin the domain containing the key decreases to half its previous size.
- Every key needs to pay at most  $\log n$  coins. But there are only  $n$  keys.

# Analysis: number swaps

## *Thought experiment*

- Each key from the smaller part pays a coin when it is being swapped.
- After a key has paid a coin the domain containing the key decreases to half its previous size.
- Every key needs to pay at most  $\log n$  coins. But there are only  $n$  keys.

*Consequence:* there are  $\mathcal{O}(n \log n)$  key swaps in the worst case.

# Randomized Quicksort

Despite the worst case running time of  $\Theta(n^2)$ , quicksort is used practically very often.

Reason: quadratic running time unlikely provided that the choice of the pivot and the pre-sorting are not very disadvantageous.

Avoidance: randomly choose pivot. Draw uniformly from  $[l, r]$ .

# Analysis (randomized quicksort)

Expected number of compared keys with input length  $n$ :

$$T(n) = (n - 1) + \frac{1}{n} \sum_{k=1}^n (T(k - 1) + T(n - k)), \quad T(0) = T(1) = 0$$

Claim  $T(n) \leq 4n \log n$ .

Proof by induction:

*Base case* straightforward for  $n = 0$  (with  $0 \log 0 := 0$ ) and for  $n = 1$ .

*Hypothesis:*  $T(n) \leq 4n \log n$  for some  $n$ .

*Induction step:*  $(n - 1 \rightarrow n)$

# Analysis (randomized quicksort)

$$\begin{aligned}T(n) &= n - 1 + \frac{2}{n} \sum_{k=0}^{n-1} T(k) \stackrel{H}{\leq} n - 1 + \frac{2}{n} \sum_{k=0}^{n-1} 4k \log k \\&= n - 1 + \sum_{k=1}^{n/2} 4k \underbrace{\log k}_{\leq \log n - 1} + \sum_{k=n/2+1}^{n-1} 4k \underbrace{\log k}_{\leq \log n} \\&\leq n - 1 + \frac{8}{n} \left( (\log n - 1) \sum_{k=1}^{n/2} k + \log n \sum_{k=n/2+1}^{n-1} k \right) \\&= n - 1 + \frac{8}{n} \left( (\log n) \cdot \frac{n(n-1)}{2} - \frac{n}{4} \left( \frac{n}{2} + 1 \right) \right) \\&= 4n \log n - 4 \log n - 3 \leq 4n \log n\end{aligned}$$

# Analysis (randomized quicksort)

## Theorem

*On average randomized quicksort requires  $\mathcal{O}(n \cdot \log n)$  comparisons.*

# Practical Considerations

Worst case recursion depth  $n - 1$ <sup>11</sup>. Then also a memory consumption of  $\mathcal{O}(n)$ .

Can be avoided: recursion only on the smaller part. Then guaranteed  $\mathcal{O}(\log n)$  worst case recursion depth and memory consumption.

---

<sup>11</sup>stack overflow possible!

# Quicksort with logarithmic memory consumption

**Input:** Array  $A$  with length  $n$ .  $1 \leq l \leq r \leq n$ .

**Output:** Array  $A$ , sorted between  $l$  and  $r$ .

**while**  $l < r$  **do**

    Choose pivot  $p \in A[l, \dots, r]$

$k \leftarrow \text{Partition}(A[l, \dots, r], p)$

**if**  $k - l < r - k$  **then**

        Quicksort( $A[l, \dots, k - 1]$ )

$l \leftarrow k + 1$

**else**

        Quicksort( $A[k + 1, \dots, r]$ )

$r \leftarrow k - 1$

The call of Quicksort( $A[l, \dots, r]$ ) in the original algorithm has moved to iteration (tail recursion!): the if-statement became a while-statement.



# Practical Considerations.

- Practically the pivot is often the median of three elements. For example:  $\text{Median3}(A[l], A[r], A[\lfloor l + r/2 \rfloor])$ .
- There is a variant of quicksort that requires only constant storage. Idea: store the old pivot at the position of the new pivot.
- Complex divide-and-conquer algorithms often use a trivial ( $\Theta(n^2)$ ) algorithm as base case to deal with small problem sizes.

## 8.4 Appendix

Derivation of some mathematical formulas

$$\log n! \in \Theta(n \log n)$$

$$\begin{aligned}\log n! &= \sum_{i=1}^n \log i \leq \sum_{i=1}^n \log n = n \log n \\ \sum_{i=1}^n \log i &= \sum_{i=1}^{\lfloor n/2 \rfloor} \log i + \sum_{\lfloor n/2 \rfloor + 1}^n \log i \\ &\geq \sum_{i=2}^{\lfloor n/2 \rfloor} \log 2 + \sum_{\lfloor n/2 \rfloor + 1}^n \log \frac{n}{2} \\ &= \underbrace{(\lfloor n/2 \rfloor - 2 + 1)}_{> n/2 - 1} + \underbrace{(n - \lfloor n/2 \rfloor)}_{\geq n/2} (\log n - 1) \\ &> \frac{n}{2} \log n - 2.\end{aligned}$$

$$[n! \in o(n^n)]$$

$$\begin{aligned} n \log n &\geq \sum_{i=1}^{\lfloor n/2 \rfloor} \log 2i + \sum_{i=\lfloor n/2 \rfloor+1}^n \log i \\ &= \sum_{i=1}^n \log i + \left\lfloor \frac{n}{2} \right\rfloor \log 2 \\ &> \sum_{i=1}^n \log i + n/2 - 1 = \log n! + n/2 - 1 \end{aligned}$$

$$\begin{aligned} n^n &= 2^{n \log_2 n} \geq 2^{\log_2 n!} \cdot 2^{n/2} \cdot 2^{-1} = n! \cdot 2^{n/2-1} \\ \Rightarrow \frac{n!}{n^n} &\leq 2^{-n/2+1} \xrightarrow{n \rightarrow \infty} 0 \Rightarrow n! \in o(n^n) = \mathcal{O}(n^n) \setminus \Omega(n^n) \end{aligned}$$

**[Even  $n! \in o((n/c)^n) \forall 0 < c < e$  ]**

Konvergenz oder Divergenz von  $f_n = \frac{n!}{(n/c)^n}$ .

Ratio Test

$$\frac{f_{n+1}}{f_n} = \frac{(n+1)!}{\left(\frac{n+1}{c}\right)^{n+1}} \cdot \frac{\left(\frac{n}{c}\right)^n}{n!} = c \cdot \left(\frac{n}{n+1}\right)^n \longrightarrow c \cdot \frac{1}{e} \lesseqgtr 1 \text{ if } c \lesseqgtr e$$

because  $\left(1 + \frac{1}{n}\right)^n \rightarrow e$ . Even the series  $\sum_{i=1}^n f_n$  converges / diverges for  $c \lesseqgtr e$ .

$f_n$  diverges for  $c = e$ , because (Stirling):  $n! \approx \sqrt{2\pi n} \left(\frac{n}{e}\right)^n$ .

# [ Ratio Test]

Ratio test for a sequence  $(f_n)_{n \in \mathbb{N}}$ : If  $\frac{f_{n+1}}{f_n} \xrightarrow[n \rightarrow \infty]{} \lambda$ , then the sequence  $f_n$  and the series  $\sum_{i=1}^n f_i$

- converge, if  $\lambda < 1$  and
- diverge, if  $\lambda > 1$ .

# [ Ratio Test Derivation ]

Ratio test is implied by Geometric Series

$$S_n(r) := \sum_{i=0}^n r^i = \frac{1 - r^{n+1}}{1 - r}.$$

converges for  $n \rightarrow \infty$  if and only if  $-1 < r < 1$ .

Let  $0 \leq \lambda < 1$ :

$$\begin{aligned} & \forall \varepsilon > 0 \exists n_0 : f_{n+1}/f_n < \lambda + \varepsilon \forall n \geq n_0 \\ \Rightarrow & \exists \mu > 0, \exists n_0 : f_{n+1}/f_n \leq \mu < 1 \forall n \geq n_0 \end{aligned}$$

Thus

$$\sum_{n=n_0}^{\infty} f_n \leq f_{n_0} \cdot \sum_{n=n_0}^{\infty} \mu^{n-n_0} \quad \text{konvergiert.}$$

(Analogously for divergence)