

# 11. Fundamental Data Structures

Abstract data types stack, queue, implementation variants for linked lists, amortized analysis [Ottman/Widmayer, Kap. 1.5.1-1.5.2, Cormen et al, Kap. 10.1.-10.2,17.1-17.3]

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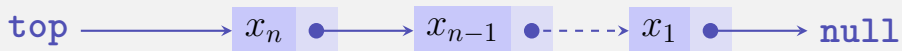
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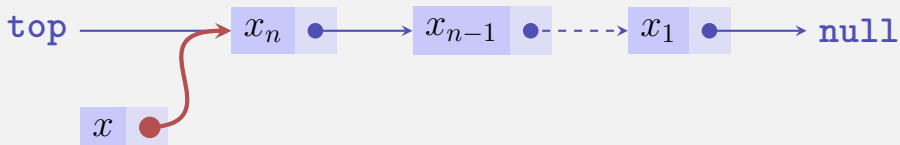
# Implementation Push



`push(x, S):`



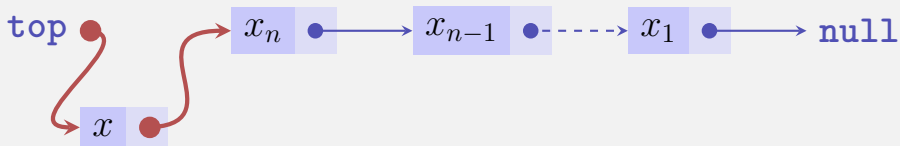
# Implementation Push



`push(x, S):`

- 1 Create new list element with  $x$  and pointer to the value of `top`.

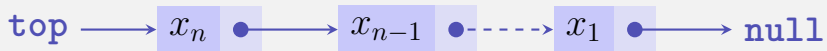
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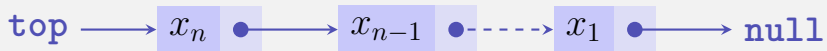
- 1 Create new list element with  $x$  and pointer to the value of `top`.
- 2 Assign the node with  $x$  to `top`.

# Implementation Pop



`pop(S)`:

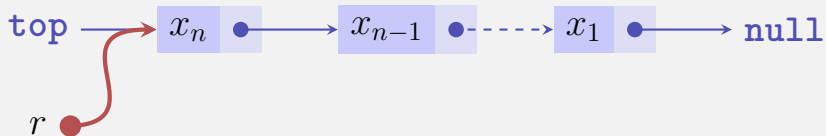
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`pop(S)`:

- 1 If `top=null`, then return `null`

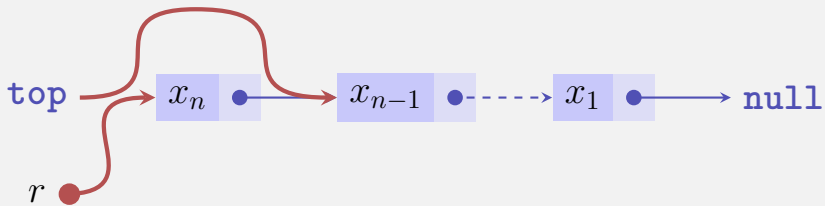
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$\text{pop}(S)$ :

- 1 If  $\text{top}=\text{null}$ , then return  $\text{null}$
- 2 otherwise memorize pointer  $p$  of  $\text{top}$  in  $r$ .

# Implementation Pop



`pop(S)`:

- 1 If `top=null`, then return `null`
- 2 otherwise memorize pointer  $p$  of `top` in  $r$ .
- 3 Set `top` to  $p.next$  and return  $r$

# Analysis

Each of the operations `push`, `pop`, `top` and `isEmpty` on a stack can be executed in  $\mathcal{O}(1)$  steps.

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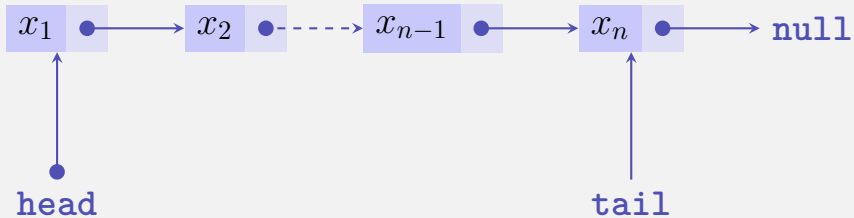
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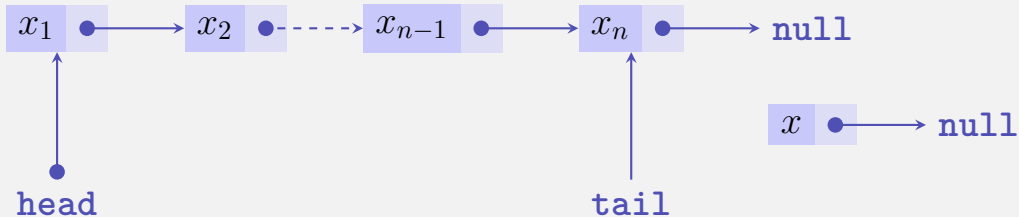
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- **emptyQueue**(): returns empty queue.

# Implementation Queue



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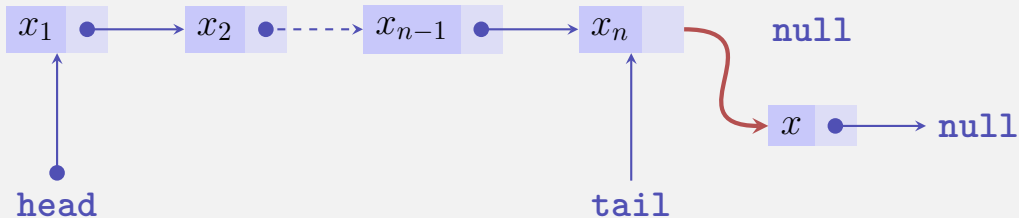
# Implementation Queue



`enqueue`( $x, S$ ):

- 1 Create a new list element with  $x$  and pointer to `null`.

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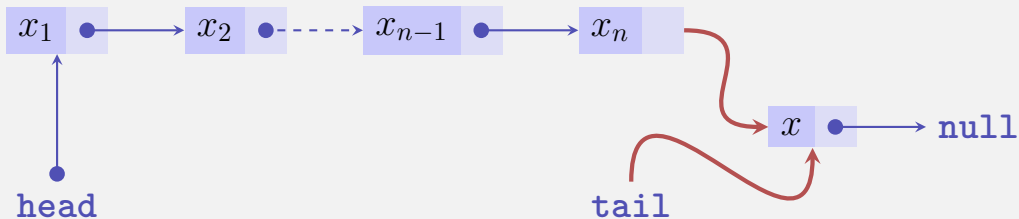


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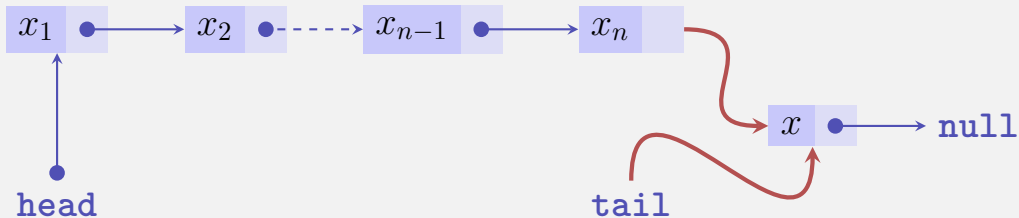
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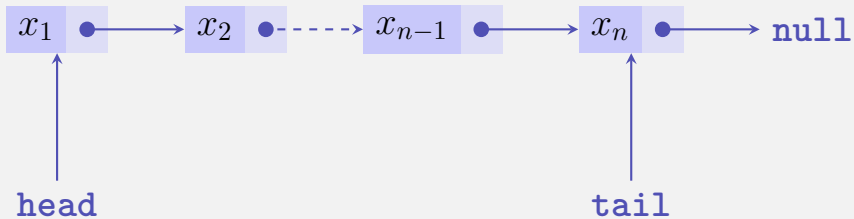
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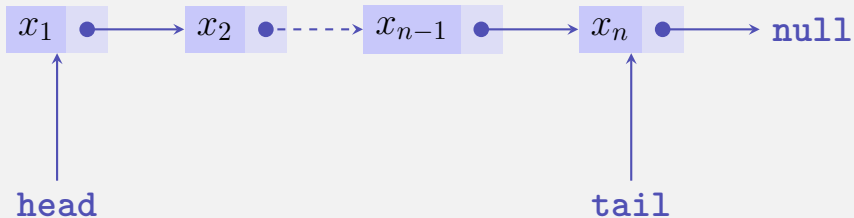
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- 4 If `head` = `null`, then set `head` to `tail`.

# Invariants



With this implementation it holds that

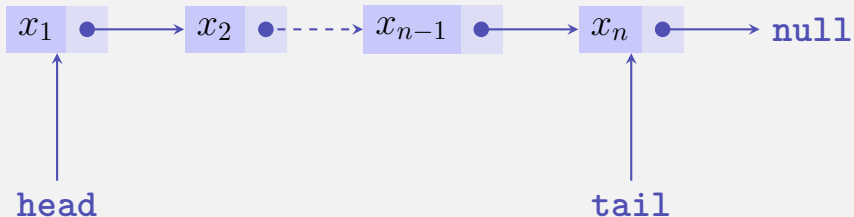
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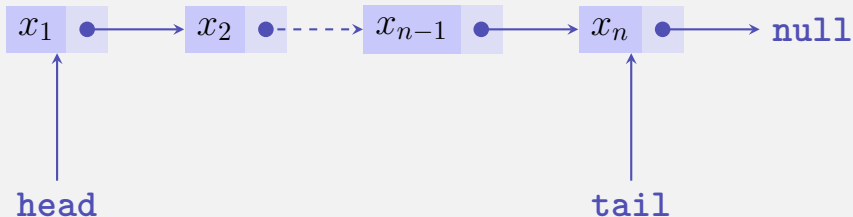
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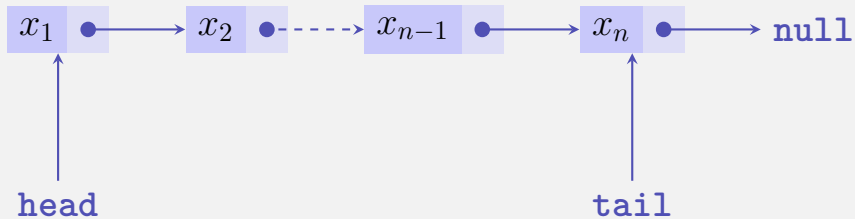
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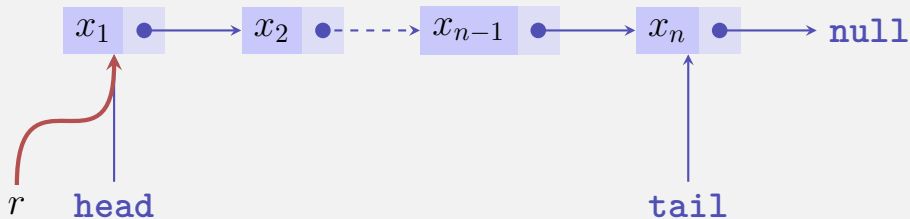
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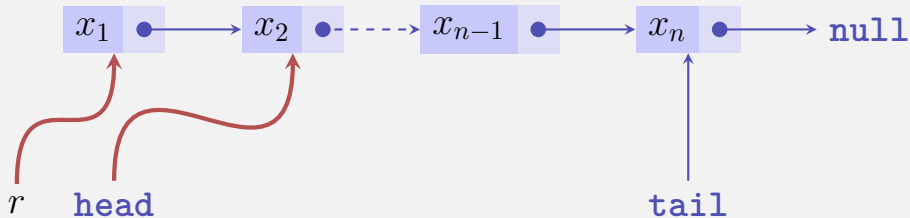


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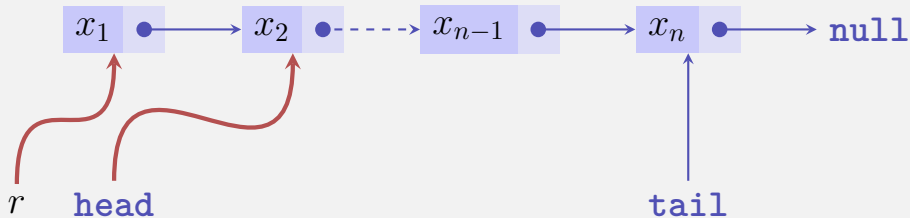
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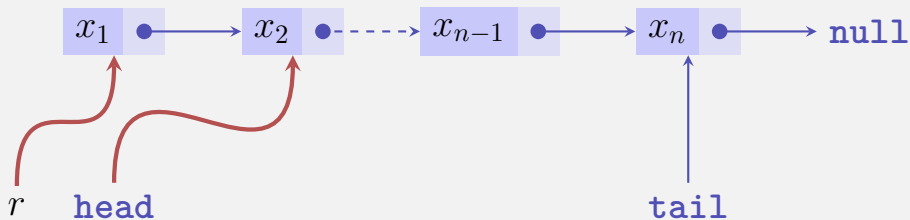
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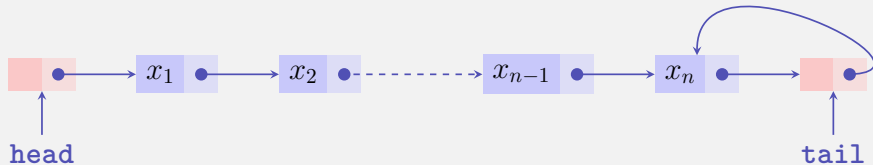
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- 4 Return the value of  $r$ .

# Analysis

Each of the operations `enqueue`, `dequeue`, `head` and `isEmpty` on the queue can be executed in  $\mathcal{O}(1)$  steps.

# Implementation Variants of Linked Lists

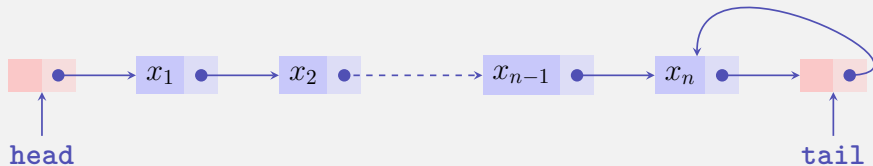
List with dummy elements (sentinels).



Advantage: less special cases

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Variant: like this with pointer of an element stored singly indirect.

(Example: pointer to  $x_3$  points to  $x_2$ .)

# Implementation Variants of Linked Lists

## Doubly linked list



# Overview

	enqueue	delete	search	concat
(A)	$\Theta(1)$	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
(B)	$\Theta(1)$	$\Theta(n)$	$\Theta(n)$	$\Theta(1)$
(C)	$\Theta(1)$	$\Theta(1)$	$\Theta(n)$	$\Theta(1)$
(D)	$\Theta(1)$	$\Theta(1)$	$\Theta(n)$	$\Theta(1)$

(A) = singly linked

(B) = Singly linked with dummy element at the beginning and the end

(C) = Singly linked with indirect element addressing

(D) = doubly linked



# priority queue

## Priority Queue

### Operations

- `insert(x,p,Q)`: Enter object  $x$  with priority  $p$ .
- `extractMax(Q)`: Remove and return object  $x$  with highest priority.

# Implementation Priority Queue

With a Max Heap

Thus

- `insert` in  $\mathcal{O}(?)$  and
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# Multistack

Multistack adds to the stack operations below

`multiPop(s, S)`: remove the  $\min(\text{size}(S), k)$  most recently inserted objects and return them.

Implementation as with the stack. Runtime of `multiPop` is  $\mathcal{O}(k)$ .

# Academic Question

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How to make a better estimation?



# Idea (accounting)

Introduction of a cost model:

- Each call of `push` costs 1 CHF and additional 1 CHF will be put to account.
- Each call to `pop` costs 1 CHF and will be paid from the account.

Account will never have a negative balance. Thus: maximal costs = number of `push` operations times two.

# More Formal

Let  $t_i$  denote the real costs of the operation  $i$ . Potential function  $\Phi_i \geq 0$  for the “account balance” after  $i$  operations.  $\Phi_i \geq \Phi_0 \forall i$ .

Amortized costs of the  $i$ th operation:

$$a_i := t_i + \Phi_i - \Phi_{i-1}.$$

It holds

$$\sum_{i=1}^n a_i = \sum_{i=1}^n (t_i + \Phi_i - \Phi_{i-1}) = \left( \sum_{i=1}^n t_i \right) + \Phi_n - \Phi_0 \geq \sum_{i=1}^n t_i.$$

**Goal:** find potential function that evens out expensive operations.

# Example stack

Potential function  $\Phi_i =$  number element on the stack.

- **push**( $x, S$ ): real costs  $t_i = 1$ .  $\Phi_i - \Phi_{i-1} = 1$ . Amortized costs  $a_i = 2$ .
- **pop**( $S$ ): real costs  $t_i = 1$ .  $\Phi_i - \Phi_{i-1} = -1$ . Amortized costs  $a_i = 0$ .
- **multipop**( $k, S$ ): real costs  $t_i = k$ .  $\Phi_i - \Phi_{i-1} = -k$ . amortized costs  $a_i = 0$ .

All operations have *constant amortized cost*! Therefore, on average Multipop requires a constant amount of time. <sup>14</sup>

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<sup>14</sup>Note that we are not talking about the probabilistic mean but the (worst-case) average of the costs.

# Example Binary Counter

Binary counter with  $k$  bits. In the worst case for each count operation maximally  $k$  bitflips. Thus  $\mathcal{O}(n \cdot k)$  bitflips for counting from 1 to  $n$ . Better estimation?

Real costs  $t_i$  = number bit flips from 0 to 1 plus number of bit-flips from 1 to 0.

$$\dots 0 \underbrace{1111111}_{l \text{ Einsen}} + 1 = \dots 1 \underbrace{0000000}_{l \text{ Zeroes}}.$$

$$\Rightarrow t_i = l + 1$$

# Example Binary Counter

$$\dots 0 \underbrace{1111111}_l \text{ Einsen} + 1 = \dots 1 \underbrace{0000000}_l \text{ Nullen}$$

potential function  $\Phi_i$ : number of 1-bits of  $x_i$ .

$$\Rightarrow \Phi_i - \Phi_{i-1} = 1 - l,$$

$$\Rightarrow a_i = t_i + \Phi_i - \Phi_{i-1} = l + 1 + (1 - l) = 2.$$

Amortized constant cost for each count operation. 😊

# 12. Dictionaries

Dictionary, Self-ordering List, Implementation of Dictionaries with Array / List /Skip lists. [Ottman/Widmayer, Kap. 3.3,1.7, Cormen et al, Kap. Problem 17-5]

# Dictionary

ADT to manage keys from a set  $\mathcal{K}$  with operations

- **insert**( $k, D$ ): Insert  $k \in \mathcal{K}$  to the dictionary  $D$ . Already exists  $\Rightarrow$  error message.
- **delete**( $k, D$ ): Delete  $k$  from the dictionary  $D$ . Not existing  $\Rightarrow$  error message.
- **search**( $k, D$ ): Returns **true** if  $k \in D$ , otherwise **false**

# Idea

Implement dictionary as sorted array

Worst case number of fundamental operations

Search

Insert

Delete



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Search  $\mathcal{O}(\log n)$  😊

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# Other idea

Implement dictionary as a linked list

Worst case number of fundamental operations

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Search  $\mathcal{O}(n)$  😞

Insert

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Implement dictionary as a linked list

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Search	$O(n)$	
Insert	$O(1)$ <sup>15</sup>	
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Implement dictionary as a linked list

Worst case number of fundamental operations

Search	$\mathcal{O}(n)$	
Insert	$\mathcal{O}(1)$ <sup>15</sup>	
Delete	$\mathcal{O}(n)$	

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# Self Ordered Lists

Problematic with the adoption of a linked list: linear search time

*Idea:* Try to order the list elements such that accesses over time are possible in a faster way

For example

- Transpose: For each access to a key, the key is moved one position closer to the front.
- Move-to-Front (MTF): For each access to a key, the key is moved to the front of the list.



# Transpose

Transpose:



Worst case: Alternating sequence of  $n$  accesses to  $k_{n-1}$  and  $k_n$ .

# Transpose

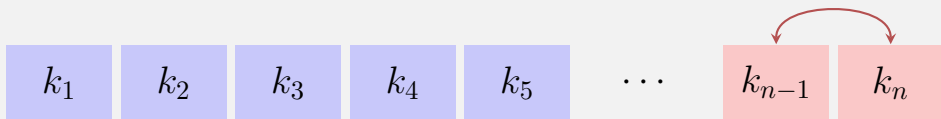
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Runtime:  $\Theta(n^2)$

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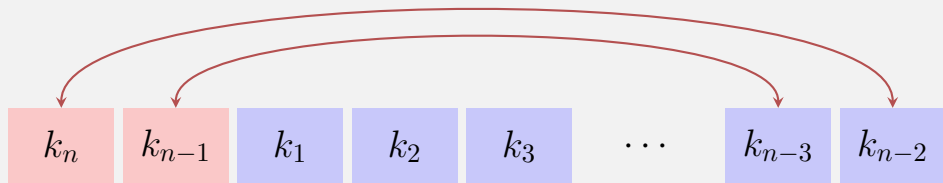
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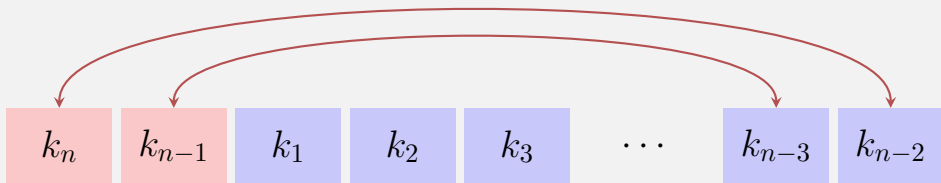
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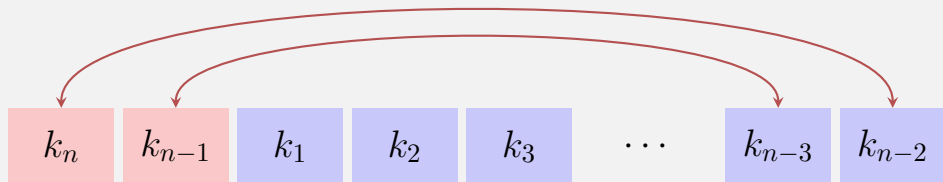


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Alternating sequence of  $n$  accesses to  $k_{n-1}$  and  $k_n$ . Runtime:  $\Theta(n)$

Also here we can provide a sequence of accesses with quadratic runtime, e.g. access to the last element. But there is no obvious strategy to counteract much better than MTF..

# Analysis

Compare MTF with the best-possible competitor (algorithm) A. How much better can A be?

Assumptions:

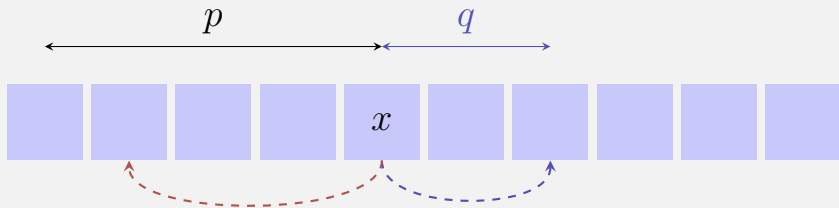
- MTF and A may only move the accessed element.
- MTF and A start with the same list.

Let  $M_k$  and  $A_k$  designate the lists after the  $k$ th step.  $M_0 = A_0$ .

# Analysis

Costs:

- Access to  $x$ : position  $p$  of  $x$  in the list.
- No further costs, if  $x$  is moved **before**  $p$
- Further costs  $q$  for each element that  $x$  is moved **back** starting from  $p$ .



# Amortized Analysis

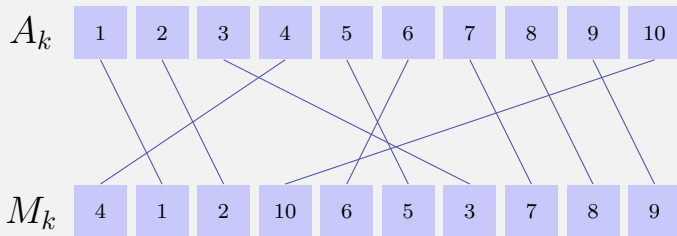
Let an arbitrary sequence of search requests be given and let  $G_k^{(M)}$  and  $G_k^{(A)}$  the costs in step  $k$  for Move-to-Front and A, respectively. Want estimation of  $\sum_k G_k^{(M)}$  compared with  $\sum_k G_k^{(A)}$ .

⇒ Amortized analysis with potential function  $\Phi$ .

# Potential Function

Potential function  $\Phi =$  Number of inversions of A vs. MTF.

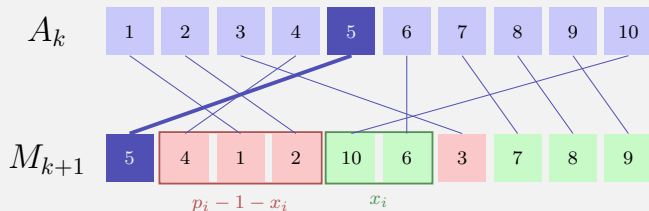
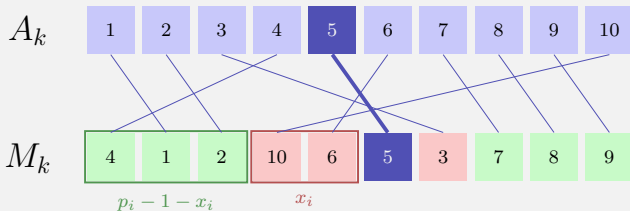
Inversion = Pair  $x, y$  such that for the positions of  $a$  and  $y$   
 $(p^{(A)}(x) < p^{(A)}(y)) \neq (p^{(M)}(x) < p^{(M)}(y))$



#inversion = #crossings

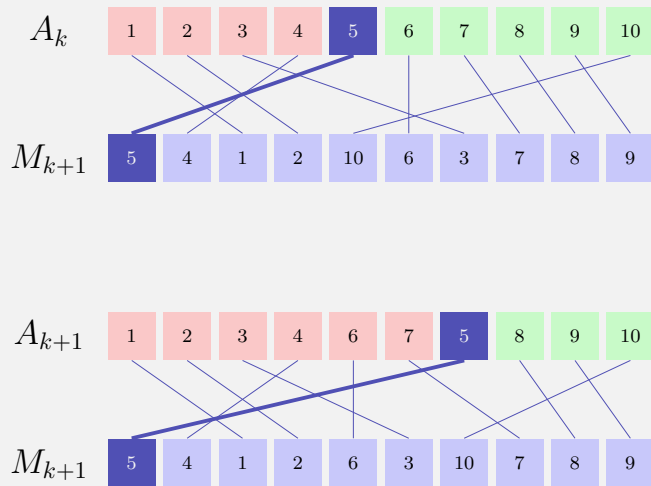
# Estimating the Potential Function: MTF

- Element  $i$  at position  $p_i := p^{(M)}(i)$ .
- access costs  $C_k^{(M)} = p_i$ .
- $x_i$ : Number elements that are in  $M$  before  $p_i$  and in  $A$  after  $i$ .
- MTF removes  $x_i$  inversions.
- $p_i - x_i - 1$ : Number elements that in  $M$  are before  $p_i$  and in  $A$  are before  $i$ .
- MTF generates  $p_i - 1 - x_i$  inversions.



# Estimating the Potential Function: A

- Wlog element  $i$  at position  $p^{(A)}(i)$ .
- $X_k^{(A)}$ : number movements to the back (otherwise 0).
- access costs for  $i$ :  
 $C_k^{(A)} = p^{(A)}(i) \geq p^{(M)}(i) - x_i$ .
- A increases the number of inversions maximally by  $X_k^{(A)}$ .



# Estimation

$$\Phi_{k+1} - \Phi_k \leq -x_i + (p_i - 1 - x_i) + X_k^{(A)}$$

Amortized costs of MTF in step  $k$ :

$$\begin{aligned} a_k^{(M)} &= C_k^{(M)} + \Phi_{k+1} - \Phi_k \\ &\leq p_i - x_i + (p_i - 1 - x_i) + X_k^{(A)} \\ &= (p_i - x_i) + (p_i - x_i) - 1 + X_k^{(A)} \\ &\leq C_k^{(A)} + C_k^{(A)} - 1 + X_k^{(A)} \leq 2 \cdot C_k^{(A)} + X_k^{(A)}. \end{aligned}$$



# Estimation

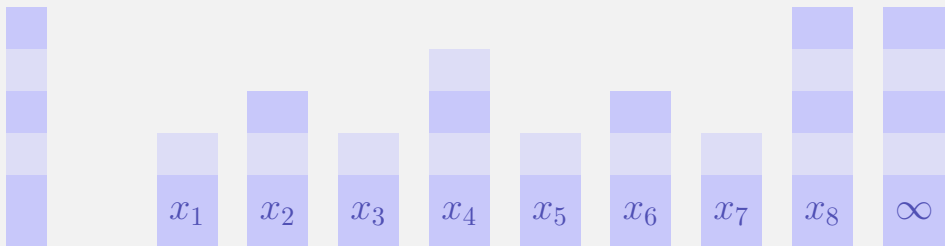
Summing up costs

$$\begin{aligned}\sum_k G_k^{(M)} &= \sum_k C_k^{(M)} \leq \sum_k a_k^{(M)} \leq \sum_k 2 \cdot C_k^{(A)} + X_k^{(A)} \\ &\leq 2 \cdot \sum_k C_k^{(A)} + X_k^{(A)} \\ &= 2 \cdot \sum_k G_k^{(A)}\end{aligned}$$

In the worst case MTF requires at most twice as many operations as the optimal strategy.

# Cool idea: skip lists

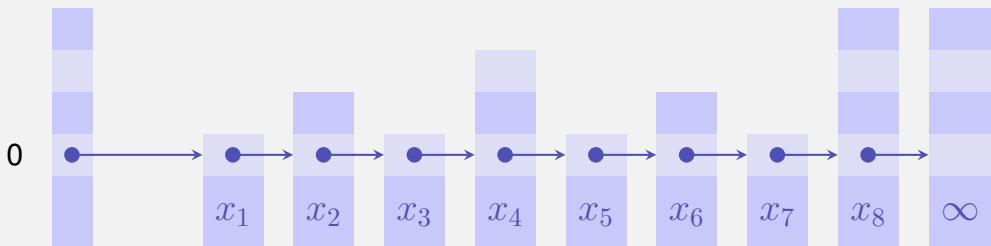
skip list



$$x_1 \leq x_2 \leq x_3 \leq \cdots \leq x_9.$$

# Cool idea: skip lists

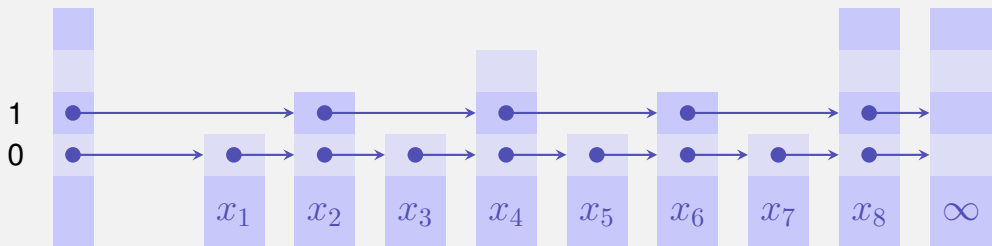
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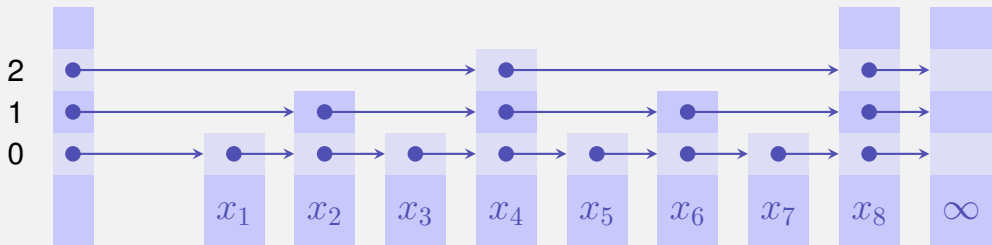
skip list



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# Cool idea: skip lists

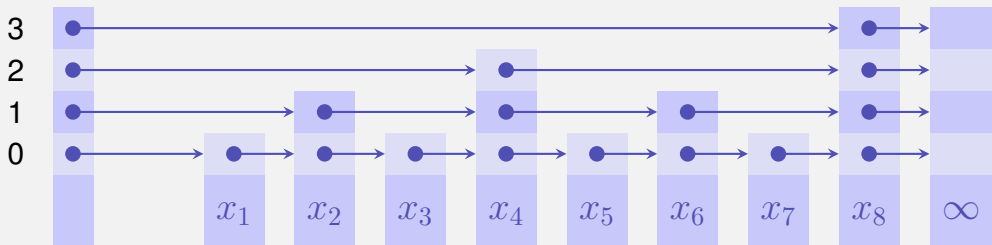
skip list



$$x_1 \leq x_2 \leq x_3 \leq \dots \leq x_9.$$

# Cool idea: skip lists

## Perfect skip list

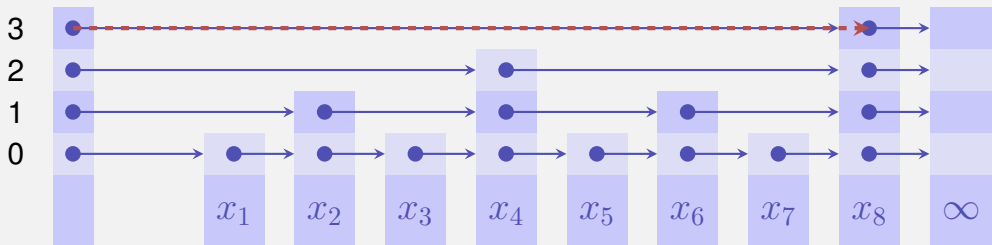


$x_1 \leq x_2 \leq x_3 \leq \dots \leq x_9$ .

Example: search for a key  $x$  with  $x_5 < x < x_6$ .

# Cool idea: skip lists

## Perfect skip list

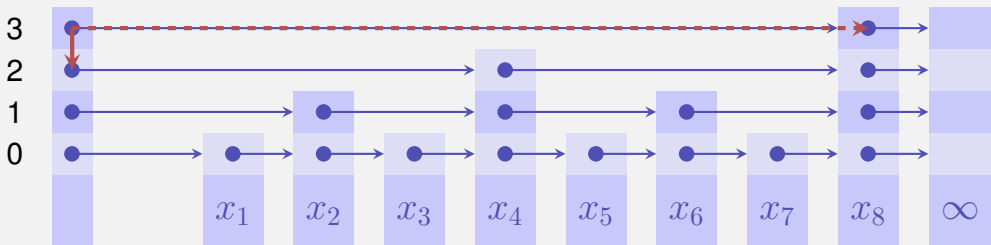


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# Cool idea: skip lists

## Perfect skip list



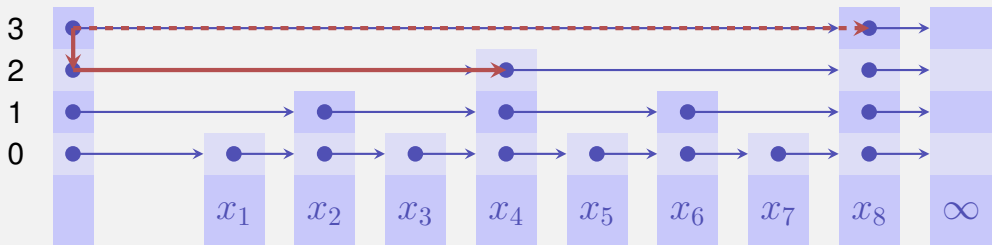
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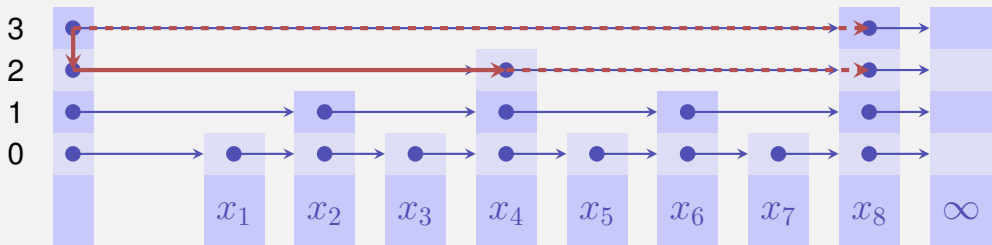


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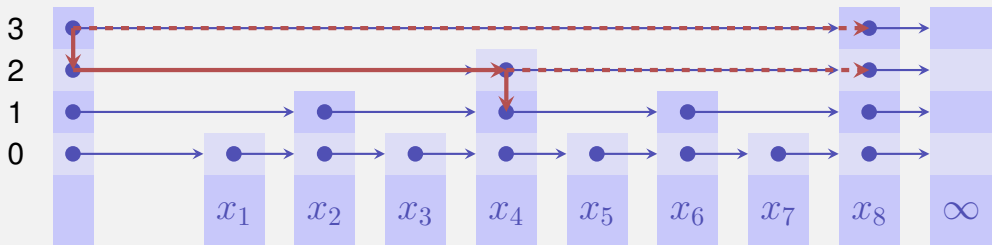


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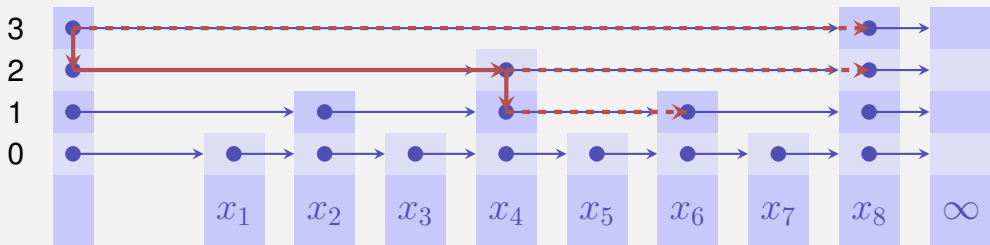


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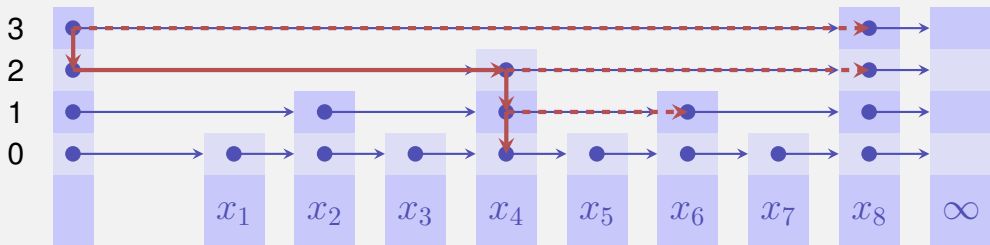


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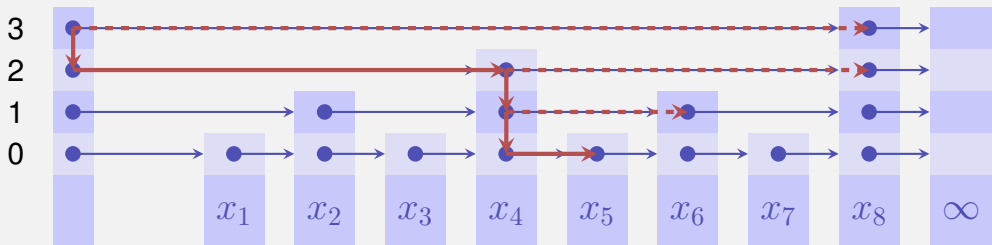


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## Perfect skip list

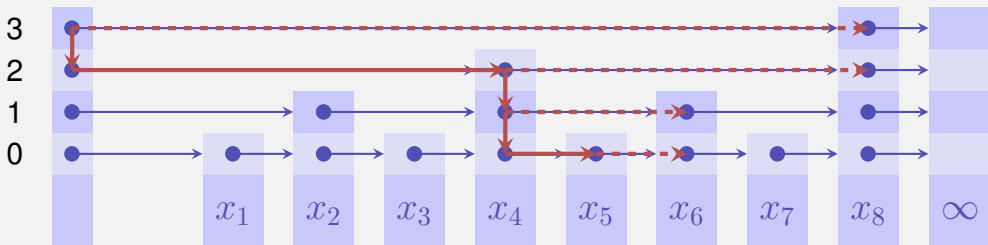


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Example: search for a key  $x$  with  $x_5 < x < x_6$ .

# Cool idea: skip lists

## Perfect skip list



$x_1 \leq x_2 \leq x_3 \leq \dots \leq x_9$ .

Example: search for a key  $x$  with  $x_5 < x < x_6$ .

# Analysis perfect skip list (worst cases)

Search in  $\mathcal{O}(\log n)$ . Insert in  $\mathcal{O}(n)$ .

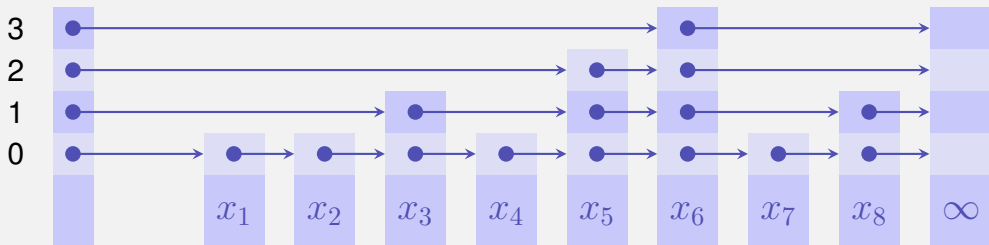


# Randomized Skip List

Idea: insert a key with random height  $H$  with  $\mathbb{P}(H = i) = \frac{1}{2^{i+1}}$ .

# Randomized Skip List

Idea: insert a key with random height  $H$  with  $\mathbb{P}(H = i) = \frac{1}{2^{i+1}}$ .



# Analysis Randomized Skip List

## Theorem

*The expected number of fundamental operations for Search, Insert and Delete of an element in a randomized skip list is  $\mathcal{O}(\log n)$ .*

The lengthy proof that will not be presented in this course observes the length of a path from a searched node back to the starting point in the highest level.