# 28. Parallel Programming II

Shared Memory, Concurrency, Excursion: lock algorithm (Peterson), Mutual Exclusion Race Conditions [C++ Threads: Williams, Kap. 2.1-2.2], [C++ Race Conditions: Williams, Kap. 3.1] [C++ Mutexes: Williams, Kap. 3.2.1, 3.3.3]

## 28.1 Shared Memory, Concurrency

Sharing Resources (Memory)	Managing state

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- Up to now: fork-join algorithms: data parallel or divide-and-conquer
- Simple structure (data independence of the threads) to avoid race conditions
- Does not work any more when threads access shared memory.

Managing state: Main challenge of concurrent programming.

Approaches:

- Immutability, for example constants.
- Isolated Mutability, for example thread-local variables, stack.
- Shared mutable data, for example references to shared memory, global variables

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## Protect the shared state

- Method 1: locks, guarantee exclusive access to shared data.
- Method 2: lock-free data structures, exclusive access with a much finer granularity.
- Method 3: transactional memory (not treated in class)

#### **Canonical Example**

```
class BankAccount {
   int balance = 0;
public:
   int getBalance(){ return balance; }
   void setBalance(int x) { balance = x; }
   void withdraw(int amount) {
      int b = getBalance();
      setBalance(b - amount);
   }
   // deposit etc.
};
```

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(correct in a single-threaded world)

**Bad Interleaving Tempting Traps** Parallel call to widthdraw(100) on the same account WRONG: void withdraw(int amount) { int b = getBalance(); Thread 1 Thread 2 if (b==getBalance()) setBalance(b - amount); int b = getBalance(); } int b = getBalance(); setBalance(b-amount); Bad interleavings cannot be solved with a repeated reading setBalance(b-amount);

## **Tempting Traps**

## **Mutual Exclusion**

#### also WRONG:

```
void withdraw(int amount) {
    setBalance(getBalance() - amount);
}
```

Assumptions about atomicity of operations are almost always wrong

We need a concept for mutual exclusion

*Only one thread* may execute the operation withdraw *on the same account* at a time.

The programmer has to make sure that mutual exclusion is used.

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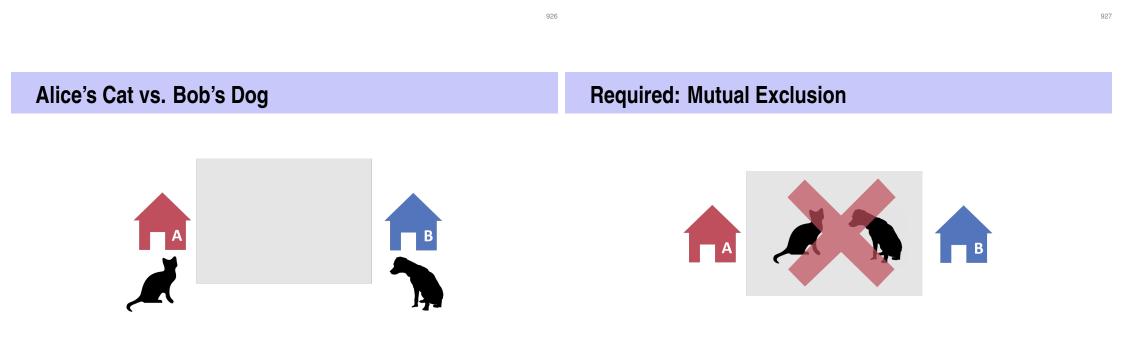
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More Tempting Traps	Just moved the problem!
<pre>class BankAccount {    int balance = 0;    bool busy = false;</pre>	Thread 1 Thread 2
<pre>public: void withdraw(int amount) {</pre>	<pre>while (busy); //spin</pre>
	<pre>while (busy); //spin busy = true;</pre>
<pre>while (busy); // spin wait busy = true; int b = getBalance(); setBalance(b - amount); busy = false;</pre>	<pre>t busy = true; int b = getBalance();</pre>
busy = false;	<pre>int b = getBalance();</pre>
}	<pre>setBalance(b - amount);</pre>
<pre>// deposit would spin on the same boolean };</pre>	<pre>\$\$\$ setBalance(b - amount);</pre>

## How ist this correctly implemented?

- We use *locks* (mutexes) from libraries
- They use hardware primitives, *Read-Modify-Write* (RMW) operations that can, in an atomic way, read and write depending on the read result.
- Without RMW Operations the algorithm is non-trivial and requires at least atomic access to variable of primitive type.

## 28.2 Excursion: lock algorithm



## **Required: No Lockout When Free**



## **Communication Types**

Transient: Parties participate at the same time



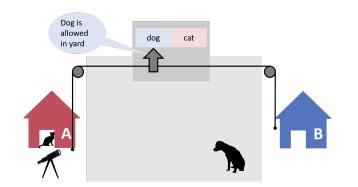
Persistent: Parties participate at different times

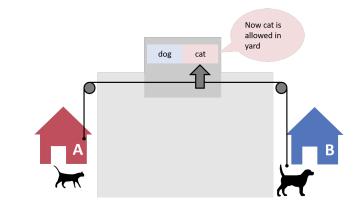


Mutual exclusion: persistent communication

## **Communication Idea 1**

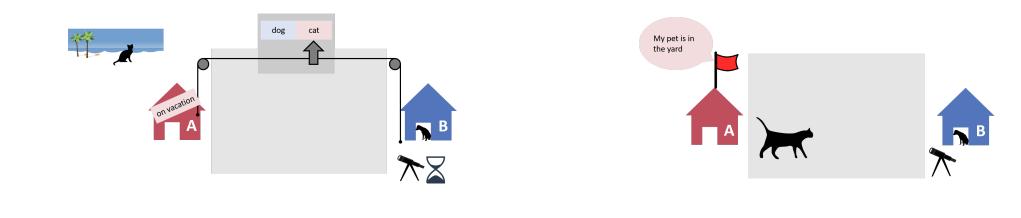
## **Access Protocol**





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## **Problem!**



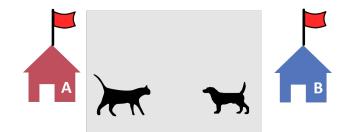
Access Protocol 2.1 Different Scenario

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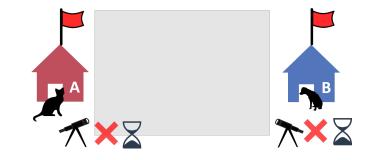


## **Communication Idea 2**

## **Problem: No Mutual Exclusion**



## **Checking Flags Twice: Deadlock**



**Access Protocol 2.2** 

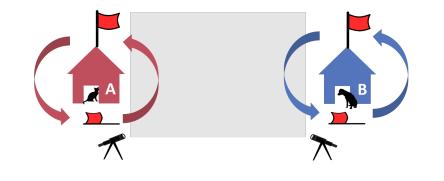
## Access Protocol 2.2:provably correct



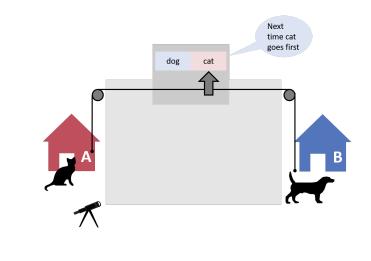


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## Weniger schwerwiegend: Starvation



## **Final Solution**



## **General Problem of Locking remains**



## Peterson's Algorithm<sup>54</sup>

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for two processes is provable correct and free from starvation

#### non-critical section

flag[me] = true // I am interested
victim = me // but you go first
// spin while we are both interested and you go first:
while (flagform) fit wistin == ma) fit;

while (flag[you] && victim == me) {};

#### critical section

flag[me] = false

The code assumes that the access to flag / victim is atomic and particularly linearizable or sequential consistent. An assumption that – as we will see below – is not necessarily given for normal variables. The Peterson-lock is not used on modern hardware.

```
<sup>54</sup>not relevant for the exam
```

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## 28.3 Mutual Exclusion

## **Critical Sections and Mutual Exclusion**

#### Critical Section

Piece of code that may be executed by at most one process (thread) at a time.

#### Mutual Exclusion

Algorithm to implement a critical section

acquire\_mutex(); // entry algorithm\\ // critical section ... release\_mutex(); // exit algorithm

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#### **Required Properties of Mutual Exclusion** class BankAccount { Correctness (Safety) At most one process executes the critical section code public: . . . m.lock(); Liveness Acquiring the mutex must terminate in m.unlock(); finite time when no process executes } in the critical section }; What if an exception occurs?

### **Almost Correct**

```
int balance = 0;
std::mutex m; // requires #include <mutex>
void withdraw(int amount) {
  int b = getBalance();
  setBalance(b - amount);
```

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## **RAII Approach**

```
class BankAccount {
   int balance = 0;
   std::mutex m;
public:
   ...
   void withdraw(int amount) {
     std::lock_guard<std::mutex> guard(m);
     int b = getBalance();
     setBalance(b - amount);
   } // Destruction of guard leads to unlocking m
};
```

What about getBalance / setBalance?

#### **Reentrant Locks**

Reentrant Lock (recursive lock)

remembers the currently affected thread;

provides a counter

- Call of lock: counter incremented
- Call of unlock: counter is decremented. If counter = 0 the lock is released.

thread

count

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### Account with reentrant lock

```
class BankAccount {
    int balance = 0;
    std::recursive_mutex m;
    using guard = std::lock_guard<std::recursive_mutex>;
public:
    int getBalance(){ guard g(m); return balance;
    }
    void setBalance(int x) { guard g(m); balance = x;
    }
    void withdraw(int amount) { guard g(m);
        int b = getBalance();
        setBalance(b - amount);
    }
};
```

#### 28.4 Race Conditions

#### **Race Condition**

#### **Example: Stack**

Stack with correctly synchronized access:

```
A race condition occurs when the result of a computation depends
on scheduling.
```

- We make a distinction between *bad interleavings* and *data races*
- **Bad interleavings** can occur even when a mutex is used.

```
template <typename T>
class stack{
    ...
    std::recursive_mutex m;
    using guard = std::lock_guard<std::recursive_mutex>;
public:
    bool isEmpty(){ guard g(m); ... }
    void push(T value){ guard g(m); ... }
    T pop(){ guard g(m); ...}
};
```

Peek

Forgot to implement peek. Like this?

template <typename T>
T peek (stack<T> &s){
 T value = s.pop();
 s.push(value);
 return value;
}



Despite its questionable style the code is correct in a sequential world. Not so in concurrent programming.

#### **Bad Interleaving!**

Initially empty stack *s*, only shared between threads 1 and 2. Thread 1 pushes a value and checks that the stack is then non-empty. Thread 2 reads the topmost value using peek().

Thread 1	Thread 2
s.push(5); assert(!s.isEmpty());	<pre>int value = s.pop();</pre>
	<pre>s.push(value); return value;</pre>

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## The fix

Peek must be protected with the same lock as the other access methods

#### **Bad Interleavings**

Race conditions as bad interleavings can happen on a high level of abstraction

In the following we consider a different form of race condition: data race.

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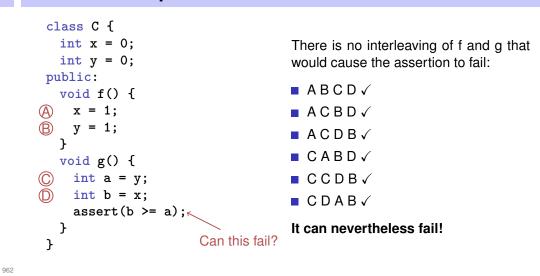
How about this? Why wrong? class counter{ It looks like nothing can go wrong because the update of count int count = 0; happens in a "tiny step". std::recursive\_mutex m; using guard = std::lock\_guard<std::recursive\_mutex>; But this code is still wrong and depends on public: language-implementation details you cannot assume. int increase(){ This problem is called *Data-Race* guard g(m); return ++count; } Moral: Do not introduce a data race, even if every interleaving you int get(){ can think of is correct. Don't make assumptions on the memory not thread-safe! return count; order. } }

#### A bit more formal

*Data Race* (low-level Race-Conditions) Erroneous program behavior caused by insufficiently synchronized accesses of a shared resource by multiple threads, e.g. Simultaneous read/write or write/write of the same memory location

*Bad Interleaving* (High Level Race Condition) Erroneous program behavior caused by an unfavorable execution order of a multithreaded algorithm, even if that makes use of otherwise well synchronized resources.

#### We look deeper



**One Resason: Memory Reordering** 

*Rule of thumb:* Compiler and hardware allowed to make changes that do not affect the *semantics of a sequentially* executed program

```
      void f() {
      void f() {

      x = 1;
      x = 1;

      y = x+1;
      x = x+1;

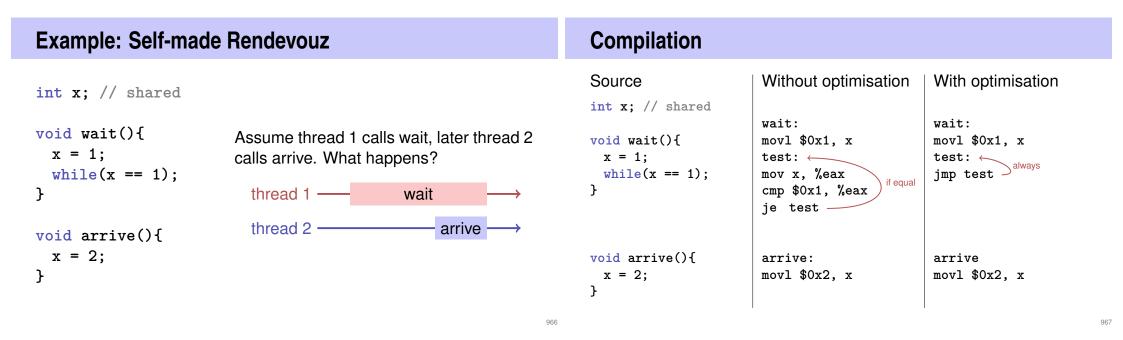
      z = x+1;
      sequentially equivalent

      y = x+1;
      y = x+1;
```

From a Software-Perspective

Modern compilers do not give guarantees that a global ordering of memory accesses is provided as in the sourcecode:

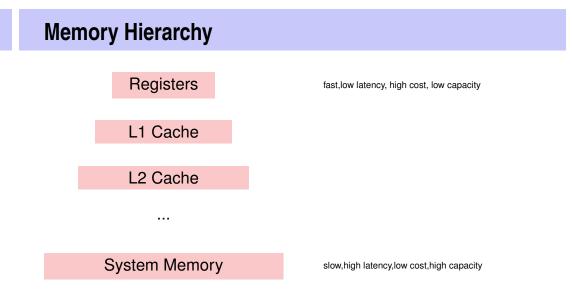
- Some memory accesses may be even optimized away completely!
- Huge potential for optimizations and for errors, when you make the wrong assumptions

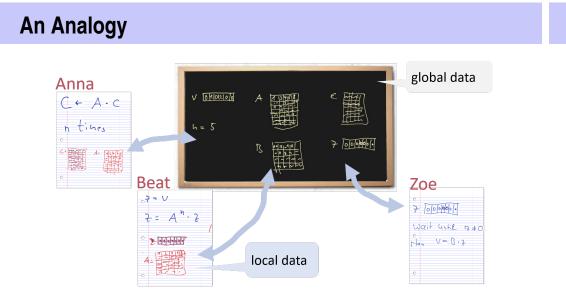


**Hardware Perspective** 

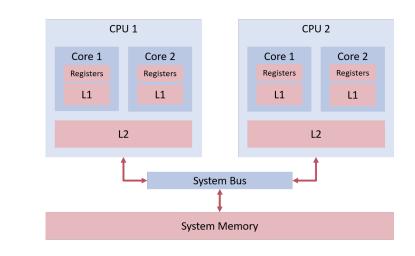
Modern multiprocessors do not enforce global ordering of all instructions for performance reasons:

- Most processors have a pipelined architecture and can execute (parts of) multiple instructions simultaneously. They can even reorder instructions internally.
- Each processor has a local cache, and thus loads/stores to shared memory can become visible to other processors at different times





## Schematic



When and if effects of memory operations become visible for threads, depends on hardware, runtime system and programming language.

A *memory model* (e.g. that of C++) provides minimal guarantees for the effect of memory operations

- leaving open possibilities for optimisation
- containing guidelines for writing thread-safe programs

For instance, C++ provides *guarantees when synchronisation with a mutex* is used.

## Fixed

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```
class C {
    int x = 0;
    int y = 0;
    std::mutex m;
public:
    void f() {
        m.lock(); x = 1; m.unlock();
        m.lock(); y = 1; m.unlock();
    }
    void g() {
        m.lock(); int a = y; m.unlock();
        m.lock(); int b = x; m.unlock();
        assert(b >= a); // cannot fail
    }
};
```

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# Atomic

Here also possible:

```
class C {
   std::atomic_int x{0}; // requires #include <atomic>
   std::atomic_int y{0};
public:
   void f() {
        x = 1;
        y = 1;
     }
   void g() {
        int a = y;
        int b = x;
        assert(b >= a); // cannot fail
   }
};
```