

TRM Implementation,

Communication Interface

Hybrid Compilation

## **4.3 BEHIND THE SCENES OF ACTIVE CELLS**

# Mapping to Hardware – Simple Example

```
IO*=CELL (input: PORT IN; output: PORT OUT;  
          buttons: PORT IN; leds: PORT OUT);  
BEGIN ...  
END IO;
```

```
Controller*=CELL (input: PORT IN; output: PORT OUT)  
BEGIN ...  
END Controller;
```

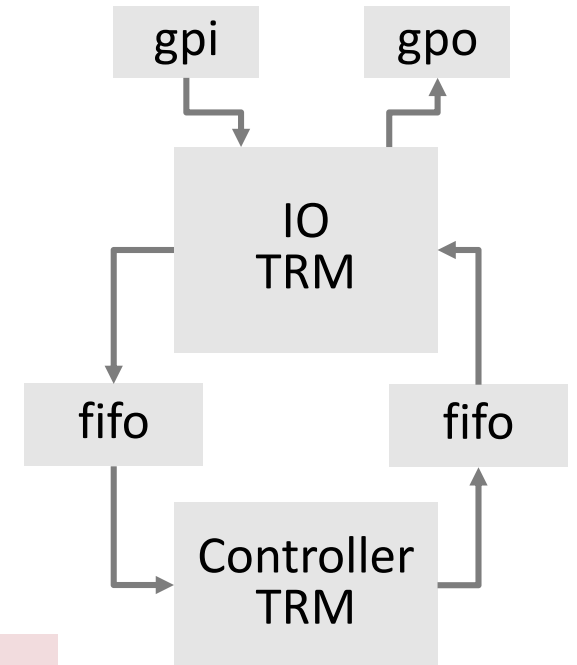
```
VAR controller: Controller; io: IO;  
    gpo{DataWidth=8}: Engines.Gpo;  
    gpi{DataWidth=11}: Engines.Gpi;
```

**BEGIN**

```
NEW(controller); NEW(io);  
NEW(gpi); NEW(gpo);
```

```
CONNECT (controller.output, io.input, 32);  
CONNECT (io.output, controller.input, 32);  
CONNECT (gpi.output, io.buttons);  
CONNECT (io.leds, gpo.input);
```

**END Simple.**



→ Blackboard / Code inspection

# Spartan3 Board



## Resources

4-input LUTs 3840

Flip Flops 3840

BRAMs 12

DSPs -

# Resource Usage Scenarios

## 1 TRM

```
CELLNET Game;  
  
IMPORT LED;  
  
TYPE  
IO*=CELL {DataMemorySize(512),  
CodeMemorySize(1024), LED} (in: PORT  
IN);  
BEGIN  
END IO;  
  
VAR io: IO;  
BEGIN  
  NEW(io);  
END Game.
```

## TRM → TRM

```
VAR io: IO; trm: TRM;  
BEGIN  
  NEW(io); NEW(trm);  
  CONNECT(trm.out, io.in);  
END Game.
```

## TRM ← → TRM → TRM

(cf. next page)

### Resources

4-input LUTs	27%
Flip Flops	5%
BRAMs	16%

### Resources

4-input LUTs	58%
Flip Flops	9%
BRAMs	33%

### Resources

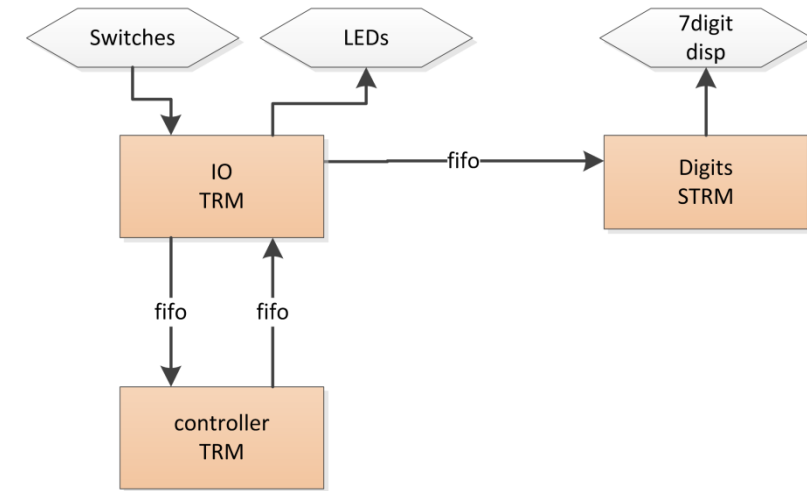
4-input LUTs	86%
Flip Flops	18%
BRAMs	75%

➔ TRM ≈ 21-27% (LUTs), 16% (BRAMs); Fifo ≈ 6% (LUTs)

# Resource Usage (Lab)

```
controller: Controller;
ioTRM: IO;
digitsDriver: DigitsDriver;
digits: Engines.LEDDigits;
gpo{DataWidth=8}: Engines.Gpo;
gpi{DataWidth=11}: Engines.Gpi;

BEGIN
NEW(controller);
NEW(ioTRM);
NEW(digitsDriver);
NEW(digits);NEW(gpi);NEW(gpo);
CONNECT( controller.cmdOUT,ioTRM.cmdIN,10);
CONNECT( ioTRM.cmdOUT,controller.cmdIN,10);
CONNECT( gpi.output, ioTRM.ButtonsIN);
CONNECT( ioTRM.LEDOUT, gpo.input);
CONNECT(ioTRM.digitsOUT, digitsDriver.cmdIN,10);
CONNECT(digitsDriver.ledOUT, digits.input);
```



## Resources

4-input LUTs	86%
Flip Flops	18%
BRAMs	75%

- 3 TRMs
- 3 FIFOs

# TRM Architectural State

- PC
- 8 registers
- flag registers
- Memory (configurable)
  - $nK * 36$  bits instruction memory (1k = 1024)
  - $nk * 32$  bits data memory

# PL vs. HDL

## Programming Language

- Sequential execution
- No notion of time

```
var a,b,c: integer;
```

```
a := 1;  
b := 2;  
c := a + b;
```

} unknown  
mapping  
to machine  
cycles

## Hardware Description Language

- Continuous execution (combinational logic)

```
wire [31:0] a,b,c;
```

```
assign a=1;  
assign b=2;  
assign c=a+b;
```

} no memory  
associated

- Synchronous execution (register transfer)

```
reg [31:0] a,b,c;
```

```
always @ (posedge clk)
```

```
begin
```

```
  a <= 1;
```

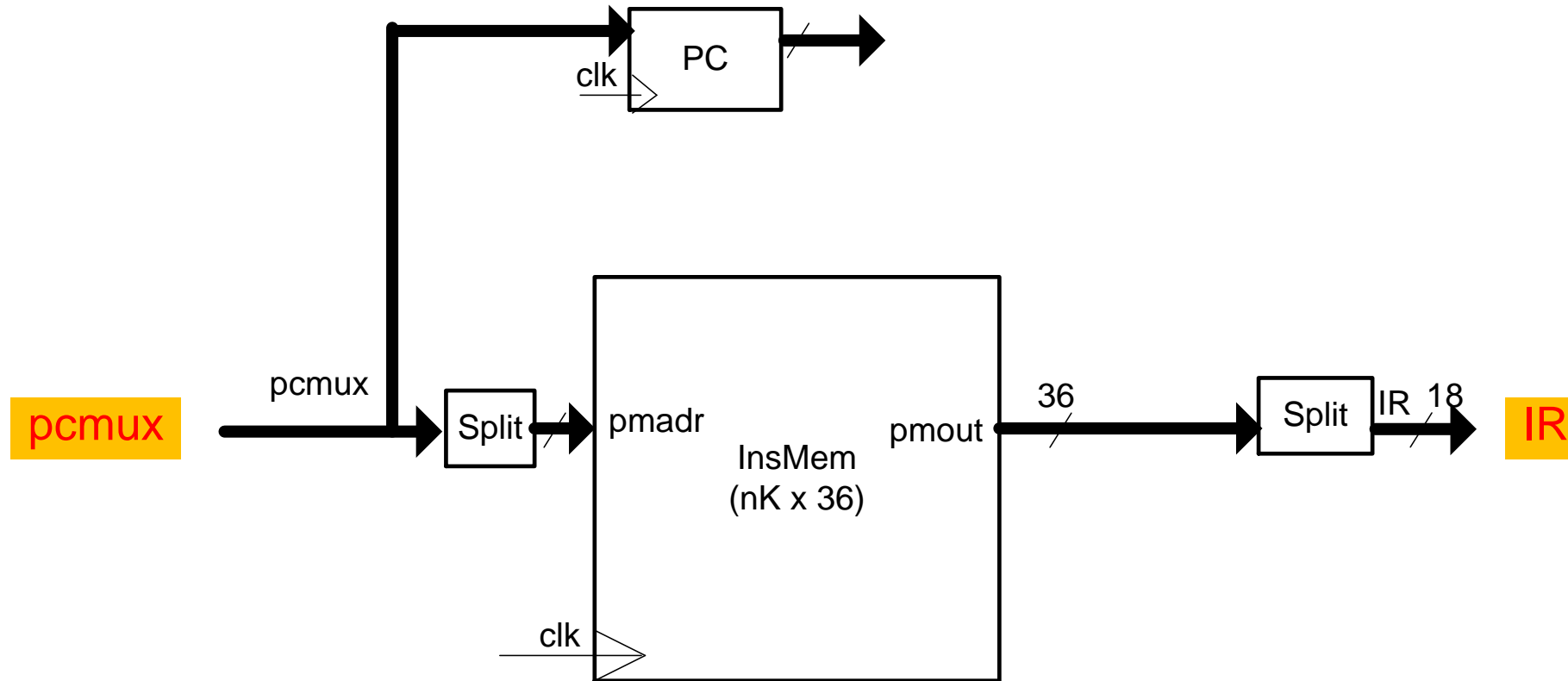
```
  b <= 2;
```

```
  c <= a+b;
```

```
end;
```

} synchronous  
at rising edge of  
the clock

# Single-Cycle Datapath: arithmetical logical instruction fetch





# Single-Cycle Datapath: instruction fetch

```
wire [PAW-1:0] pcmux, nxpc;
wire [17:0] IR;
reg [PAW-1:0] PC;

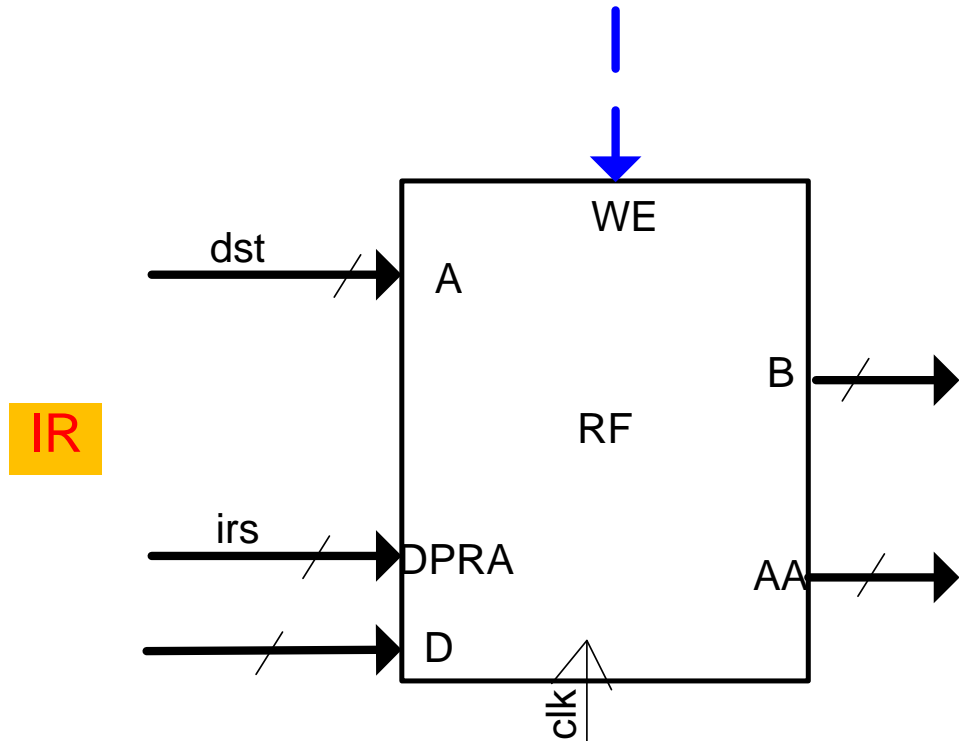
IM #(.BN(IMB)) imx(.clk(clk), .pmadr({{{32-PAW}}{1'b0}}, pcmux[PAW-1:1])),
    .pmout(pmout));

assign IR = (~rst)? NOP: (PC[0]) ? pmout[35:18] : pmout[17:0];

always @ (posedge clk) begin
    if (~rst) PC <= 0;
    else if (stall0)
        PC <= PC;
    else
        PC <= pcmux;
end
```

# Single-Cycle Datapath: register read

- STEP 2: Read source operands from register file



```

wire [2:0] rd, rs;
wire regWr;
wire [31:0] rdOut, rsOut;

```

```
//register file
```

```
...
```

```

assign irs = IR[2:0];
assign ird = IR[13:11];
assign dst = (BL)? 7: ird;

```

source register

destination register

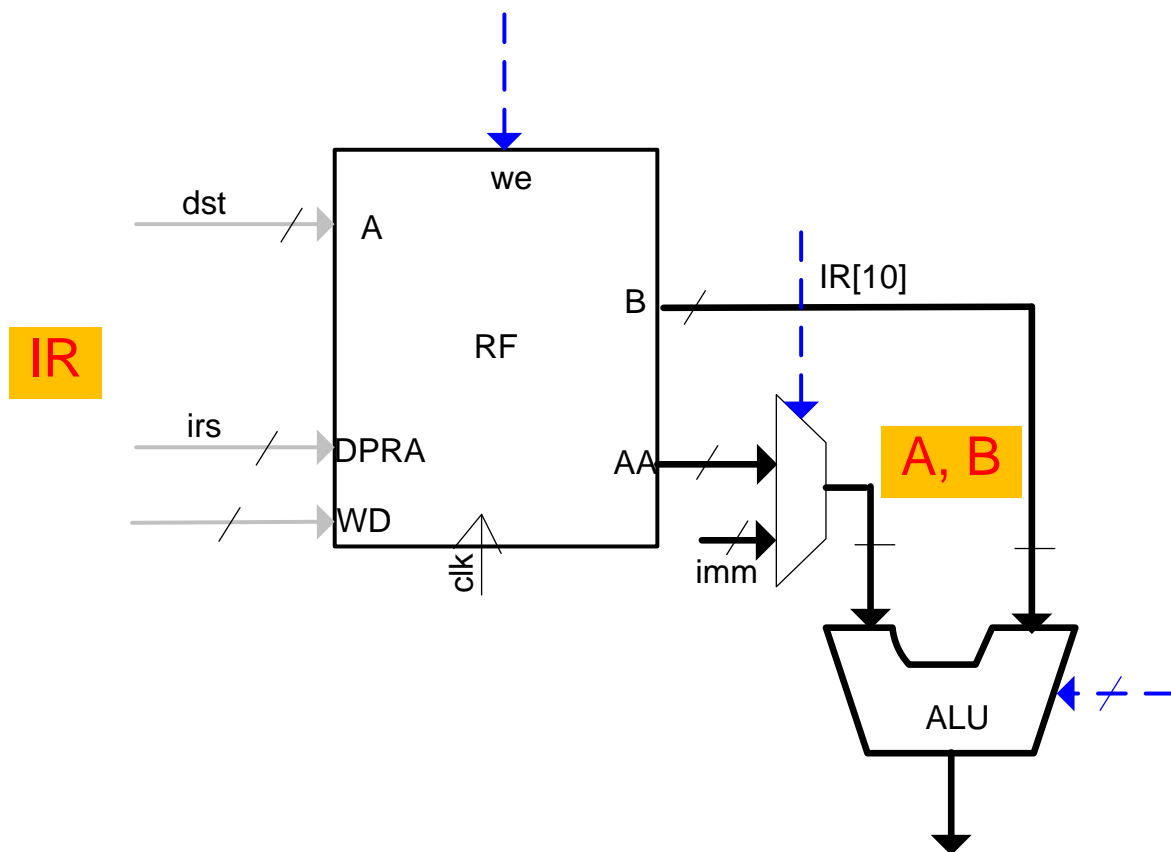
# Single-Cycle Datapath: ALU

- STEP 3: Compute the result via ALU

```
wire [31:0] AA, A, B, imm;
wire [32:0] aluRes;
```

```
assign A = (IR[10])? AA:
           {22'b0, imm};
```

```
assign minusA = {1'b0, ~A} + 33'd1;
assign aluRes =
  (MOV)? A:
  (ADD)? {1'b0, B} + {1'b0, A} :
  (SUB)? {1'b0, B} + minusA :
  (AND)? B & A :
  (BIC)? B & ~A :
  (OR)? B | A :
  (XOR)? B ^ A :
  ~A;
```



# Control Path

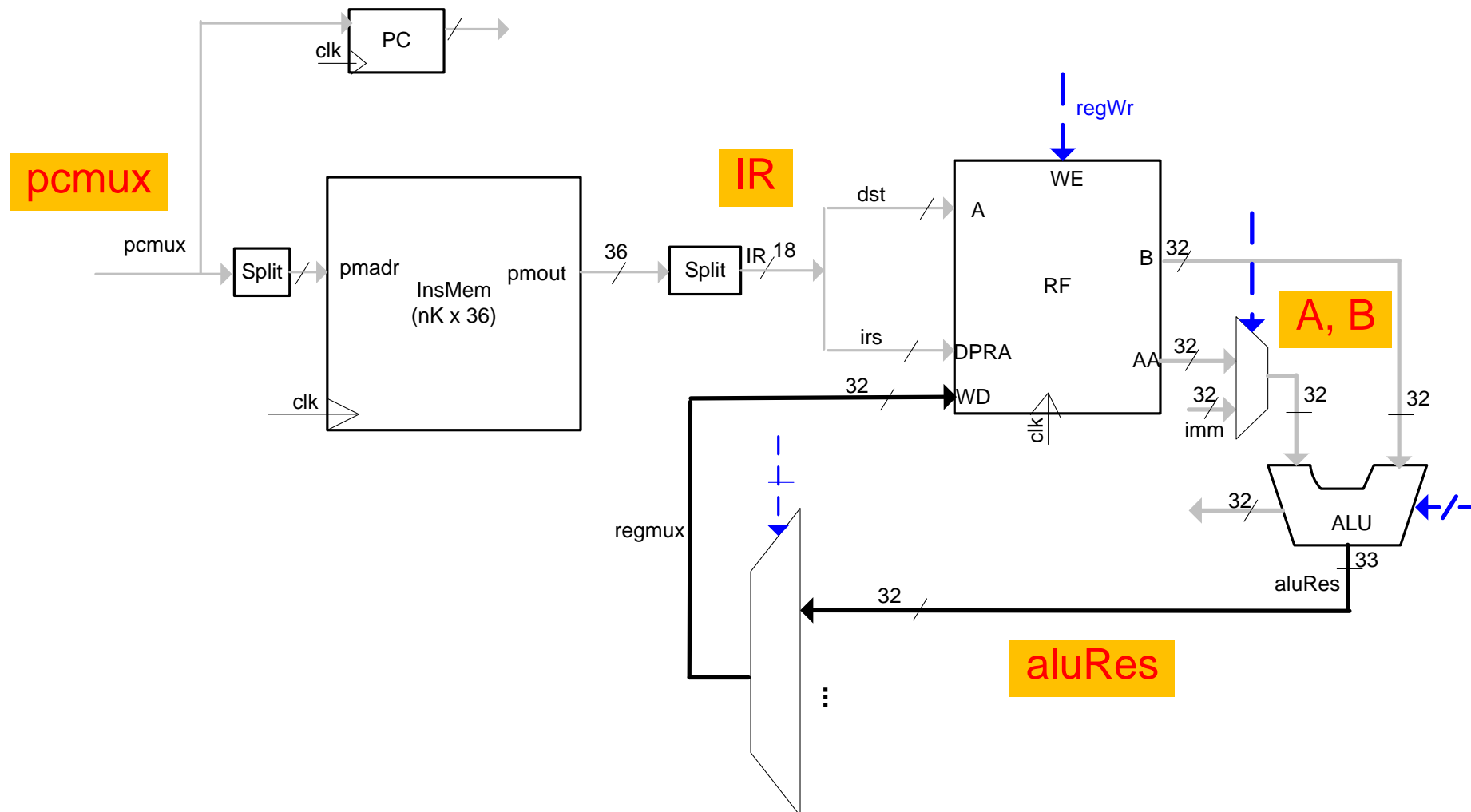
```
assign vector = IR[10] & IR[9] & ~IR[8] & ~IR[7];  
assign op = IR[17:14];
```

```
assign MOV = (op == 0);  
assign NOT = (op == 1);  
assign ADD = (op == 2);  
assign SUB = (op == 3);  
assign AND = (op == 4);  
assign BIC = (op == 5);  
assign OR = (op == 6);  
assign XOR = (op == 7);  
assign MUL = (op == 8) & (~IR[10] | ~IR[9]);  
assign ROR = (op == 10);  
assign BR = (op == 11) & IR[10] & ~IR[9];  
assign LDR = (op == 12);  
assign ST = (op == 13);  
assign Bc = (op == 14);  
assign BL = (op == 15);  
assign LDH = MOV & IR[10] & IR[3];  
assign BLR = (op == 11) & IR[10] & IR[9];
```

IR <sub>17:14</sub>	Function
0000	B := A
0001	B := ~A
0010	B := B + A
0011	B := B - A
0100	B := B & A
0101	B := B & ~A
0110	B := B   A
0111	B := B ^ A

# Single-Cycle Datapath: write back to Rd

- STEP 4: Write result back to Rd



# Single-Cycle Datapath: write back to Rd

```
wire [31:0] regmux;
```

```
wire regwr;
```

```
...
```

```
assign regwr = (BL | BLR | LDR & ~IR[10] |
                ~(IR[17] & IR[16]) & ~BR & ~vector)) & ~stall0;
```

```
assign regmux =
```

```
(BL | BLR) ? {{{32-PAW}}{1'b0}}, nxcpc} :
```

```
(LDR & ~loenbReg) ? dmout :
```

```
(LDR & loenbReg)? InbusReg: //from IO
```

```
(MUL) ? mulRes[31:0] :
```

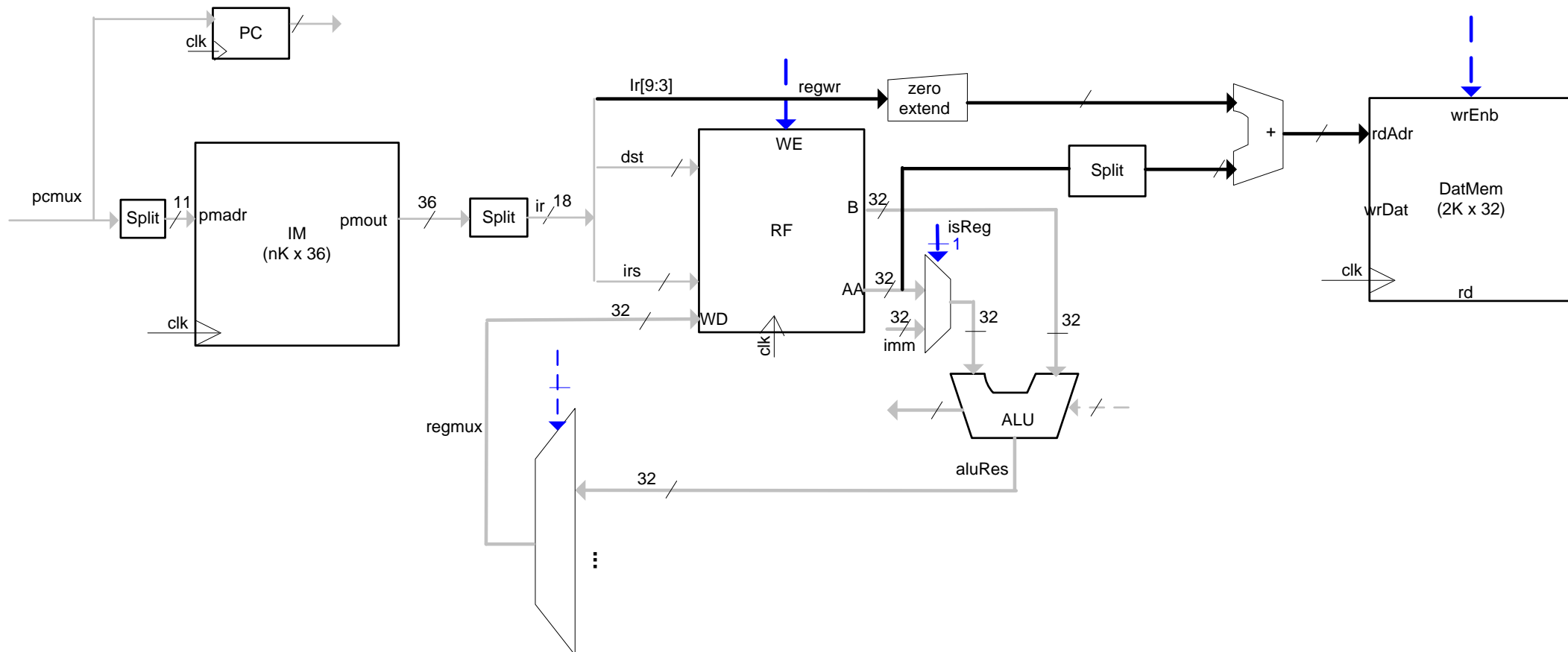
```
(ROR) ? s3 :
```

```
(LDH) ? H :
```

```
aluRes;
```

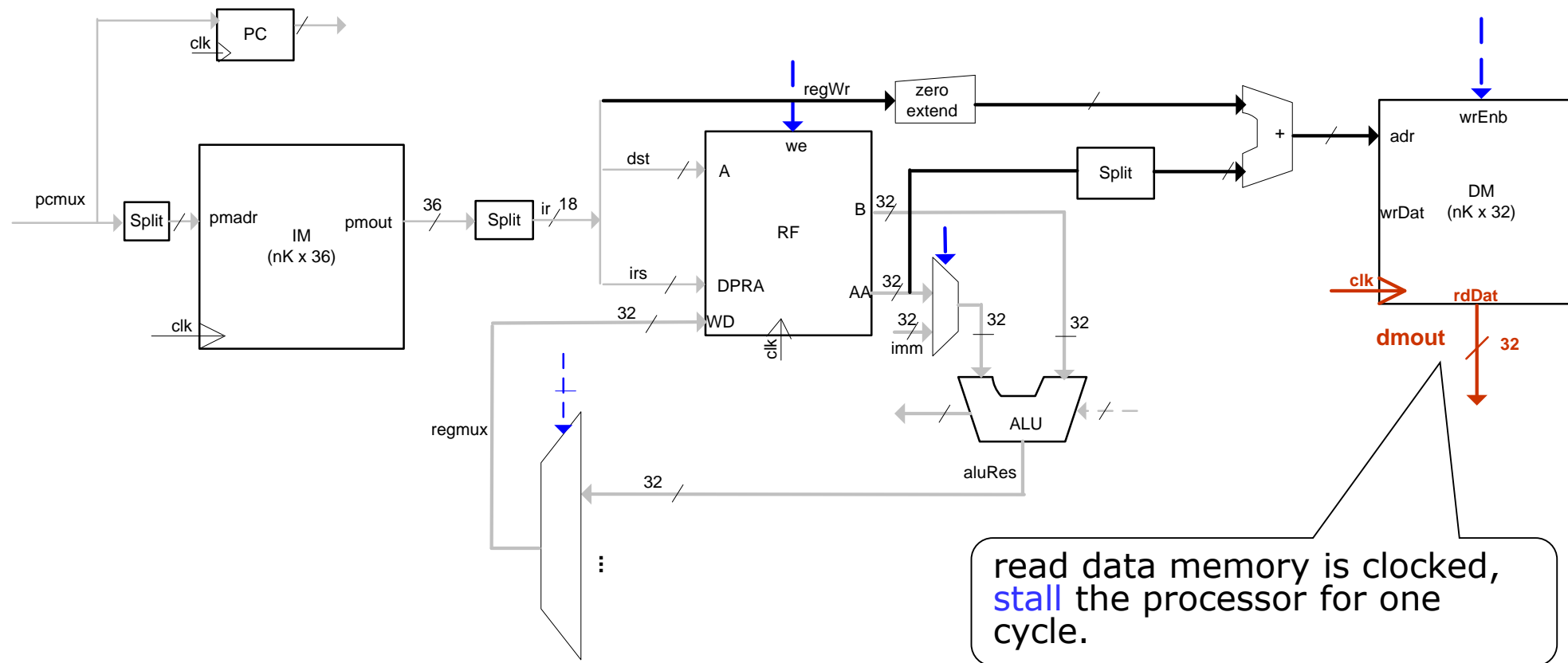
# Single-Cycle Datapath: LD

- **STEP 1:** Fetch instruction
- **STEP 2:** Read source operand from the register file
- **STEP 3:** Compute the memory address



# Single-Cycle Datapath: LD

- **STEP 3:** Compute the memory address
- **STEP 4:** Read data from data memory



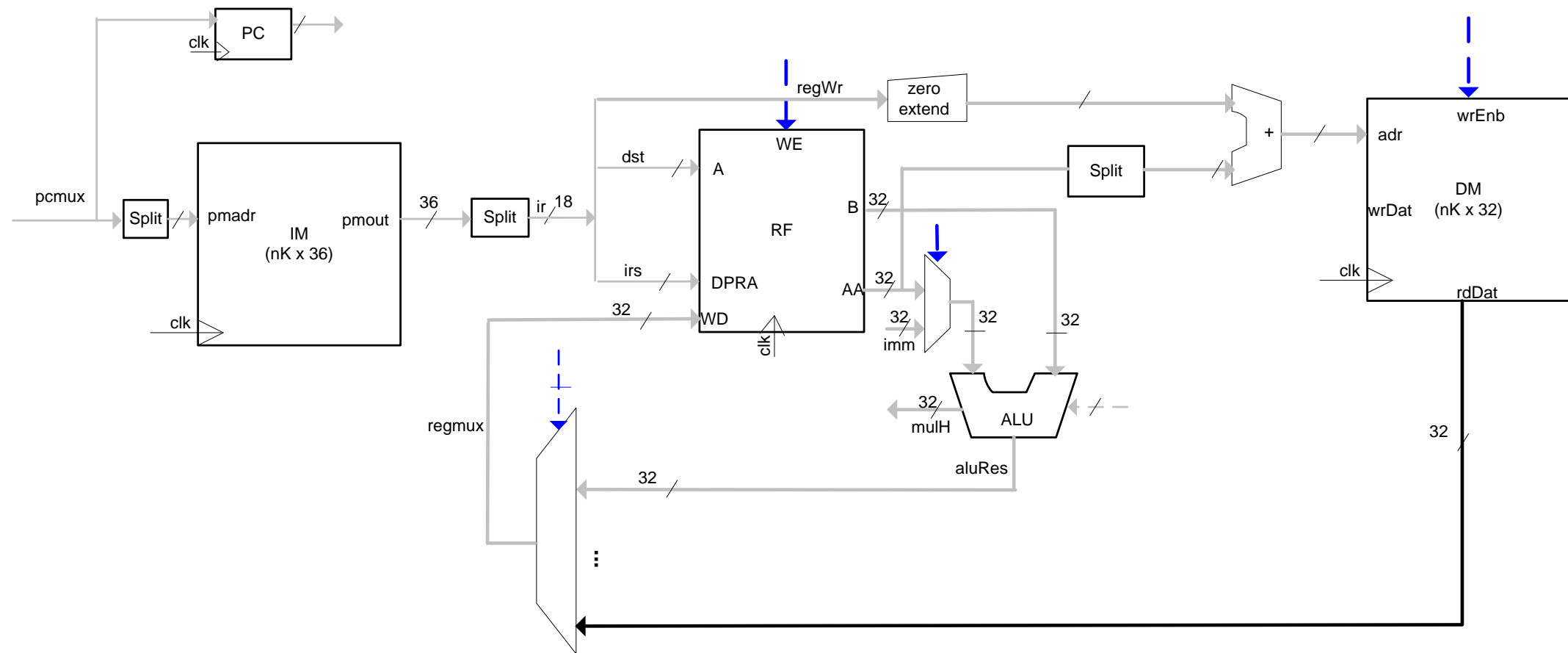


# TRM Stalling

- stop fetching next instruction, pcmux keeps the current value
- disable register file write enable and memory write enable signals to avoid changing the state of the processor.
  - only LD and MUL instructions stall the processor.
  - **dmwe** signal is not affected.
  - **regwr** signal is affected.

# Single-Cycle Datapath: LD

- STEP 4: Read data from data memory
- STEP 5: Write data back into the register file



# TRM: LD

## Verilog code in TRM module

```
wire [31:0] dmout;
wire [DAW:0] dmadr;
wire [6:0] offset;
reg IoenbReg;

//register file
...
Assign dmadr = (irs == 7) ? {{{DAW-6}{1'b0}}, offset} : (AA[DAW:0] + {{{DAW-6}{1'b0}}, offset));
assign ioenb = &(dmadr[DAW:6]);
assign rfWd = ...
    (LDR & ~IoenbReg)? dmout:
    (LDR & IoenbReg)? InbusReg: //from IO
    ...;
always @(posedge clk)
    IoenbReg <= ioenb;
```

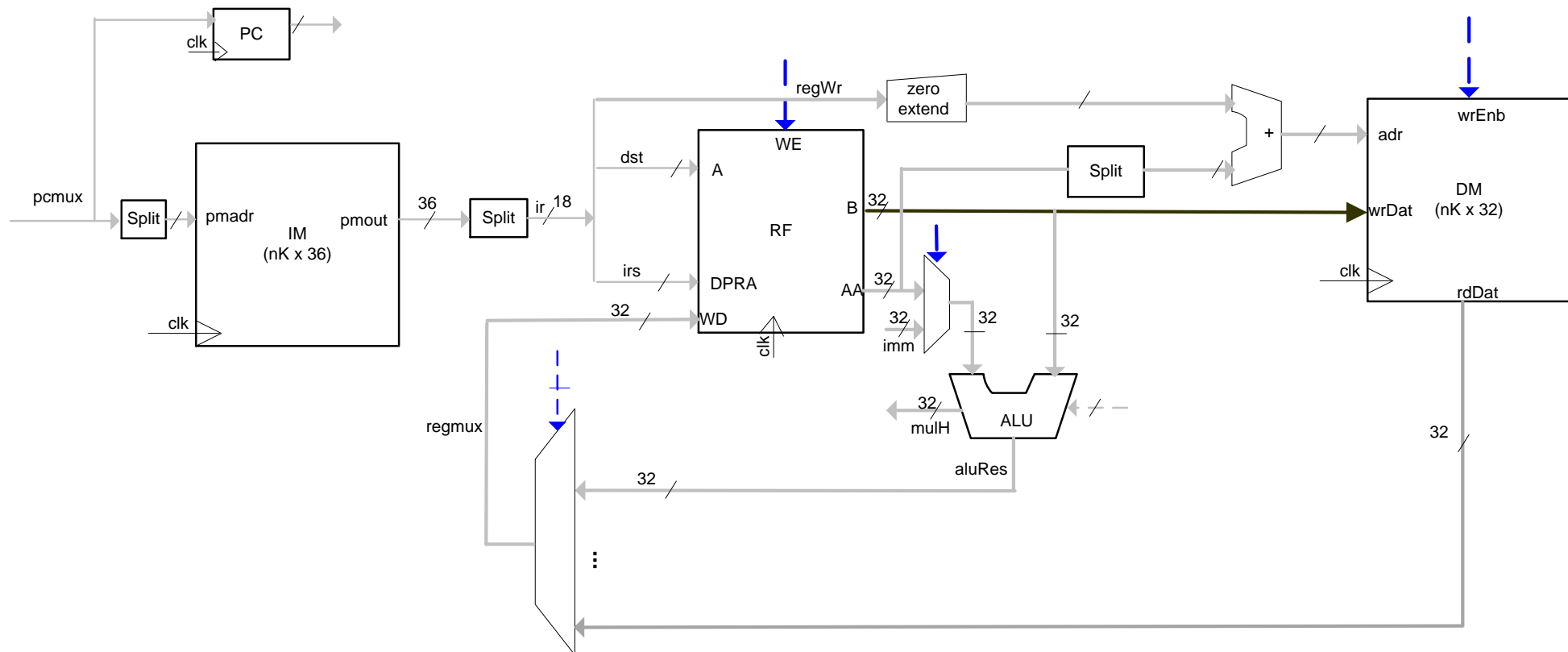
LD rd, [rs+offset]

Src register = lr ignored  
(Harvard architecture!)

I/O space: Uppermost  
 $2^6$  bytes in data  
memory

# Single-Cycle Datapath: ST

- **STEP 1:** Fetch instruction
- **STEP 2:** Read source operand from the register file
- **STEP 3:** Compute the memory address
- **STEP 4:** Write data into the data memory



# Single-Cycle Datapath: ST

- **STEP 3:** Compute the memory address
- **STEP 4:** Write data into the data memory

```
wire [31:0] dmin;
wire dmwr;

//register file
...
DM #(.BN(DMB)) dmx (.clk(clk),
    .wrDat(dmin),
    .wrAdr({{{31-DAW}}{1'b0}},dmadr}),
    .rdAdr({{{31-DAW}}{1'b0}},dmadr}),
    .wrEnb(dmwe),
    .rdDat(dmout));

Assign dmwe = ST & ~IR[10] & ~ioenb;
assign dmin = B;
```

# Single-Cycle Datapath: set flag registers

```
always @ (posedge clk, negedge rst) begin // flags
    handling
    if (~rst) begin N <= 0; Z <= 0; C <= 0; V <= 0; end
    else begin
        if (regwr) begin
            N <= aluRes[31];
            Z <= (aluRes[31:0] == 0);
            C <= (ROR & s3[0]) | (~ROR & aluRes[32]);
            V <= ADD & ((~A[31] & ~B[31] & aluRes[31])
                | (A[31] & B[31] & ~aluRes[31]))
                | SUB & ((~B[31] & A[31] & aluRes[31])
                | (B[31] & ~A[31] & ~aluRes[31]));
        end
    end
end
```

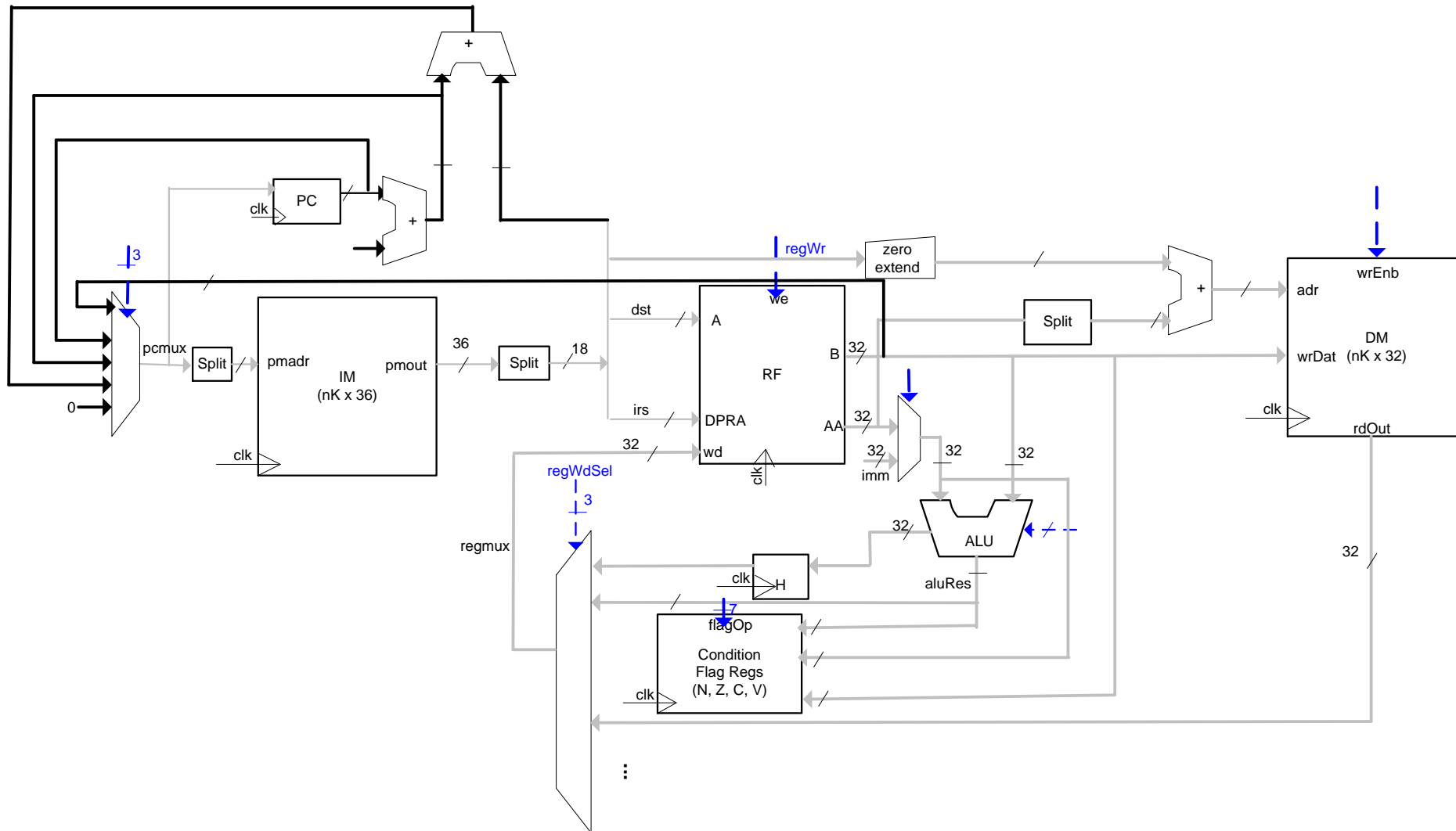


# Single-Cycle Datapath: Branch instructions

- Type c instructions, BR instruction, BL instruction
  - $PC \leq PC + 1 + \text{off}$
  - $PC \leq Rs$
  - **$PC \leq PC + 1$  (by default)**
  - **$PC \leq PC$  (if stall)**
  - **$PC \leq 0$  (reset)**



# Single-Cycle Datapath: Branch instructions



# Single-Cycle Datapath: Branch instructions

```
//pcmux logic
assign pcmux =
    (~rst) ? 0 :
    (stall0) ? PC :
    (BL)? {{10{IR[BLS-1]}}}, IR[BLS-1: 0]} + nxpc :
    (Bc & cond) ? {{{PAW-10}{IR[9]}}}, IR[9:0]} + nxpc :
    (BLR | BR ) ? A[PAW-1:0] :
    nxpc;
```

# Complete single-cycle datapath

