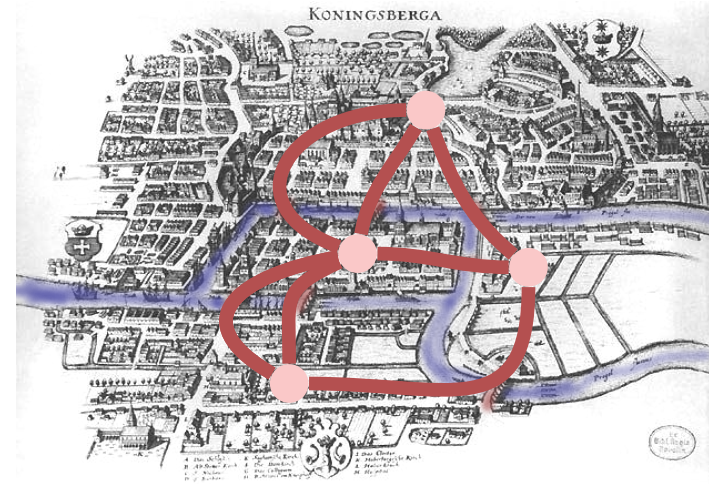


Königsberg 1736

22. Graphs

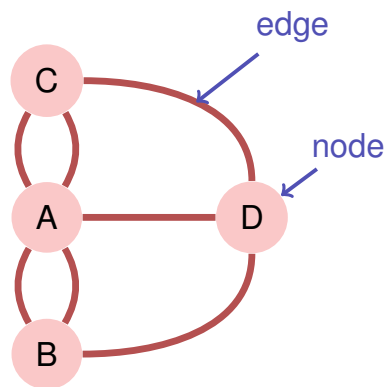
Reflexive transitive closure, Graph Traversal (DFS, BFS), Connected components, Topological Sorting Ottman/Widmayer, Kap. 9.1 - 9.4, Cormen et al, Kap. 22



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Graph

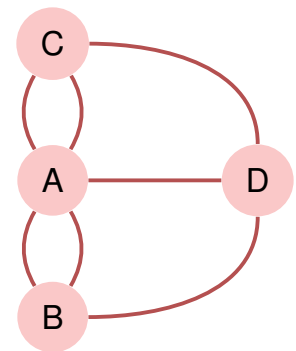


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Cycles

- Is there a cycle through the town (the graph) that uses each bridge (each edge) exactly once?
- Euler (1736): no.
- Such a cycle is called *Eulerian path*.
- Eulerian path \Leftrightarrow each node provides an even number of edges (each node is of an *even degree*).

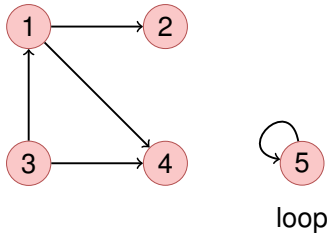
' \Rightarrow ' ist straightforward, ' \Leftarrow ' ist a bit more difficult



605

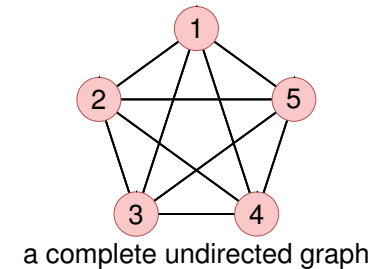
Notation

A **directed graph** consists of a set $V = \{v_1, \dots, v_n\}$ of nodes (*Vertices*) and a set $E \subseteq V \times V$ of Edges. The same edges may not be contained more than once.



Notation

An **undirected graph** consists of a set $V = \{v_1, \dots, v_n\}$ of nodes and a set $E \subseteq \{\{u, v\} | u, v \in V\}$ of edges. Edges may not be contained more than once.³¹



³¹As opposed to the introductory example – otherwise call it multi-graph.

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Notation

A graph $G = (V, E)$ with E comprising all edges is called **complete**.
 A graph where V can be partitioned into disjoint sets U and W such that each $e \in E$ provides a node in U and a node in W is called **bipartite**.
 A **weighted graph** $G = (V, E, c)$ is a graph $G = (V, E)$ with an **edge weight function** $c : E \rightarrow \mathbb{R}$. $c(e)$ is called **weight** of the edge e .

Notation

For directed graphs $G = (V, E)$

- $w \in V$ is called **adjacent** to $v \in V$, if $(v, w) \in E$
- **Predecessors** of $v \in V$: $N^-(v) := \{u \in V | (u, v) \in E\}$.
Successors: $N^+(v) := \{u \in V | (v, u) \in E\}$
- **In-Degree**: $\deg^-(v) = |N^-(v)|$,
Out-Degree: $\deg^+(v) = |N^+(v)|$



$$\deg^-(v) = 3, \deg^+(v) = 2 \quad \deg^-(w) = 1, \deg^+(w) = 1$$

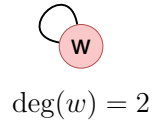
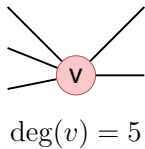
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Notation

For undirected graphs $G = (V, E)$:

- $w \in V$ is called **adjacent** to $v \in V$, if $\{v, w\} \in E$
- **Neighbourhood** of $v \in V$: $N(v) = \{w \in V | \{v, w\} \in E\}$
- **Degree** of v : $\deg(v) = |N(v)|$ with a special case for the loops: increase the degree by 2.



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Relationship between node degrees and number of edges

For each graph $G = (V, E)$ it holds

- 1 $\sum_{v \in V} \deg^-(v) = \sum_{v \in V} \deg^+(v) = |E|$, for G directed
- 2 $\sum_{v \in V} \deg(v) = 2|E|$, for G undirected.

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Paths

- **Path**: a sequence of nodes $\langle v_1, \dots, v_{k+1} \rangle$ such that for each $i \in \{1 \dots k\}$ there is an edge from v_i to v_{i+1} .
- **Length** of a path: number of contained edges k .
- **Weight** of a path (in weighted graphs): $\sum_{i=1}^k c(\{v_i, v_{i+1}\})$ (bzw. $\sum_{i=1}^k c(\{v_i, v_{i+1}\})$)
- **Simple path**: path without repeating vertices
- **Connected**: undirected graph where for each pair $v, w \in V$ there is a connecting path.

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Cycles

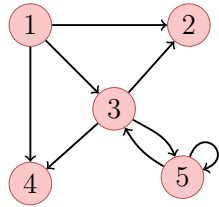
- **Cycle**: path $\langle v_1, \dots, v_{k+1} \rangle$ with $v_1 = v_{k+1}$
- **Simple cycle**: Cycle with pairwise different v_1, \dots, v_k , that does not use an edge more than once.
- **Acyclic**: graph without any cycles.

Conclusion: undirected graphs cannot contain cycles with length 2 (loops have length 1)

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Representation using a Matrix

Graph $G = (V, E)$ with nodes v_1, \dots, v_n stored as *adjacency matrix* $A_G = (a_{ij})_{1 \leq i, j \leq n}$ with entries from $\{0, 1\}$. $a_{ij} = 1$ if and only if edge from v_i to v_j .



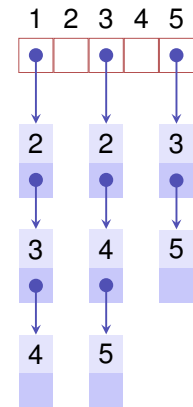
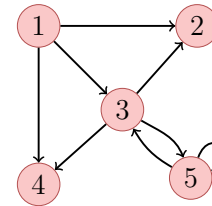
$$\begin{pmatrix} 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}$$

Memory consumption $\Theta(|V|^2)$. A_G is symmetric, if G undirected.

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Representation with a List

Many graphs $G = (V, E)$ with nodes v_1, \dots, v_n provide much less than n^2 edges. Representation with *adjacency list*: Array $A[1], \dots, A[n]$, A_i comprises a linked list of nodes in $N^+(v_i)$.



Memory Consumption $\Theta(|V| + |E|)$.

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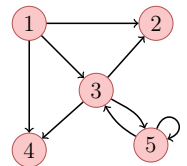
Runtimes of simple Operations

Operation	Matrix	List
Find neighbours of $v \in V$	$\Theta(n)$	$\Theta(\deg^+ v)$
find $v \in V$ without neighbour	$\mathcal{O}(n^2)$	$\mathcal{O}(n)$
$(u, v) \in E$?	$\mathcal{O}(1)$	$\mathcal{O}(\deg^+ v)$
Insert edge	$\mathcal{O}(1)$	$\mathcal{O}(1)$
Delete edge	$\mathcal{O}(1)$	$\mathcal{O}(\deg^+ v)$

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Adjacency Matrix Product

$$B := A_G^2 = \begin{pmatrix} 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}^2 = \begin{pmatrix} 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 2 \end{pmatrix}$$



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Interpretation

Theorem

Let $G = (V, E)$ be a graph and $k \in \mathbb{N}$. Then the element $a_{i,j}^{(k)}$ of the matrix $(a_{i,j}^{(k)})_{1 \leq i, j \leq n} = A_G^k$ provides the number of paths with length k from v_i to v_j .

Proof

By Induction.

Base case: straightforward for $k = 1$. $a_{i,j} = a_{i,j}^{(1)}$.

Hypothesis: claim is true for all $k \leq l$

Step ($l \rightarrow l + 1$):

$$a_{i,j}^{(l+1)} = \sum_{k=1}^n a_{i,k}^{(l)} \cdot a_{k,j}$$

$a_{k,j} = 1$ iff edge k to j , 0 otherwise. The sum above counts the number of nodes having a direct connection to v_j where a path of length l exists from v_i i.e. all paths with length $l + 1$.

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Shortest Path

Question: is there a path from i to j ? How long is the shortest path?

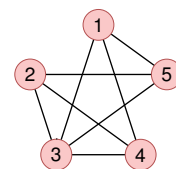
Answer: exponentiate A_G until for some $k < n$ it holds that $a_{i,j}^{(k)} > 0$.

k provides the path length of the shortest path. If $a_{i,j}^{(k)} = 0$ for all $1 \leq k < n$, then there is no path from i to j .

Number triangles

Question: How many triangular path does an undirected graph contain?

Answer: Remove all cycles (diagonal entries). Compute A_G^3 . $a_{ii}^{(3)}$ determines the number of paths of length 3 that contain i . There are 6 different permutations of a triangular path. Thus for the number of triangles: $\sum_{i=1}^n a_{ii}^{(3)} / 6$.



$$\begin{pmatrix} 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \end{pmatrix}^3 = \begin{pmatrix} 4 & 4 & 8 & 8 & 8 \\ 4 & 4 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 4 & 4 \\ 8 & 8 & 8 & 4 & 4 \end{pmatrix} \Rightarrow 24/6 = 4 \text{ Dreiecke.}$$

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Graphs and Relations

Graph $G = (V, E)$ with adjacencies $A_G \hat{=} \text{Relation } E \subseteq V \times V$ over V

- **reflexive** $\Leftrightarrow a_{i,i} = 1$ for all $i = 1, \dots, n$.
- **symmetric** $\Leftrightarrow a_{i,j} = a_{j,i}$ for all $i, j = 1, \dots, n$ (undirected)
- **transitive** $\Leftrightarrow (u, v) \in E, (v, w) \in E \Rightarrow (u, w) \in E$.

Equivalence relation \Leftrightarrow collection of complete, undirected graphs where each element has a loop.

Reflexive transitive closure of $G \Leftrightarrow$ **Reachability relation** E^* :
 $(v, w) \in E^*$ iff \exists path from node v to w .

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Computation of the Reflexive Transitive Closure

Goal: computation of $B = (b_{ij})_{1 \leq i, j \leq n}$ with $b_{ij} = 1 \Leftrightarrow (v_i, v_j) \in E^*$

Observation: $a_{ij} = 1$ already implies $(v_i, v_j) \in E^*$.

First idea:

- Start with $B \leftarrow A$ and set $b_{ii} = 1$ for each i (Reflexivity).
- Iterate over i, j, k and set $b_{ij} = 1$, if $b_{ik} = 1$ and $b_{kj} = 1$. Then all paths with length 1 and 2 taken into account.
- Repeated iteration \Rightarrow all paths with length $1 \dots 4$ taken into account.
- $\lceil \log_2 n \rceil$ iterations required.

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Improvement: Algorithm of Warshall (1962)

Inductive procedure: all paths known over nodes from $\{v_i : i < k\}$.
Add node v_k .

Algorithm ReflexiveTransitiveClosure(A_G)

Input : Adjacency matrix $A_G = (a_{ij})_{i,j=1}^n$

Output : Reflexive transitive closure $\hat{B} = (b_{ij})_{i,j=1}^n$ of G

```
B ← A_G
for k ← 1 to n do
  akk ← 1 // Reflexivity
  for i ← 1 to n do
    for j ← 1 to n do
      bij ← max{bij, bik · bkj} // All paths via vk
return B
```

Runtime $\Theta(n^3)$.

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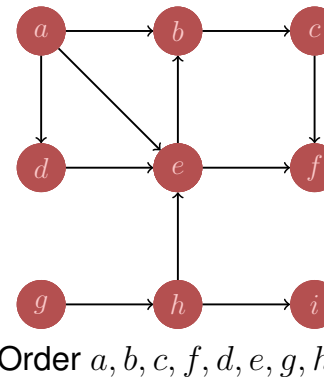
Correctness of the Algorithm (Induction)

Invariant (k): all paths via nodes with maximal index $< k$ considered.

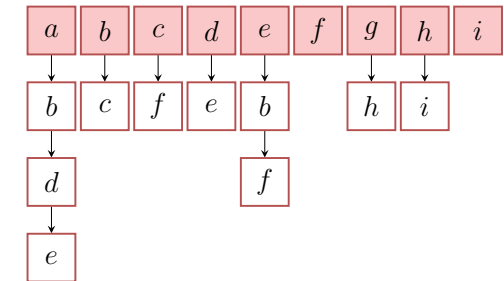
- Base case ($k = 1$): All directed paths (all edges) in A_G considered.
- Hypothesis: invariant (k) fulfilled.
- Step ($k \rightarrow k + 1$): For each path from v_i to v_j via nodes with maximal index k : by the hypothesis $b_{ik} = 1$ and $b_{kj} = 1$. Therefore in the k -th iteration: $b_{ij} \leftarrow 1$.

Graph Traversal: Depth First Search

Follow the path into its depth until nothing is left to visit.



Adjazenzliste



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Algorithm Depth First visit DFS-Visit(G, v)

Input : graph $G = (V, E)$, Knoten v .

Mark v visited

```
foreach  $(v, w) \in E$  do
  if  $\neg(w \text{ visited})$  then
    DFS-Visit( $w$ )
```

Depth First Search starting from node v . Running time (without recursion): $\Theta(\text{deg}^+ v)$

Algorithm Depth First visit DFS-Visit(G)

Input : graph $G = (V, E)$

```
foreach  $v \in V$  do
  if  $\neg(v \text{ visited})$  then
    DFS-Visit( $G, v$ )
```

Depth First Search for all nodes of a graph. Running time:

$$\Theta(|V| + \sum_{v \in V} (\text{deg}^+(v) + 1)) = \Theta(|V| + |E|).$$

Problem with recursion?

With large graphs a stack overflow can happen.

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Iterative DFS-Visit(G, v)

Input : graph $G = (V, E)$

Stack $S \leftarrow \emptyset$; push(S, v)

```

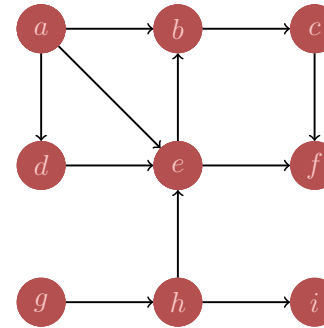
while  $S \neq \emptyset$  do
   $w \leftarrow \text{pop}(S)$ 
  if  $\neg(w \text{ visited})$  then
    mark  $w$  visited
    foreach  $(w, c) \in E$  do // (in reverse order, potentially)
      if  $\neg(c \text{ visited})$  then
        push( $S, c$ )
    
```

Stack size up to $|E|$, for each node an extra of $\Theta(\text{deg}^+(w) + 1)$ operations. Overall: $\mathcal{O}(|V| + |E|)$

Including all calls from the above main program: $\Theta(|V| + |E|)$

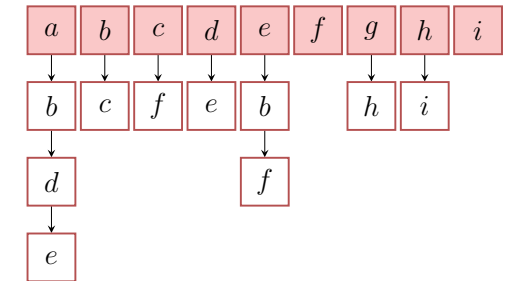
Graph Traversal: Breadth First Search

Follow the path in breadth and only then descend into depth.



Order $a, b, d, e, c, f, g, h, i$

Adjazenzliste



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Iterative BFS-Visit(G, v)

Input : graph $G = (V, E)$

Queue $Q \leftarrow \emptyset$

Mark v as active

enqueue(Q, v)

while $Q \neq \emptyset$ do

$w \leftarrow \text{dequeue}(Q)$

mark w visited

foreach $(w, c) \in E$ do

if $\neg(c \text{ visited} \vee c \text{ active})$ then

Mark c as active

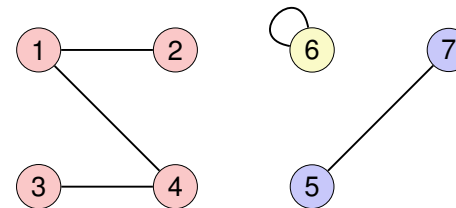
enqueue(Q, c)

- Algorithm requires extra space of $\mathcal{O}(|V|)$. (Why does that simple approach not work with DFS?)

- Running time including main program: $\Theta(|V| + |E|)$.

Connected Components

Connected components of an undirected graph G : equivalence classes of the reflexive, transitive closure of G . Connected component = subgraph $G' = (V', E')$, $E' = \{\{v, w\} \in E \mid v, w \in V'\}$ with $\{\{v, w\} \in E \mid v \in V' \vee w \in V'\} = E = \{\{v, w\} \in E \mid v \in V' \wedge w \in V'\}$



Graph with connected components $\{1, 2, 3, 4\}$, $\{5, 7\}$, $\{6\}$.

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Computation of the Connected Components

- Computation of a partitioning of V into pairwise disjoint subsets V_1, \dots, V_k
- such that each V_i contains the nodes of a connected component.
- Algorithm: depth-first search or breadth-first search. Upon each new start of $\text{DFSSearch}(G, v)$ or $\text{BFSSearch}(G, v)$ a new empty connected component is created and all nodes being traversed are added.

Topological Sorting

Topological Sorting of an acyclic directed graph $G = (V, E)$:
Bijjective mapping

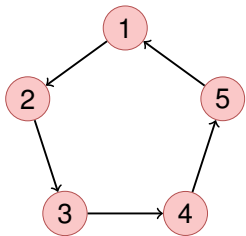
$$\text{ord} : V \rightarrow \{1, \dots, |V|\} \quad | \quad \text{ord}(v) < \text{ord}(w) \quad \forall (v, w) \in E.$$

Can identify i with v_i . Topological sorting $\hat{=} \langle v_1, \dots, v_{|V|} \rangle$.

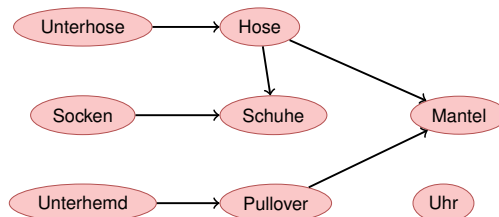
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(Counter-)Examples



Cyclic graph: cannot be sorted topologically.



A possible topological sorting of the graph:
Unterhemd, Pullover, Unterhose, Uhr, Hose, Mantel, Socken, Schuhe

Observation

Theorem

A directed graph $G = (V, E)$ permits a topological sorting if and only if it is acyclic.

Proof “ \Rightarrow ”: If G contains a cycle it cannot permit a topological sorting, because in a cycle $\langle v_{i_1}, \dots, v_{i_m} \rangle$ it would hold that

$$v_{i_1} < \dots < v_{i_m} < v_{i_1}.$$

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Inductive Proof Opposite Direction

- Base case ($n = 1$): Graph with a single node without loop can be sorted topologically, set $\text{ord}(v_1) = 1$.
- Hypothesis: Graph with n nodes can be sorted topologically
- Step ($n \rightarrow n + 1$):
 - 1 G contains a node v_q with in-degree $\text{deg}^-(v_q) = 0$. Otherwise iteratively follow edges backwards – after at most $n + 1$ iterations a node would be revisited. Contradiction to the cycle-freeness.
 - 2 Graph without node v_q and without its edges can be topologically sorted by the hypothesis. Now use this sorting and set $\text{ord}(v_i) \leftarrow \text{ord}(v_i) + 1$ for all $i \neq q$ and set $\text{ord}(v_q) \leftarrow 1$.

Preliminary Sketch of an Algorithm

Graph $G = (V, E)$. $d \leftarrow 1$

- 1 Traverse backwards starting from any node until a node v_q with in-degree 0 is found.
- 2 If no node with in-degree 0 found after n steps, then the graph has a cycle.
- 3 Set $\text{ord}(v_q) \leftarrow d$.
- 4 Remove v_q and his edges from G .
- 5 If $V \neq \emptyset$, then $d \leftarrow d + 1$, go to step 1.

Worst case runtime: $\Omega(|V|^2)$.

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Improvement

Idea?

Compute the in-degree of all nodes in advance and traverse the nodes with in-degree 0 while correcting the in-degrees of following nodes.

Algorithm Topological-Sort(G)

Input : graph $G = (V, E)$.

Output : Topological sorting ord

Stack $S \leftarrow \emptyset$

foreach $v \in V$ **do** $A[v] \leftarrow 0$

foreach $(v, w) \in E$ **do** $A[w] \leftarrow A[w] + 1$ // Compute in-degrees

foreach $v \in V$ with $A[v] = 0$ **do** $\text{push}(S, v)$ // Memorize nodes with in-degree 0

$i \leftarrow 1$

while $S \neq \emptyset$ **do**

$v \leftarrow \text{pop}(S)$; $\text{ord}[v] \leftarrow i$; $i \leftarrow i + 1$ // Choose node with in-degree 0

foreach $(v, w) \in E$ **do** // Decrease in-degree of successors

$A[w] \leftarrow A[w] - 1$

if $A[w] = 0$ **then** $\text{push}(S, w)$

if $i = |V| + 1$ **then return** ord **else return** "Cycle Detected"

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Algorithm Correctness

Theorem

Let $G = (V, E)$ be a directed acyclic graph. Algorithm $\text{TopologicalSort}(G)$ computes a topological sorting ord for G with runtime $\Theta(|V| + |E|)$.

Proof: follows from previous theorem:

- 1 Decreasing the in-degree corresponds with node removal.
- 2 In the algorithm it holds for each node v with $A[v] = 0$ that either the node has in-degree 0 or that previously all predecessors have been assigned a value $\text{ord}[u] \leftarrow i$ and thus $\text{ord}[v] > \text{ord}[u]$ for all predecessors u of v . Nodes are put to the stack only once.
- 3 Runtime: inspection of the algorithm (with some arguments like with graph traversal)

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Algorithm Correctness

Theorem

Let $G = (V, E)$ be a directed graph containing a cycle. Algorithm $\text{TopologicalSort}(G)$ terminates within $\Theta(|V| + |E|)$ steps and detects a cycle.

Proof: let $\langle v_{i_1}, \dots, v_{i_k} \rangle$ be a cycle in G . In each step of the algorithm remains $A[v_{i_j}] \geq 1$ for all $j = 1, \dots, k$. Thus k nodes are never pushed on the stack and therefore at the end it holds that $i \leq V + 1 - k$.

The runtime of the second part of the algorithm can become shorter. But the computation of the in-degree costs already $\Theta(|V| + |E|)$.

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